



# CLUSTER

CL-EST-RS-0451/EID B Issue: 1  
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## 3. ELECTRICAL INTERFACE DESIGN



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### 3.1 POWER SUPPLY INTERFACE

#### 3.1.1 General interface description

The general request of the Wave Experiment is:

- One redundant power line connected to the WEC/PWR device which is the single point interface with the spacecraft for the power needed in operational phase.
- One redundant power line distributed to the 4 deployment unit of the electric booms.
- No keep alive line is requested.

FUNCTION	Number of Main Lines Required	Number of Redundant Lines Required	LCL class
+28 V MAIN BUS (Switched and Current limited)	1	1	C 25 W /0.93 A
	1	1	E 63 W /2.30 A
EXPERIMENT KEEP ALIVE LINE	0		

Table 3.1/1 Power Supply Interface Requirements

#### 3.1.2 Power distribution block diagram

##### a/ Power distribution

The power distribution concept of the WEC is shown in Fig. 3.1/1.1 for the main experiment and Fig. 3.1/1.2 for the details of the deployment units.

For the WEC Power Supply, a general principle of redundancy has been adopted: no single point failure shall cause failure of more than one of the wave consortium instruments.

- Two fully redundant +5 volts supplies operating from separate spacecraft +28 volts lines are provided for the DWP.
- Separate power supplies that can operate from both spacecraft +28 volts lines are provided for the instruments: STAFF/mwf, STAFF/spa, WHISPER.
- One +28 volts line, being the addition of both spacecraft lines



is delivered to each of the experiments EFW and WBD that have their own converter and regulator circuits in their units.

- One separate +28 volts line is provided to the transmitter of WHISPER. This instrument which generates pulses at a middle voltage (200 volts) must be correctly isolated from the other power lines.

b/ Keep alive

n/a

c/ Switching concept

The ON/OFF switches for all the instruments, but the DWP, are included inside the WEC/PWR unit. The DWP may be switched ON or OFF by the general WEC ON/OFF command at the spacecraft level.

The main current in each of the two main bus lines will be measured in the Power Supply unit and monitored by the DWP. The current of the transmitter of WHISPER will be controlled inside this experiment.

d/ mechanism

The deployment phase is controlled by the micro processor of the EFW experiment with a possibility for the spacecraft to stop the procedure in case of problem.

The control is shown on fig 3.1/1.3.

Fig 3.1/1.1 WEC power distribution concept

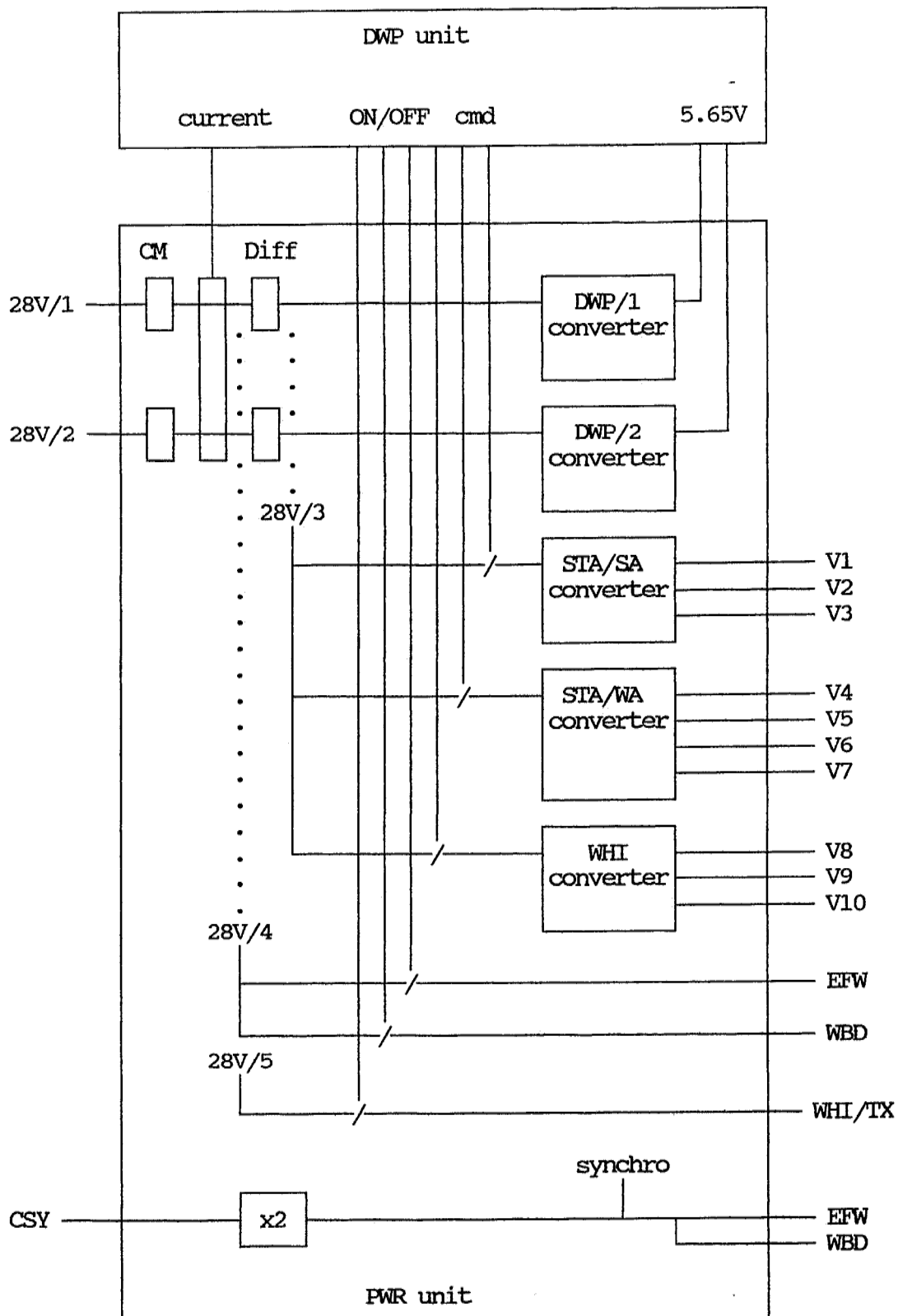
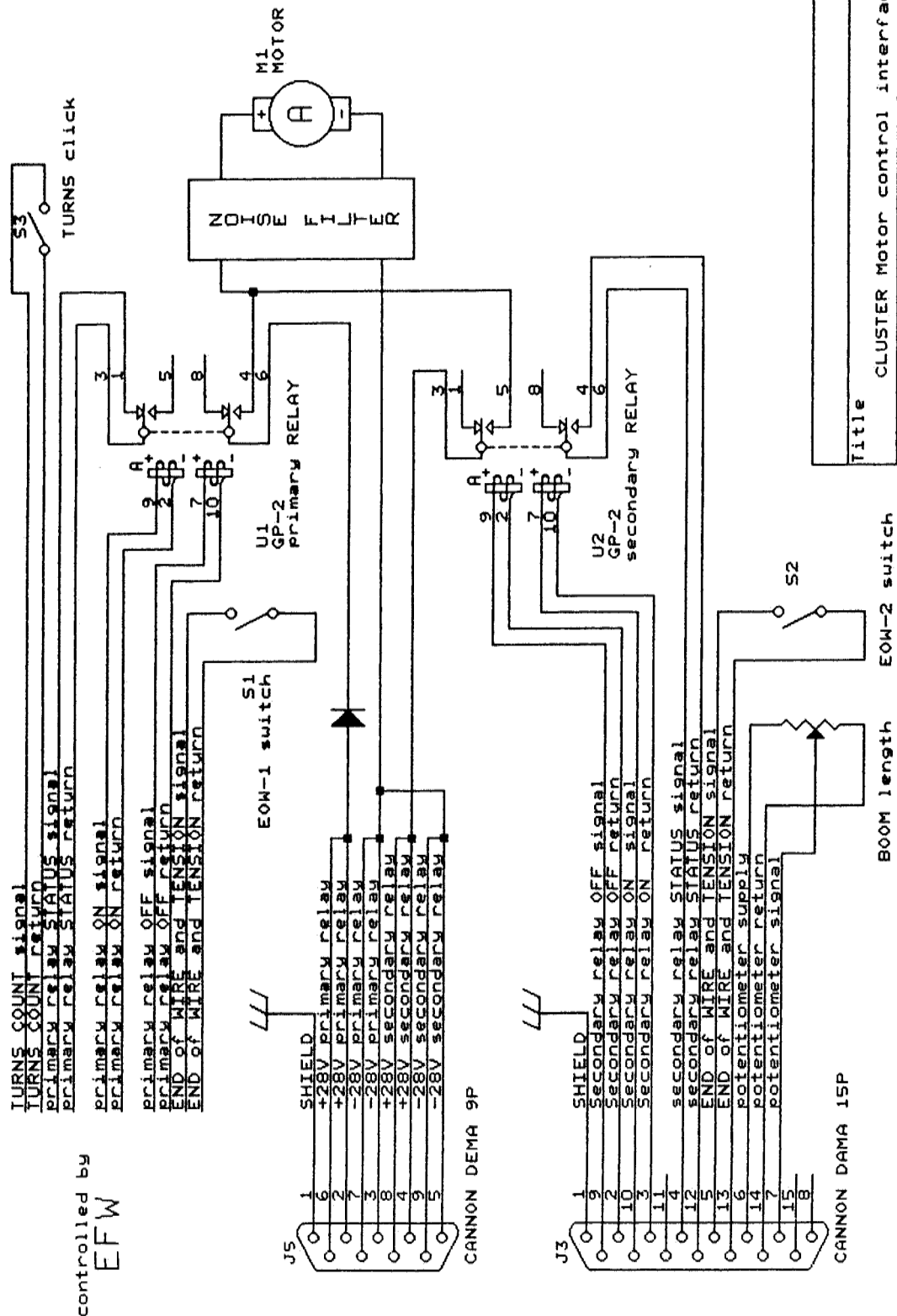


Fig 3.1/1.2 Power distribution of the deployment units

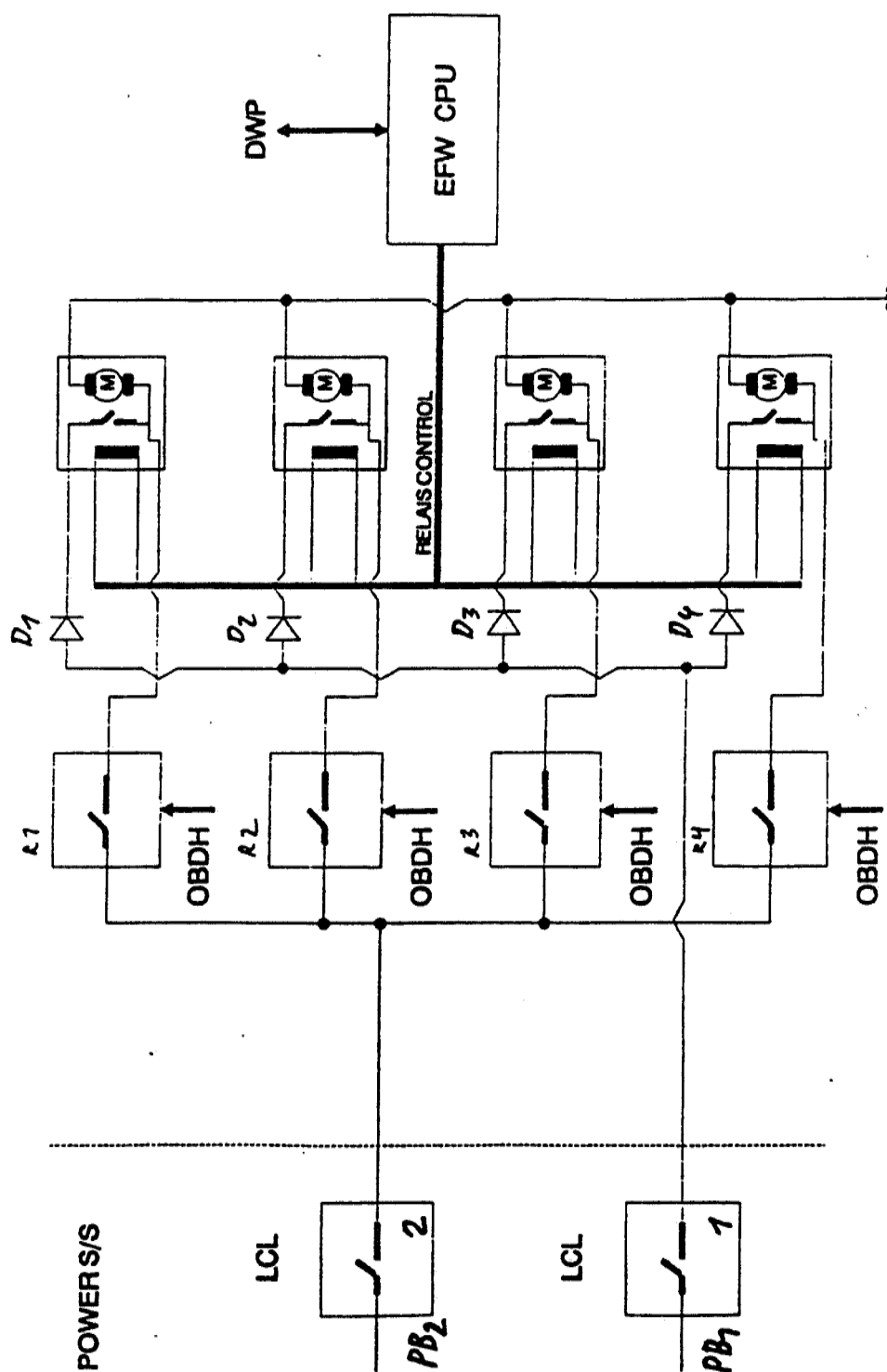
deployment-motor (S/C link)  
 power and control interface

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Fig 3.1/1.3 Deployment control of the deployment units







### 3.1.3 Power requirements

#### a) Power budget

The total WEC mean power consumption is 13.8 Watts if all the instruments are in their nominal mode, see table 3.1/2.a.

The allocation affected to WEC is 12.0 W

The WEC will work with a mean operational power consumption which is mode dependent (see tab 3.1/2.c) and can vary in the range 10.6 to 11.9 Watts.

Depending on the power available, WEC may operate between 12 and 13.8 W.

The total WEC maximum power is estimated to 17.5 Watts.

This figure is obtained with the assumption that all the WEC instruments are running simultaneously in their maximum individual power consumption. This is not foreseen during nominal operations.

Individual mean power per unit is given in table 3.1/2.

#### b) Power Profil

An estimated power profiles is given on figure 3.1/2.1

WHISPER Power Profile (fig 3.1/2.2)

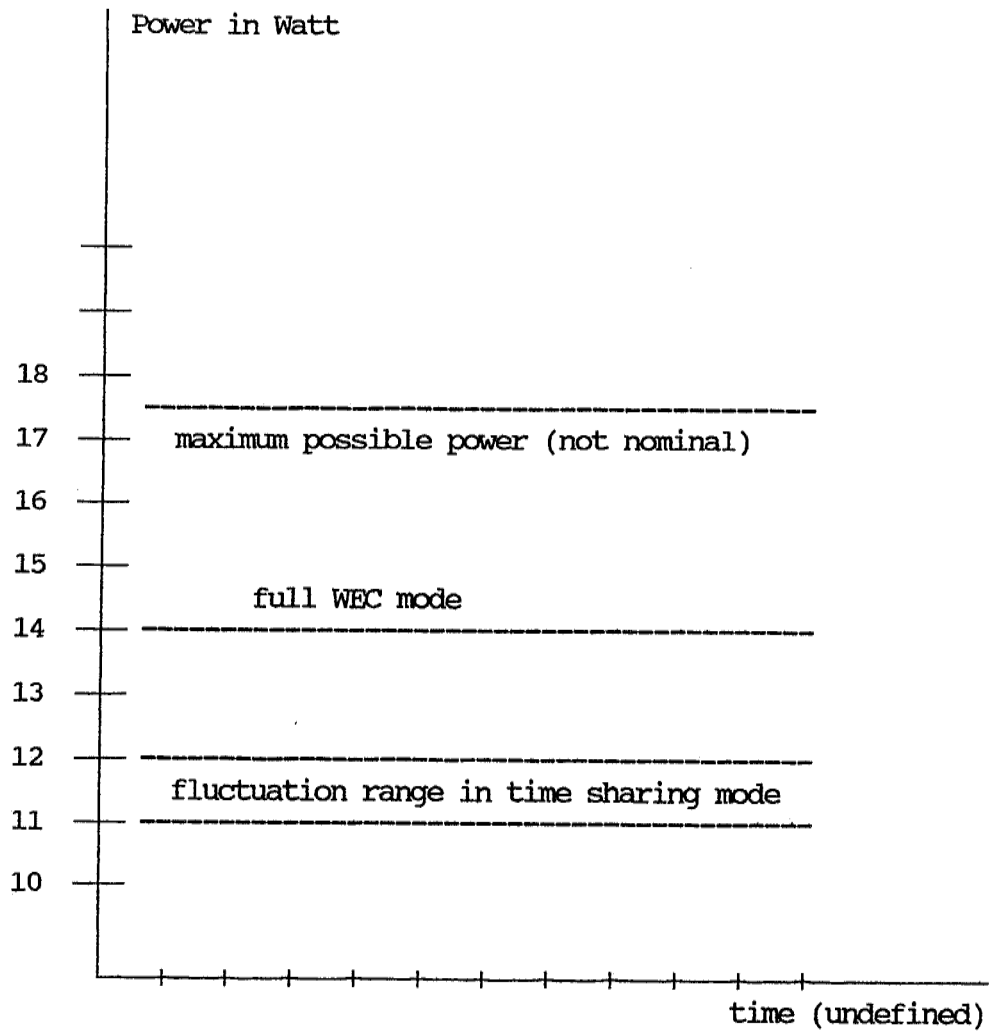
- Power profile in Natural wave mode :  
Constant power at 1.75 Watt (2.4 primary power)

- Power profile in sounding mode with a 1ms pulse at 100V and 80 kHz :

Constant power at 1.75 Watt (2.4 primary power)  
plus a mean power of 0.45 W (standard rate), slightly modulated at the repetition rate of the transmission (fig 3.1/2.1).

- Fig 3.1/2.2 shows a typical power profile of the WHISPER transmitted pulse. Due to the filtering at the input of the transmitter, the current pulse is largely reduced in the 27 V input line.

Fig. 3.1/2.1 : WEC power profiles



Power Watt

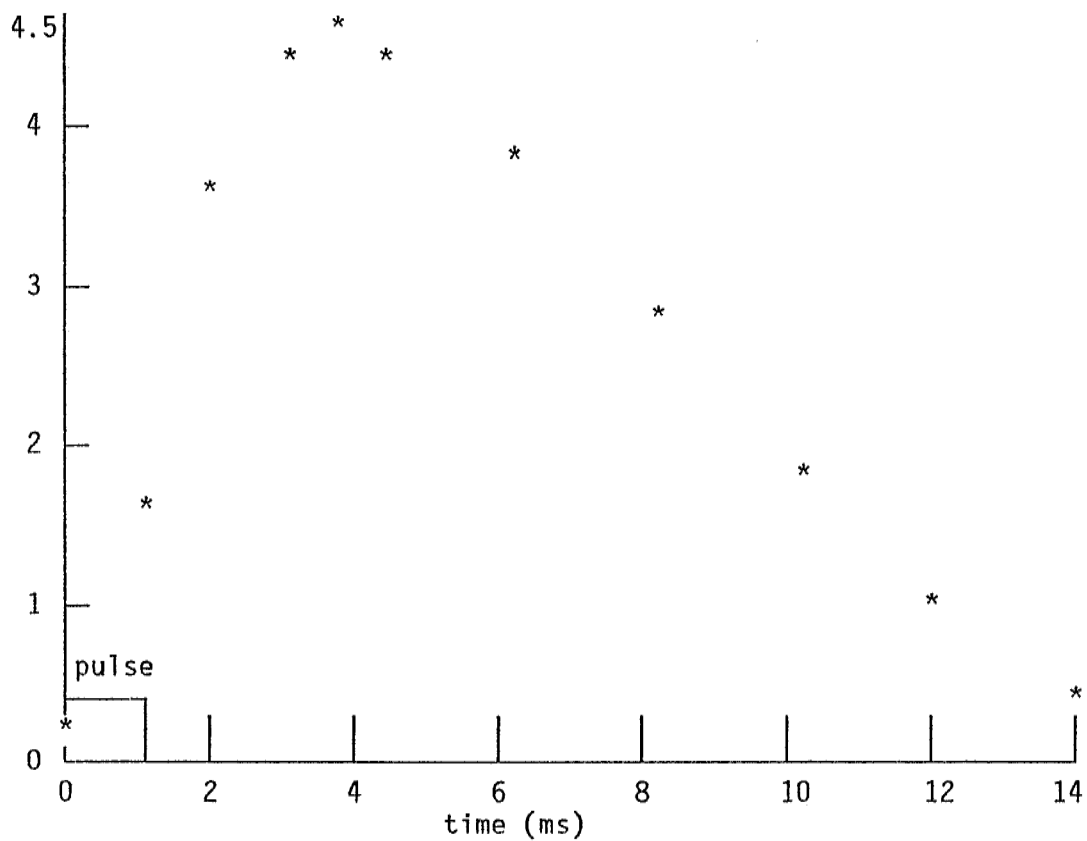


Fig 3.1/2.2 Whisper power profile



c) Turn on current

A typical turn-on current characteristic is shown on figure 3.1/3

d) Kal current

N/A

e) Unit average power

Typical examples of power dissipation versus operational modes are shown in table 3.1/3.

f) Mechanism

Power consumption during deployment phase is about 14 Watts when two motors are activated (see table 3.1/2.b). Each deployment unit will require power only when deploying the 50 meter boom. The current required to operate each motor is 100 - 150 mA. The motor startup spike (due to the lack of back EMF) is 1 amp with a decay time constant of .05 second at room temperature. This decay time constant can increase to about 10 seconds when the mechanism is very cold (-20 to -30 C) due to gearhead lubricant viscosity increase. In addition, there is a 2.6 Amp 0.8 A/microsec TBC spike decaying with a tbd microsecond time constant, caused by motor EMI filters.

The deployment will be performed by pair of opposite units, but the second units will start with a certain delay ( @ .1 s) after the first one.

During deployment the WEC Power must be turned on. DWP will turn on EFW to allow EFW to control the deployment motors.



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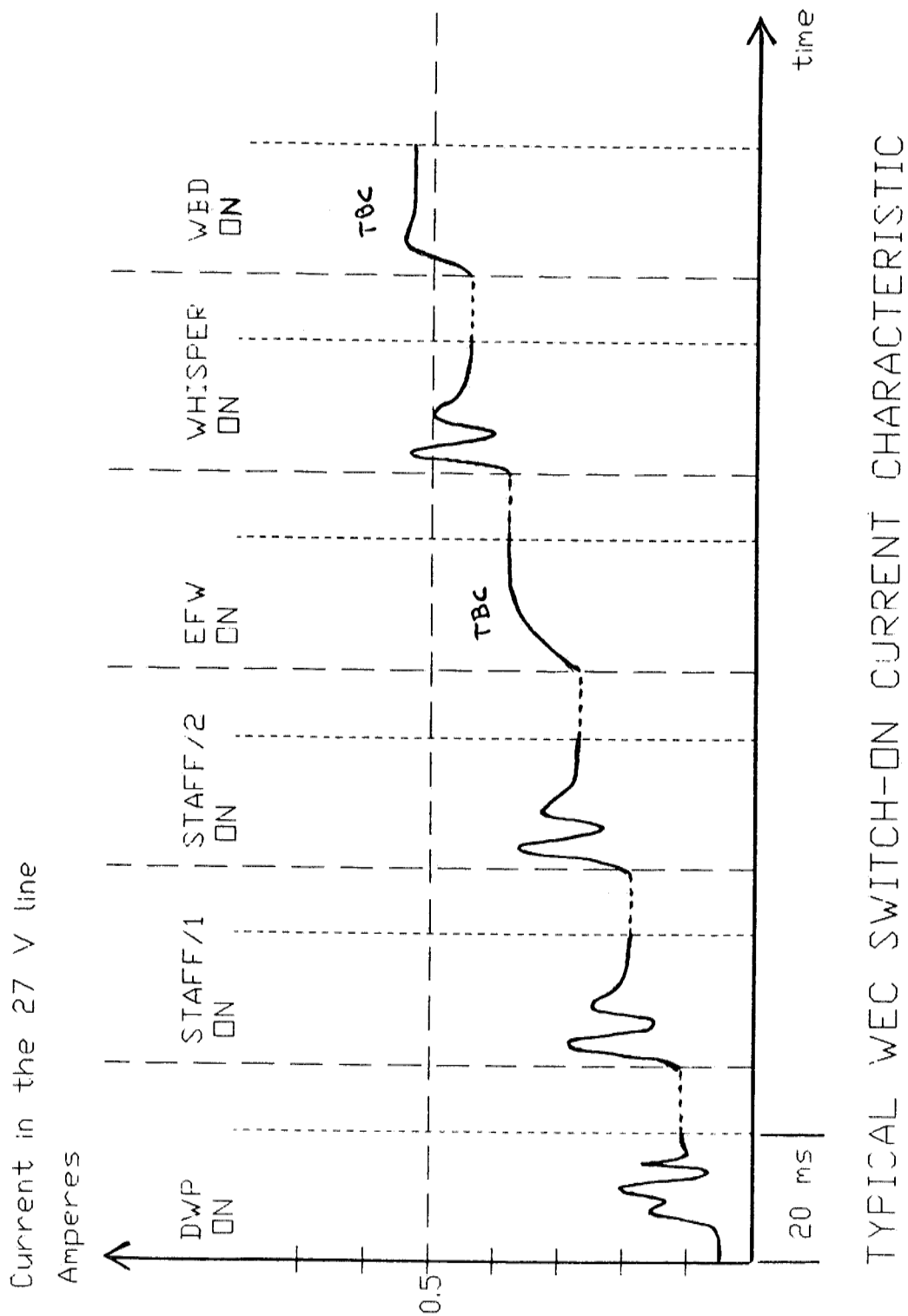
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Fig. 3.1/3 Typical WEC turn-ON characteristic



WEC POWER TABLE mW					
sub/unit	minimum	nominal	maximum	nominal per unit	
Probe 1 /EFW	50	90	100	90	P.1
Probe 2	50	90	100	90	P.2
Probe 3	50	90	100	90	P.3
Probe 5	50	90	100	90	P.4
WEC. 1 /EFW	130	160	200	160	WEC. 1
WEC. 2	130	160	200	160	WEC. 2
WEC. 3	130	160	200	160	WEC. 3
WEC. 4	130	160	200	160	WEC. 4
WEC. 5 /EFW	2000 (*)	2150 (*)	2400 (*)	2150	WEC. 5
sub/unit	reduced	nominal	maximum	nominal per unit	
WEC. 7 /STA		70	100	70	WEC. 7
WEC. 8				2720	WEC. 8
WEC. 8/1/STA		670	970		
WEC. 8/2/STA	1900	2050	2200		
WEC. 9				3700	WEC. 9
WEC. 9/1/WHI		1750	2000		
WEC. 9/2/DWP		1500	5200		
WHISPER / TX		450	1500		
WEC.10 /WBD		1700	1950	1700	WEC.10
WEC.11 /PWR				2480	WEC.11
for 8/1		350			
for 8/2		750			
for 9/1		650			
for 9/2		600			
for EFW		80			
for WBD		50			
Total WEC Power with all exp in nominal mode :				13 820	mW
Power allocated to WEC at selection :				11 750	mW

Tab 3.1/2.a Unit power requirement

(\*) the power consumption of EFW is extremely dependent of the level of the signal. The minimum or nominal values are expected the most part of the time, and the maximum value a few % of an orbit

WEC POWER TABLE mW				
sub/unit	minimum	nominal	maximum	nominal per unit
Probe 1 /EFW	50	90	100	90 P.1
Probe 2	50	90	100	90 P.2
Probe 3	50	90	100	90 P.3
Probe 5	50	90	100	90 P.4
WEC. 1 /EFW	100	120	200	120 WEC. 1
WEC. 2	100	120	200	120 WEC. 2
WEC. 3	100	120	200	120 WEC. 3
WEC. 4	100	120	200	120 WEC. 4
WEC. 5 /EFW	1800 (*)	1950 (*)	2400 (*)	1950 WEC. 5
sub/unit	reduced	nominal	maximum	nominal per unit
WEC. 7 /STA		70	100	70 WEC. 7
WEC. 8				2600 WEC. 8
WEC. 8/1/STA		850	970	
WEC. 8/2/STA	1450	1750	2200	
WEC. 9				3730 WEC. 9
WEC. 9/1/WHI	1200	1590	2000	
WEC. 9/2/DWP		1740	5200	
WHISPER / TX		400	1500	
WEC.10 /WBD		2130	2150	2130 WEC.10
WEC.11 /PWR				2460 WEC.11
for 8/1		400		
for 8/2		680		
for 9/1		570		
for 9/2		810		
Total WEC Power with all exp in nominal mode :				13 780 mW
Power allocated to WEC at selection :				11 750 mW

Tab 3.1/2.a Unit power requirement

(\*) the power consumption of EFW is extremely dependent of the level of the signal. The minimum or nominal values are expected the most part of the time, and the maximum value a few % of an orbit



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WEC POWER TABLE mW		
DEPLOYMENT CONFIGURATION		
WEC. 5 /EFW		1950
WEC. 9/2/DWP		1740
WEC.11 /PWR		810
WEC. a /motor ( a = 1 or 3 )		4200
WEC. b /motor ( b = 2 or 4 )		4200
Total Power in deployment phase :		12900 mW

Tab 3.1/2.b Power requirement during deployment





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UNIT \ MODE	A	PWR(mW)	B	PWR(mW)	C	PWR(mW)	D	PWR(mW)
WEC 7	nominal	740	nominal	740	nominal	740	nominal	740
WEC 8/1 STAFF/mwf	nominal	2050	reduced	1900	nominal	2050	OFF	2050
WEC 8/2 STAFF/spa	OFF		active	1750	passive	1750	passive	1750
WEC 9/1 WHISPER	nominal	1500	nominal	1500	nominal	1500	nominal	1500
WEC 9/2 DWP	nominal	3150	nominal	3150	nominal	3150	nominal	3150
WEC 1 to 5 EFW	nominal	1700	OFF		OFF		nominal	1700
WEC 10 WBD	ON	1830	ON	2430	ON	2430	ON	1730
WEC 11 PWR	OFF		ON	400	OFF		OFF	
WHISPER/tx								
expected Power (mW)	10 970	11 920	10 620	10 570				

Tab 3.1/2.c Examples of working modes of the Wave Consortium

### 3.1.4 Interface circuits

#### 3.1.4.1 With main bus :

- a) For WEC 11 (WEC power unit)

see Fig 3.1/4.1

- b) For WEC 1/4 (EFW)

see Fig 3.1/4.2

- c) For WEC 5 (EFW)

see Fig 3.1/4.3

- d) For WEC 10 (WBD)

see Fig 3.1/4.4

#### 3.1.4.2 With keep alive line :

N/A

### 3.1.5 Converter Synchronisation Interface

WEC11 receives the 131.072 kHz CSY clock from OBDH on one non redundant line.

This frequency is multiplied by two and the 262.144 kHz is used to synchronise the five DC/DC converters of WEC11.


The 262.144 kHz is also re-distributed to EFW and WBD to synchronise their own power supplies.

Since the synchronisation frequency is divided by two inside the PWR integrated circuits, all the DC/DC converters of WEC, EFW, WBD operate at 131.072 kHz.

Free running frequencies will be kept in a range of  $\pm 5\%$  w.r.t. the nominal frequency.

Interface circuits: Ref. to Fig. 3.1/5

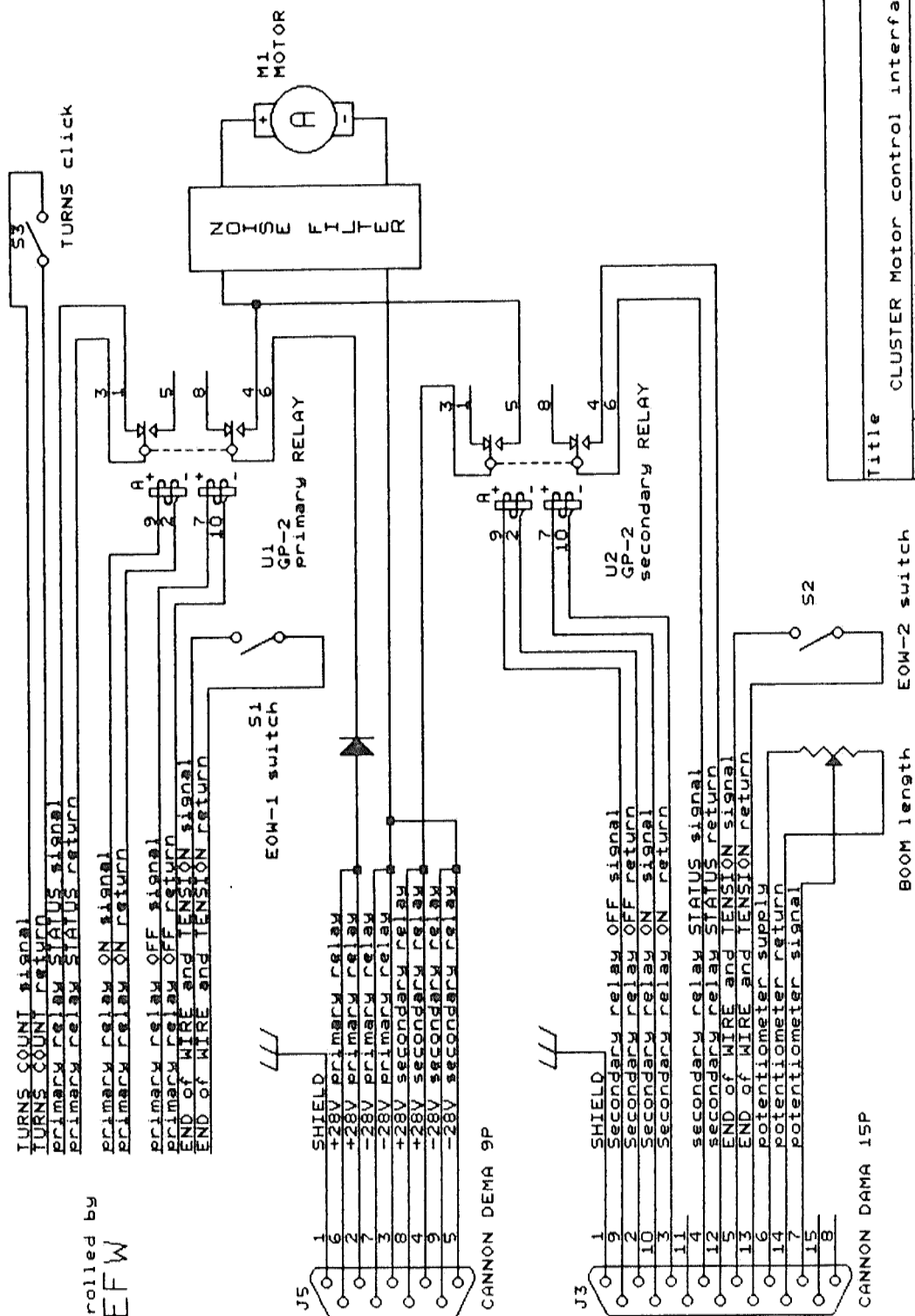


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deployment-motor (S/C link)  
power and control interface



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controlled by  
EFW

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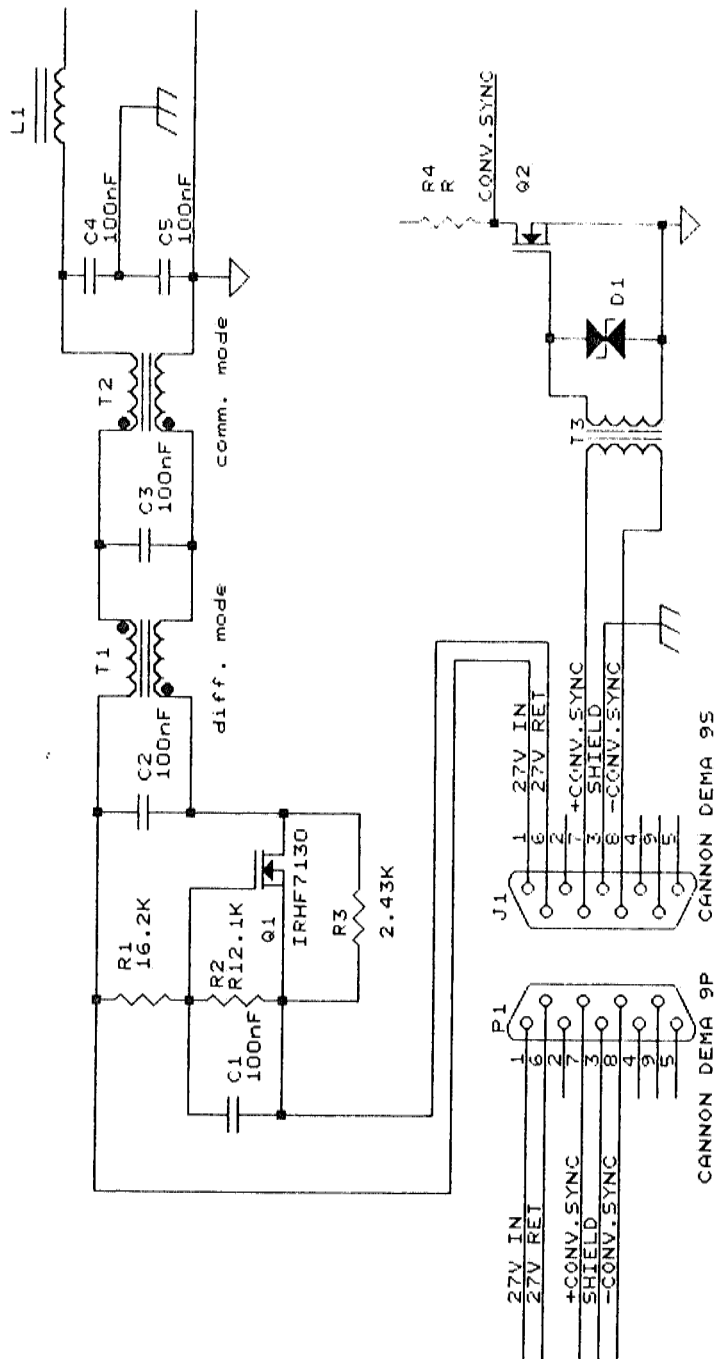
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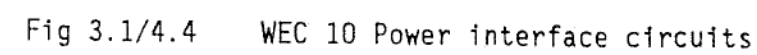
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Fig 3.1/4.3 WEC 5 Power interface circuits



DC/DC converter interface (WEC-5 to WEC11)  
WEC internal interface

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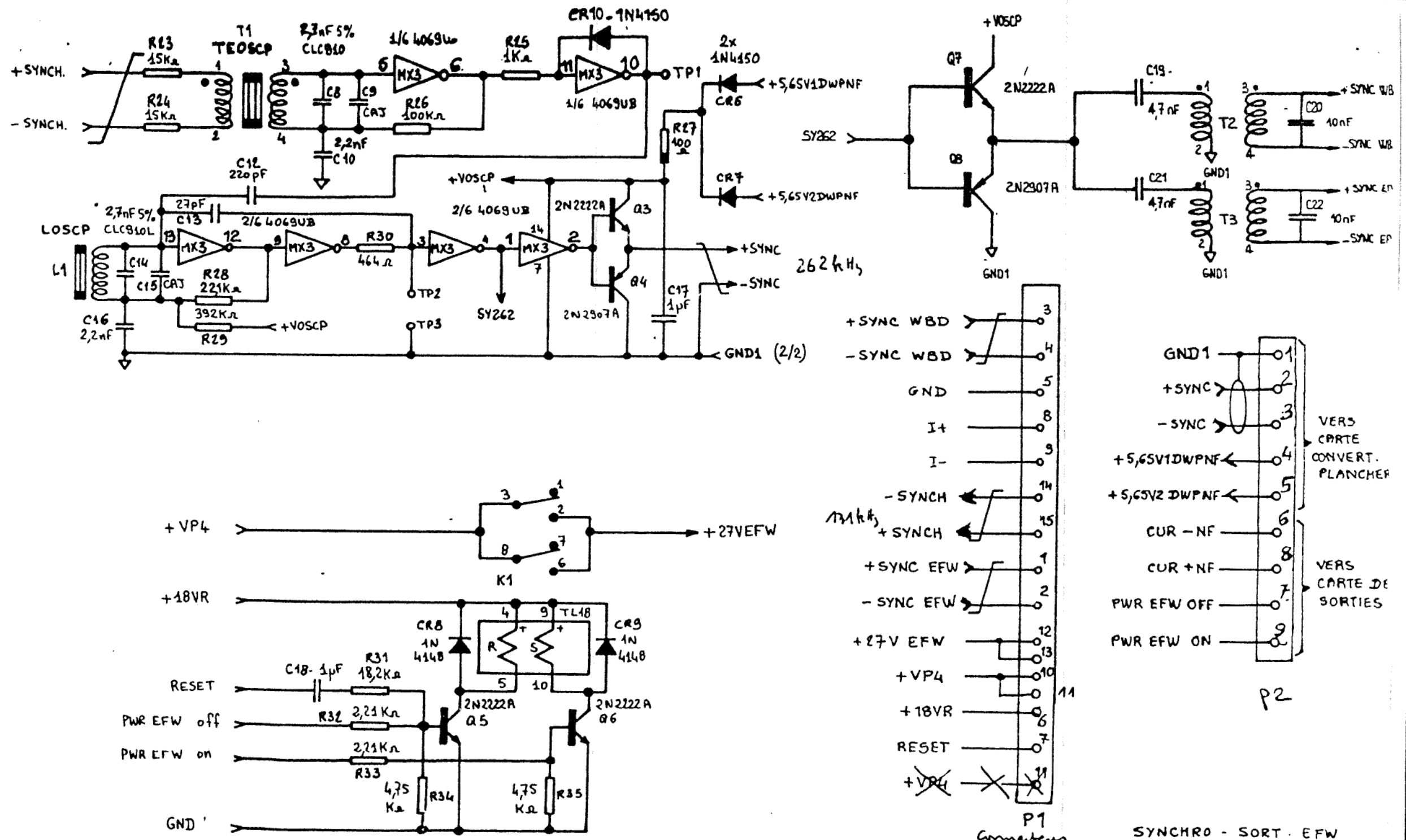


Fig 3.1/5 WEC 11 synchro interface circuit

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### 3.2 PYROTECHNIC INTERFACE

This section concerns only the boom deployment mechanisms.

#### 3.2.1 Electro Explosive devices

As defined by the tables 3.2/1 and 3.2/2.

FUNCTION	Number of Main Lines Required	Number of Redundant Lines Required
Pyro firing line	4	4

Table 3.2/1 Pyro interface requirement

#### 3.2.2 Alternative to EED's :

None

#### 3.2.3 Safety

The EEDs will comply with the safety request of EID Part A Section 11.

#### 3.2.4 Pyrotechnic Interface circuit

See Fig 3.2/1





Pyro type Procurement specification	ICI Americas ISE192 wire cutters MIL-STD 1512
Qualification status	previously flown on GEOS, ISEE, ISPM waivered for use on CRRES
Number of EED's Number of squibs per EED's	2 per deployment unit 1 (integral)
Electrical characteristics Max All-Fire Min No-Fire Bridge Resistance Insulation Resistance between shorted Kads and case Electrostatic discharge from a 500 pF through a 5K $\Omega$ from leads to case Operating temperature Storage temperature	5,0 A - 10 ms 1,0 A - 5 minutes 1 $\Omega$ $\pm$ 0.1 $\Omega$  100 M $\Omega$ at 500 V  50 KV - 40 C + 66 C - 54 C + 71 C
Mechanical Characteristics Weight Maximum pyrotechnic Weight Dimensions	2,250 g  0,025 g 19,05 mm L x 4,699 mm diam
Storage Life	10 years


Table 3.2/2 Pyrotechnic data



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Diagram illustrating the PYRO SHORTING JUMPER assembly. The assembly includes the EED HOUSING, PYRO CONNECTOR J4, and the PYRO SHORTING JUMPER.

The EED HOUSING contains two EEDs (EED #1 and EED #2) connected to PYRO CONNECTOR J4. The PYRO CONNECTOR J4 has pins 8, 9, 1, 2, 6, 4, and 5. The PYRO SHORTING JUMPER has two SHORT-PYRO (DEH-9P) connectors. The first connector has pins 8, 9, 1, 2, 6, 4, and 5. The second connector has pins 8, 9, 1, 2, 6, 4, and 5. The PYRO SHORTING JUMPER is connected to the PYRO CONNECTOR J4 and the PYRO SHORTING JUMPER. The PYRO SHORTING JUMPER is connected to the PYRO SHORTING JUMPER. The PYRO SHORTING JUMPER is connected to the PYRO SHORTING JUMPER.

MATERIAL _____	U.S. STD THIRD ANGLE PROJECTIONS 	SPACE SCIENCES LABORATORY UNIVERSITY OF CALIFORNIA, BERKELEY, CA 94720 (415) 642-7297 FAX (415) 643-7629	
FINISH _____	DIMENSIONS UNLESS OTHERWISE SPECIFIED	TITLE	
DRAWN BY NO/YR D PANKOV 10/90	STANDARD BILATERAL TOLERANCES: ± .XX - .XX° ANGLES SURFACES ± .XXX - .XXX° ± .X° ✓	EFW WEC 1-4 WIRE HARNESS SCHEMATIC	
APPROVED NO/YR D PANKOV 10/90	SCALE - DO NOT SCALE - 1 : 2	DRAWING NO. 26306 - 009	REVISION B SHEET

### 3.3 ON-BOARD DATA HANDLING INTERFACE

#### 3.3.1 Channel Allocation

Interface Parameter	Signal Type or functions	Number of main Channels	Number redundant Channels
Telecommand Channels	Memory Load Command (16 bit) WEC 9.2 Switch closure on/off command	1 0	1 0
Telemetry Channels	Serial 16 bit (Science) WEC 9.2 Serial 16 bit (Science) WEC 10 Serial 16 bit (Housekeeping) WEC 9.2	1 1 1	1 1 1
Timing Channels	Reset Pulse WEC 9.2 Reset Pulse WEC 10 High Frequency clock	1 1 0	1 1 0
Service Channels	Sun Reference Pulse WEC 9.2 Spin Segment Clock WEC 9.2 Experiment Converter Synch. WEC 11	1 1 1	1 1 n/a
Thermistor Channels	S/C Powered	0	n/a

Table 3.3/1 Experiment OBDH Interfaces : WEC

#### Functional Descriptions :

##### a) Telecommand channels :

16 bit serial, active high data, most significant bit first, as described in TTC-B-01.  
Redundancy implementation TBD.

##### b) Telemetry channels :

16 bit serial, active high data, most significant bit first, as described in TTC-B-01.  
Redundancy implementation TBD.

##### c) Timing channels :



Exact frequency and timing TBD.

- d) Service channels.

CSY synchro frequency is at 131 kHz.

### 3.3.2 Electrical Interface Circuits

Compliant with ESA document TTC-01.

Exact implementation of redundancy TBD. The following circuits implement separate circuits for the normal and redundant channels, it is understood that this is not the most desirable solution.

#### 3.3.2.1 Telecommand circuit

WEC 9.2 see Fig 3.3/1

#### 3.3.2.2 Telemetry circuit

- a) WEC 9.2  
see Fig 3.3/2.1

- b) WEC 10  
see Fig 3.3/2.2

#### 3.3.2.3 Timing circuit

- a) WEC 9.2  
see Fig 3.3/3.1

- b) WEC 10  
see Fig 3.3/3.2

#### 3.3.2.4 Service Interface circuit

- a) WEC 9.2  
see Fig 3.3/4.1

- B) WEC 11  
see Fig 3.3/4.2



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Fig 3.3/1

WEC 9.2 Telecommand Data Interface Circuit

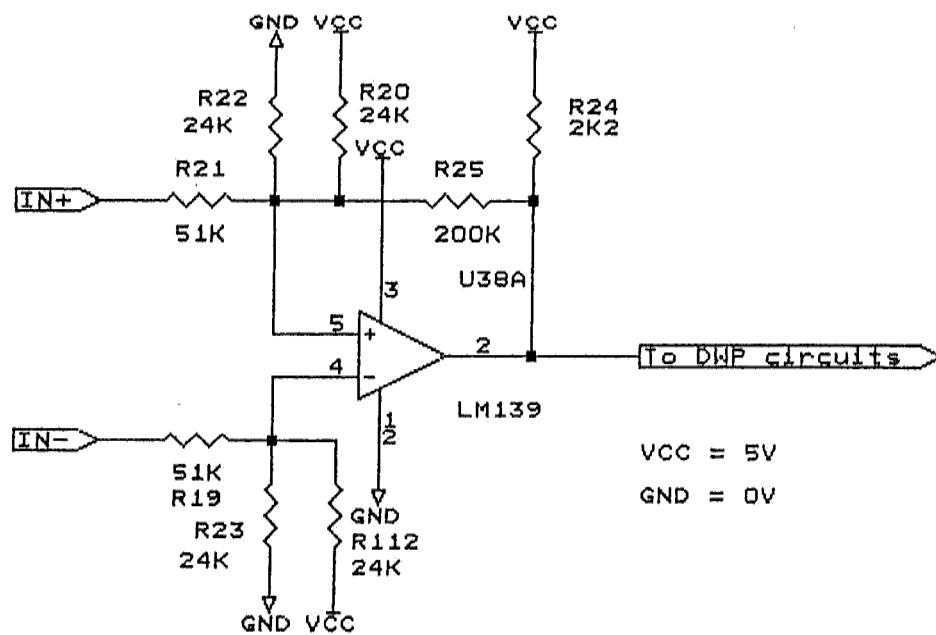


Fig 3.3/2.1 WEC 9.2 Telemetry Data Interface Circuit

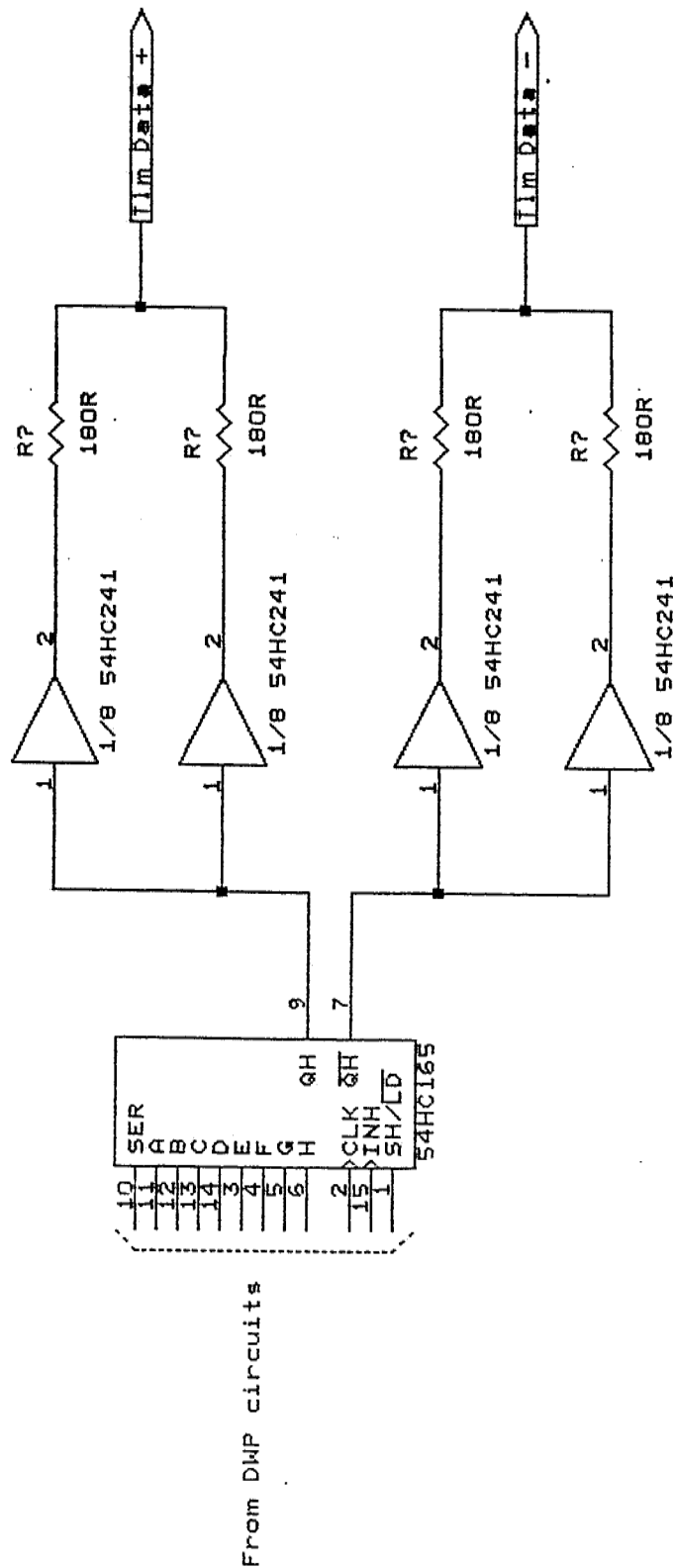
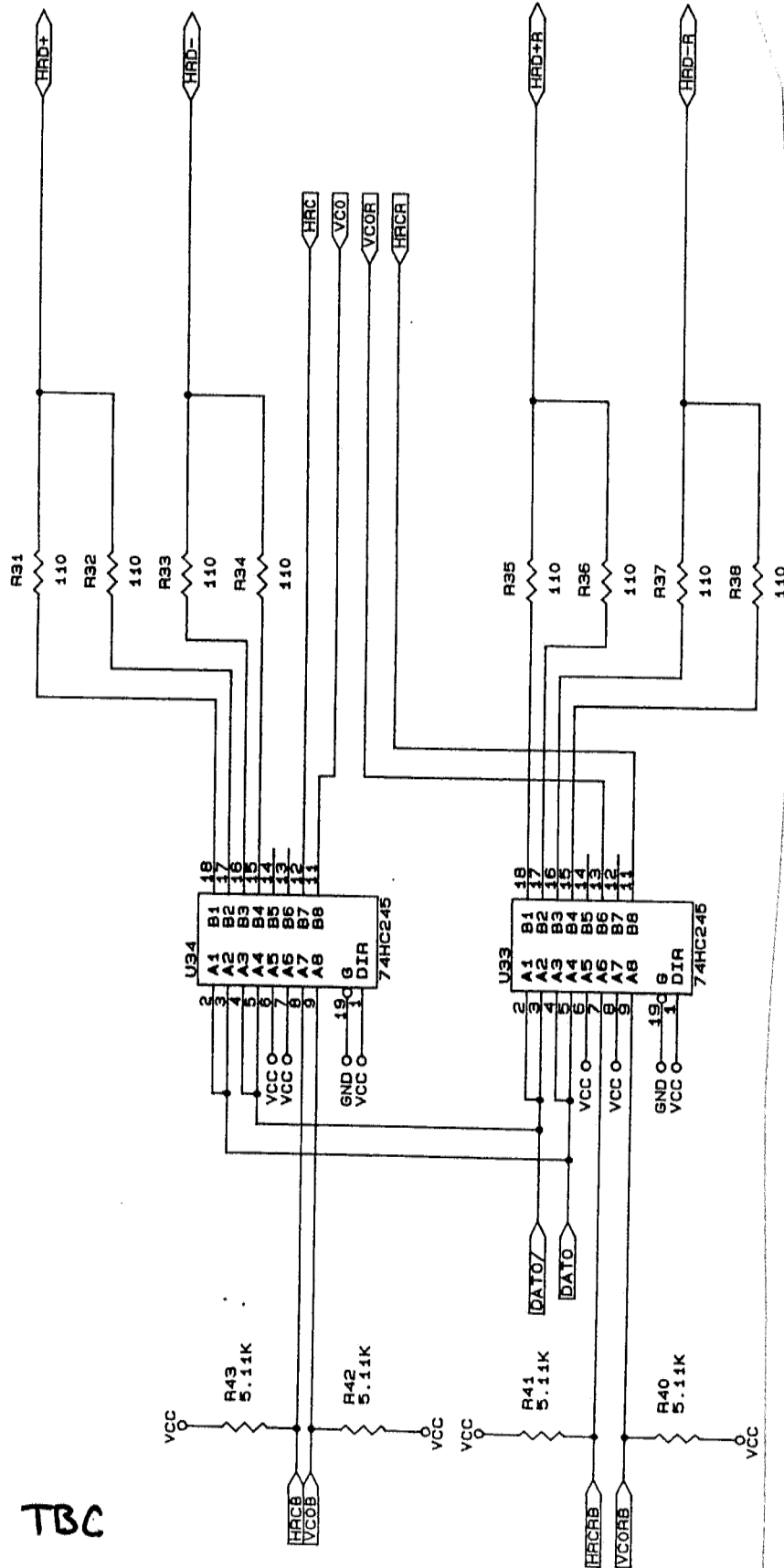


Fig 3.3/2.2 WEC 10 telemetry interface circuit



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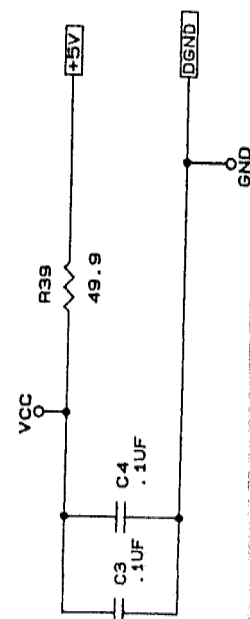


Fig 3.3/3.1 WEC 9.2 Timing (Clock and Sample) Interface Circuit

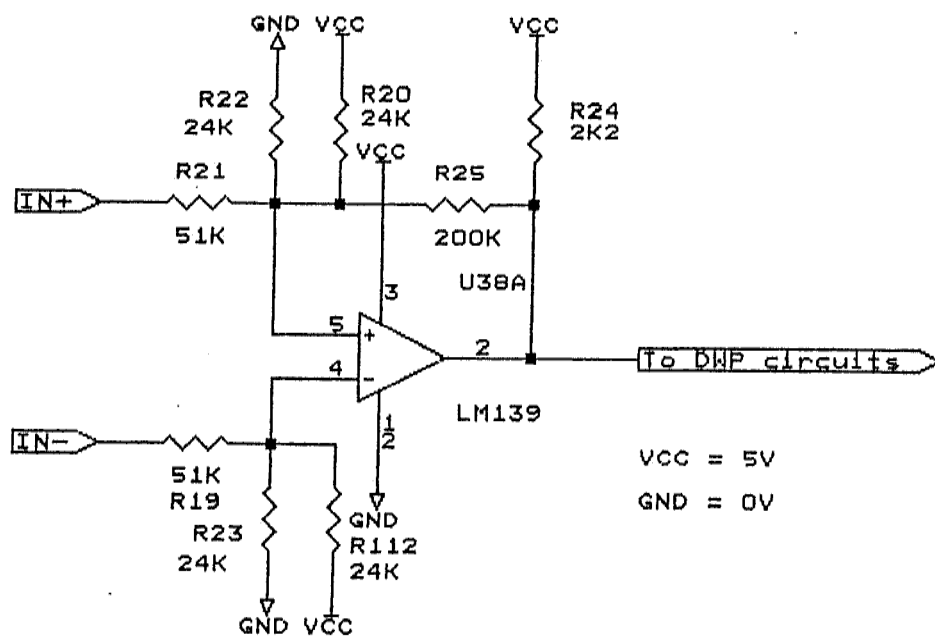
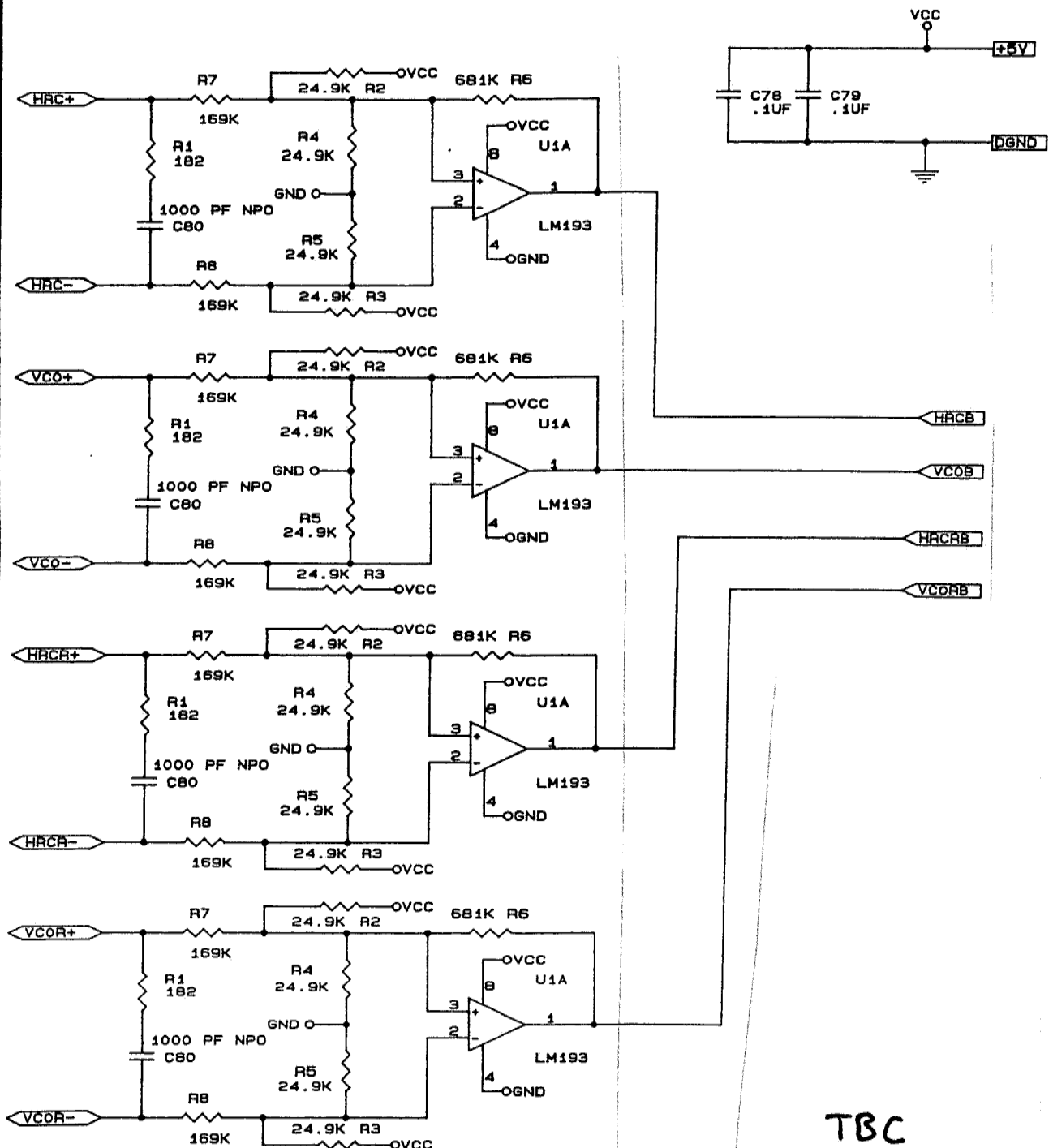




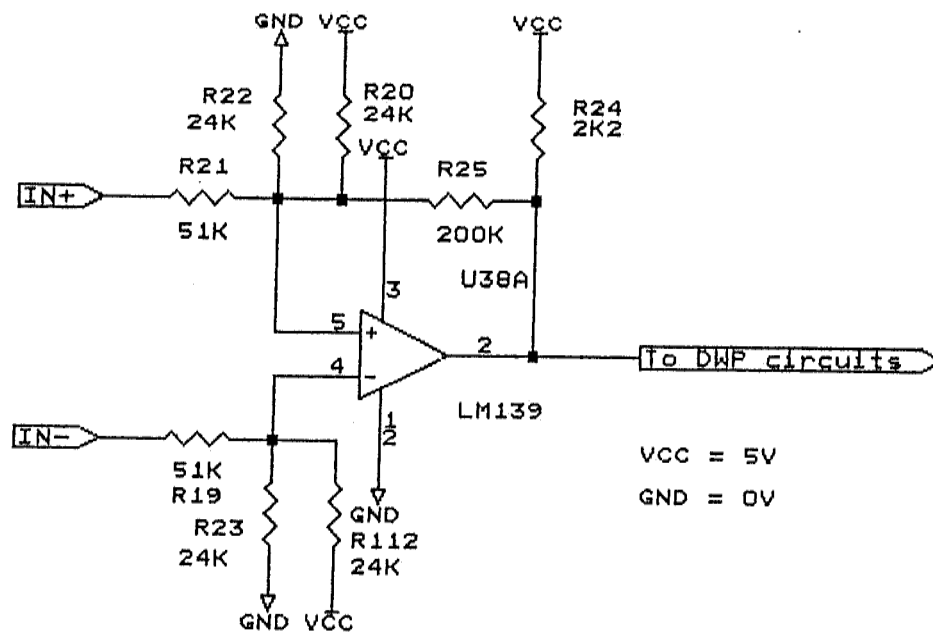
Fig 3.3/3.2 WEC 10 timing interface circuit



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Date		University of Iowa	
Drawn: W. Robison		Dept. of Physics & Astronomy	
Designed: J. Phillips		Iowa City, IOWA, USA	
Approved:		CLUSPB.SCH	
Archived:		Title Cluster WBD HR interface	
		Size Document Number	
		B 92-31002	
		REV 0	
		Date: March 7, 1991 Sheet 1 of 1	

Fig 3.3/4.1 WEC 9.2 Service Signals Interface Circuit



### 3.3.3 Timing

Timing information will be included within the data field of telemetry packets - exact format TBD.

Timing information will be derived from the Reset Pulse and from clocks generated internally within DWP. Typical resolution of 128 micro-second. Note that the OBDH High Frequency Clock is NOT required.

### 3.3.4 Bit Rate Requirement

	allocation	block size	exact bite rate
NM 1	5.2 Kbps	336	5217.17 bps
NM 2	5.2 Kbps	336	5217.17 bps
NM 3	5.2 Kbps	336	5217.17 bps
BM 1	43.8 Kbps	456	43898.73 bps
BM 2	91.5 Kbps	950	91455.69 bps
BM 3	tbd	tbd	tbd
WBD M	220.0 Kbps	n/a	220752.00 bps
HK	250 bps	192	298.12 bps

Table 3.3/2 Bit Rate Requirements

### 3.3.5 Monitoring

#### a/ Concept

DWP will maintain at all times during the operation of WEC a "housekeeping block" within the "kernel processor module" memory.

The housekeeping block is continuously updated by DWP, and a "housekeeping snapshot" taken on the first transistion of the DWP "master clock" that occurs after an OBDH reset pulse. This housekeeping snapshot can be read by the spacecraft OBDH by transitions on the RTU housekeeping TM sampling line.

The Spacecraft RTU serial digital telemetry (SDT) interface to DWP will be configured to be 16 bits.

The current size of the Housekeeping block is 96 words.

## b/ Housekeeping telemetry contents

The correct reception and execution of all telecommands will be reported in the housekeeping telemetry. The correct and safe functioning of the experiment will also be verifiable through the housekeeping telemetry.

a summary list of the housekeeping parameters is given on table 3.3/3. A complete description of each parameters , as required for entry into the AIT data base, will be provided as a dedicated document.

Word	Description
0	DWP model tag
1	reset count
2	snapshot offset
3	DWP operation error word
4	WEC operation error word
5	current WEC mode (macro slot number)
6	current DWP configuration
7	processor module 0 health (links)
8	processor module 1 health (links)
9	processor module 2 health (links)
10	DWP clock status
11	current OBDH acquisition mode
12-14	WEC instrument power status
15	EFW processing control
16	STAFF/SA processing control
17	STAFF/WA processing control
18	WHISPER processing control
19	WBD processing control
20	DWP correlation control
21	DWP memory read address pointer
22	DWP memory write address pointer
23	external experiment status
24	last DWP configuration telecommand
25	initial WEC power on status
26	instrument/interface failure
27-42	memory load echo
43-50	analogue monitor values (16 bytes)
51-52	EFW H/K
53-65	STAFF H/K
66-74	WHISPER H/K and WBD gain
75-76	WBD H/K
77-78	EFW boom potential (V1-V2, V3-V4)
79-80	SPARE particle correlator)
81-96	additional H/K (EFW)

Tab 3.3/3 Housekeeping parameters list



3.4

INTERFACES TO OTHER EXPERIMENT

DWP -> EDI	
Data:	WHISPER blanking pulse
Requested by:	EDI
Interface type:	Digital serial link using differential drivers.
Cable requirements:	1 x twisted shielded pair cable TBC grounded at DWP.
Comments:	see 3.4.1

Table 3.4/1 : WEC/EDI IEL

DWP -> ASPOC	
Data:	EFW Spacecraft potential and WHISPER synchronisation
Requested by:	ASPOC
Interface type:	Digital serial link 1 clock and 1 data line using differential drivers.
Cable requirements:	2 x screened twisted pair cable grounded at DWP.
Comments:	see 3.4.2

Table 3.4/2 : WEC/ASPOC IEL



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DWP -> CIS	
Data:	EFW Spacecraft potential and WHISPER synchronisation
Requested by:	CIS
Interface type:	Digital serial link 1 Clock and 1 data line using differential drivers.
Cable requirements:	2 x screened twisted pair cable grounded at DWP.
Comments:	see 3.4.2

Table 3.4/3 : WEC/CIS IEL

FGM -> DWP	
Data:	Magnetic Field
Requested by:	EFW
Interface type:	Digital serial link 1 Clock and 1 data line using differential receivers.
Cable requirements:	2 x screened twisted pair cable grounded at FGM.
Comments:	See 3.4.3

Table 3.4/4 : WEC/FGM IEL



DWP -> PEACE	
Data:	WHISPER synchronisation
Requested by:	PEACE
Interface type:	Digital serial link 1 Clock and 1 data line using differential drivers.
Cable requirements:	2 x screened twisted pair cable grounded at DWP.
Comments:	See 3.4.4

Table 3.4/5 : WEC/PEACE IEL

PEACE -> DWP	
Data:	Electron plate pulse
Requested by:	DWP
Interface type:	Digital serial link using differential receivers.
Cable requirements:	1 x screened twisted pair cable grounded at PEACE.
Comments:	DWP particle correlator See 3.4.4

Table 3.4/6 : PEACE/WEC IEL



STAFF -> EDI	
Data:	Magnetic wave components
Requested by:	EDI
Interface type:	3 analogic signals
Cable requirements:	3 tsp overall shielding grounded at STAFF
Comments:	See 3.4.5

Table 3.4/7 : STAFF/EDI IEL

#### 3.4.1 Distribution of WHISPER blanking pulse

##### a/ Purpose

The WHISPER instrument in its investigation of plasma electron densities, employs the established technique of Resonance Sounding. This requires the transmission of a radio wave over a limited time period at a fixed frequency.

Eventually, natural resonances of the plasma in that frequency range will be triggered, and are detected by a radio receiver on WHISPER immediately after the wave transmission is complete.

The frequency is then increased by a constant step value, and the process is repeated. A succession of these steps constituting a sweep, allows the properties of the neighbouring plasma to be investigated throughout the range of interest.

##### b/ data transmission

DWP informs other CLUSTER instruments of an imminent WHISPER rf transmission in one of two ways. The simplest is the distribution of a Blanking Pulse covering the period of the rf transmission. The other method is for DWP to send special words across the spacecraft potential interface (see 3.4.2). Upon receipt of a DWP generated warning the other instruments may then inhibit sensitive sensors and/or suspend operation.

##### c/ Interface circuits

Differential driver i/f shown in fig 3.4/1.



The EDI experiment is recommended to use the differential receiver interface shown in Fig 3.4/2.

d/ Timing and synchronisation

The timing of the Blanking Pulse is shown in Fig 3.4/4.1.

The period between successive blanking pulses depends on the operation mode of the WHISPER instrument and is a minimum of 13.3 ms. Bursts of WHISPER activity will be synchronised to spacecraft spin in some WHISPER modes. WHISPER transmission and spin synchronisation is described in detail in section 3.4.2 and Fig 3.4/4.4.

3.4.2 Spacecraft potential and WHISPER synchronisation

a/ Purpose

Two instruments receive information on the spacecraft potential from the EFW instrument (ASPOC and CIS). This potential can be as high as +50 V for spacecraft in the magnetosphere, and can make some types of plasma measurement almost impossible.

ASPOC controls the CLUSTER spacecraft ion emitters in a feedback loop with the EFW instrument which measures the spacecraft potential. ASPOC holds the spacecraft potential at a point such that there is no net transfer of charge between the spacecraft and its environment.

DWP also encodes within the spacecraft potential word, information about WHISPER rf transmissions and synchronisation with spacecraft spin.

b/ data transmission

DWP transfers words across the serial interface by setting the PotData line to the MSB of the data word value, and then taking the PotClock line to logic low. The other 15 (TBC) bits of data should be latched by the receiving instruments on the falling edge of subsequent clock pulses.

Note that PotClock is low when the interface is inactive. A Gate pulse may be generated by the receiving instrument, by connecting PotClock to the input of a 4098 retriggerable monostable with a time constant of 1 ms (min)

c/ Interface circuits

Differential driver shown in fig 3.4/1.



d/ Timing and Synchronisation

The timing characteristics for the interface are shown in Fig 3.4/4.

The format of the word transmitted to ASPOC and CIS is shown in tab 3.4/2.2

Bits	Description
15	1 if new spacecraft potential
14 - 12	WHISPER transmission information
11 - 0	Spacecraft potential value

Tab 3.4/2.2

Spacecraft Potential value will be transmitted once per spacecraft spin by DWP (top bit of the word set to 1). The format of the potential value (12 bits) is TBD.

Before and after each burst of WHISPER rf transmission, a word will be transmitted across the interface. The WHISPER transmission information can be decoded as shown in tab 3.4/2.3.

Bits 14 13 12	WHISPER Command
0 0 0	No command
0 0 1	Start glide
0 1 0	Stop glide
0 1 1	Start synchronous
1 0 0	Stop synchronous
1 0 1	Start continuous
1 1 0	Stop continuous
1 1 1	undefined

Tab 3.4/2.3

The WHISPER instrument has three synchronisation modes. These are Gliding, Synchronous and Continuous. These methods of synchronisation are described below and in Fig 3.4/4.4.

The Gliding synchronisation mode divides the spin of the spacecraft into a number of equal period spin segments. Spin segment 0 starts at the Sun Reference pulse. Each spin of the spacecraft, WHISPER will only be allowed to transmit during one spin segment (the WHISPER segment). WHISPER may transmit more than



one rf pulse during the WHISPER segment. The first rf pulse will be preceded by the Start Glide command, and the last rf pulse will be followed by the Stop Glide command. On the next spin of the spacecraft, the new WHISPER segment will be the segment immediately following the WHISPER segment in the last spin.

The Synchronous mode synchronises the WHISPER rf transmissions to the voltage flyback period of the electron plate detectors. Voltage flyback occurs 16 or 32 times per spin of the spacecraft. WHISPER will only transmit a single rf pulse 16 or 32 times per spin, synchronised to the voltage flyback period. A Start Synchronous command is sent before the single rf pulse, and a Stop Synchronous command immediately after.

In the Continuous mode WHISPER is not synchronised with the spin of the spacecraft, and transmits rf pulses at intervals of multiples of 13.3 ms. A Start Continuous command is sent by DWP before every rf pulse, and a Stop Continuous command afterwards.

DWP will send the appropriate Start command for the mode at least 1.11 ms (TBC) before the start of the first rf pulse, and the Stop command for the mode no sooner than 1 ms (TBC) after the end of the last rf pulse.

DWP will ensure that there is an interval of at least 2 ms between the transmission of any two words to allow the receiving instrument time to recognise and read the first word.

### 3.4.3 Supply of FGM Data to EFW

#### a/ Purpose

EFW requires FGM data so that Electric field phenomena can be related to the ambient magnetic field (Eg polarisation). DWP will interface to FGM, and transmit received FGM vectors across the DWP to EFW control interface.

#### b/ Data exchange

FGM data will be transmitted to DWP as a word of length 64 bits transmitted over a serial interface. FGM transfers its data by setting the FGMDData line to the LSB (bit 0) of the FGM word, and then taking the FGMClock line to logic high. The other 63 bits of data are latched by DWP on the rising edge of subsequent clock pulses.

#### c/ Interface circuits

The differential receiver shown in fig 3.4/2.

**d/ Timing and Synchronisation**

The timing characteristics for the interface are shown in Fig 3.4/4.3.

FGM will provide magnetic field vectors 16 times per second, contained in 64 bit words. The structure of the word is shown in Tab 3.4/3.2

Synchronisation is provided by logical zeros and start bits.

Bits	Description
0	start bit (logical 1)
1 - 12	X component (12 bits) of B-field
13 - 24	Y component (12 bits) of B-field
25 - 36	Z component (12 bits) of B-field
37 - 39	range (3 bits)
40 - 63	logical 0

Tab 3.4/3.2

The FGM clock runs at a continuous rate of 1024 Hz, with no inactive periods between 64 bit words.

**3.4.4 DWP to PEACE Interface****a/ Purpose**

Electron Plate Pulses from the PEACE instrument are required by the DWP particle correlator. A signal from PEACE to DWP supplies a clock whose frequency varies with the number of electrons detected.

The PEACE plate sensor selection is controlled by DWP. Once per spacecraft spin DWP will send a plate selection command over a control interface.

In addition, DWP will send WHISPER transmission and spin synchronisation information across the control interface.

**b/ data exchange**

An 8-bit counter circuit will allow DWP to count the number of pulses in any specified time interval. Counter reset and register facilities will be provided.

The PEACE control byte is transmitted by DWP as an 8-bit serial signal. DWP transfers the control byte by setting the PCData line to the MSB (bit 7) of the control byte, and then taking the



PCclock line to logic low. The other bits of the byte are transferred on subsequent clock pulses.

Note that PCclock is low when DWP is not transmitting control bytes to PEACE. A Gate pulse may be generated by the receiving instrument by connecting PCclock to the input of a 4098 retriggerable monostable with a time constant of 1 ms (min).

c/ Interface circuits

The differential driver shown in Fig 3.4/1 will be used for the transmission of the signal to PEACE.

The differential receiver shown in Fig 3.4/2 will be used for the reception of pulses signal from PEACE.

d/ Timing and Synchronisation

Electron Plate Pulses at a frequency of up to 1 MHz are expected. Minimum pulse width should be 500 ns and the pulse counter will be incremented on the rising edge of the pulse.

PEACE will supply pulses from one of 16 electron detectors. DWP will select the detector to be used each spin by sending a control byte down the PEACE control interface (with bit 7 set to 1).

The format of this control byte is shown in Tab 3.4/4.2

Bits	Description
7	1 if correlator changed
6 - 4	WHISPER transmission information
3 - 0	Correlator channel select

Tab 3.4/4.2

Before and after each burst of WHISPER rf transmission, a word will be transmitted across the interface. The WHISPER transmission information can be decoded as shown in Tab 3.4/4.3



Bits 6 5 4			WHISPER Command
0	0	0	No command
0	0	1	Start glide
0	1	0	Stop glide
0	1	1	Start synchronous
1	0	0	Stop synchronous
1	0	1	Start continuous
1	1	0	Stop continuous
1	1	1	undefined

Tab 3.4/4.3

The WHISPER synchronisation protocol is described in section 2.4. DWP will ensure that there is an interval of at least 2 ms between the transmission of any two control bytes to allow PEACE to recognise and read the first control byte.

The timing diagram for the control interface is shown in Fig 3.4/4.5.

### 3.4.5 Supply of STAFF magnetic waves to EDI

#### a/ Purpose

On request from EDI, the STAFF experiment will transmit to EDI the 3 components of the magnetic wave forms. They are analog signals in a frequency range up to 4 kHz. The 3 components Bx, By, Bz are aligned with the WEC reference axis Ex, Ey, Ez defined as follows:

Ex is parallel to the S/C axis Xb (spin axis)  
Ey is in the direction of the long boom V3  
Ez is in the direction of the long boom V1

#### c/ Interface circuits

See Fig 3.4/3.



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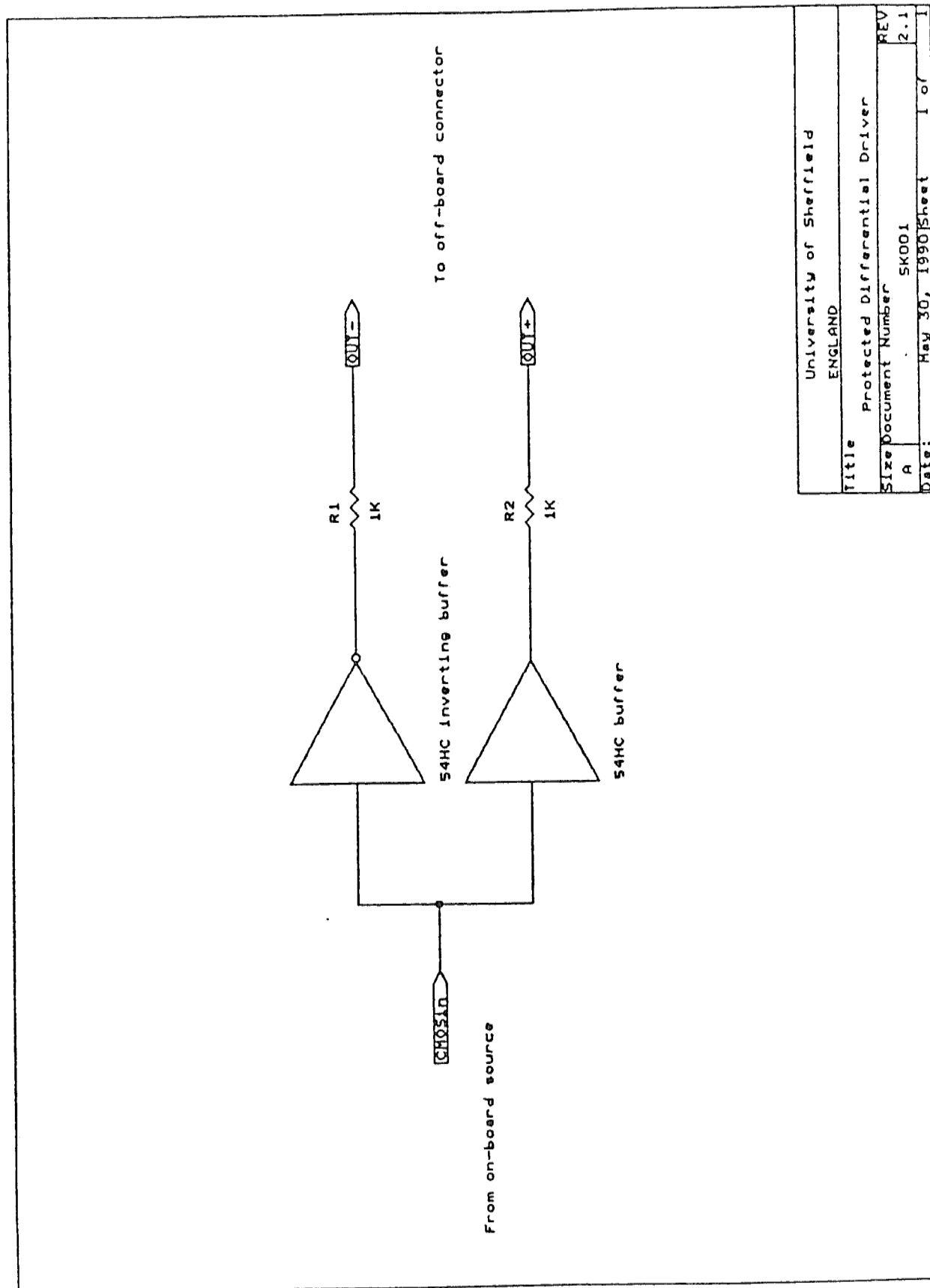
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Fig 3.4/1 Differential driver





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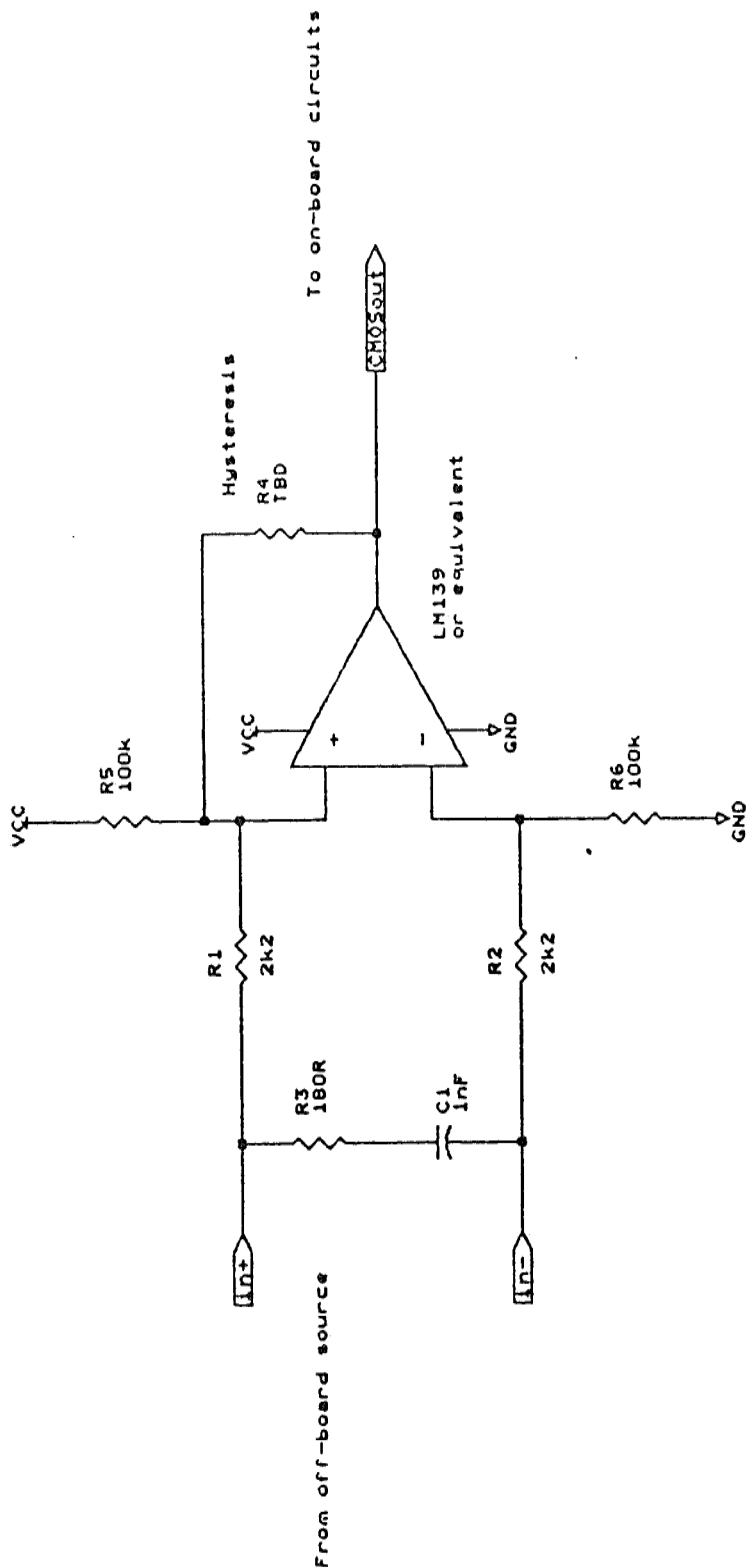
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Fig 3.4/2 Differential receiver



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Differential Receiver circuit (from EID C)

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1 of 1

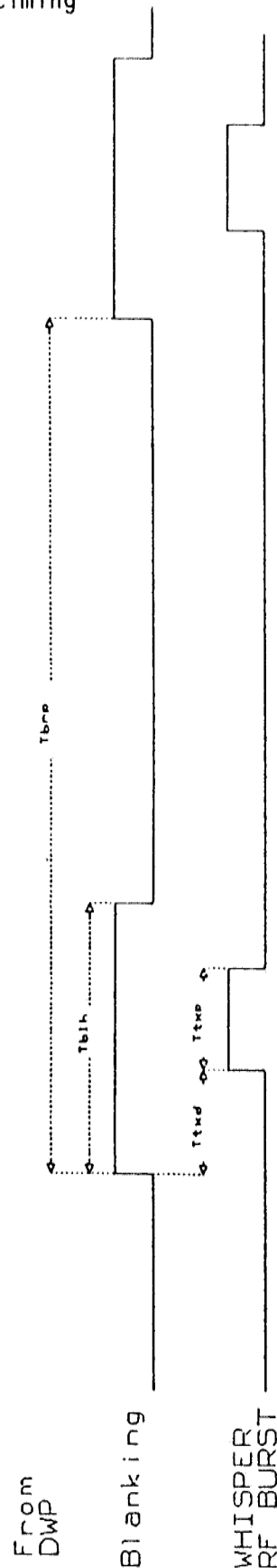


Fig 3.4/4.1 WHISPER Blanking pulse timing

## Distribution of WHISPER Blanking Pulse

### Timing Characteristics

Parameter	Description	min	max
Tbrp	Pulse repetition rate	13.3 ms	
Tblh	Blanking Signal Active	3.33 ms	3.33 ms
Ttxd	Blanking start to Transmission Delay	1.11 ms	1.11 ms
Ttxp	RF Transmission Duration	0.5 ms	1 ms



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WHISPER Blanking Pulse
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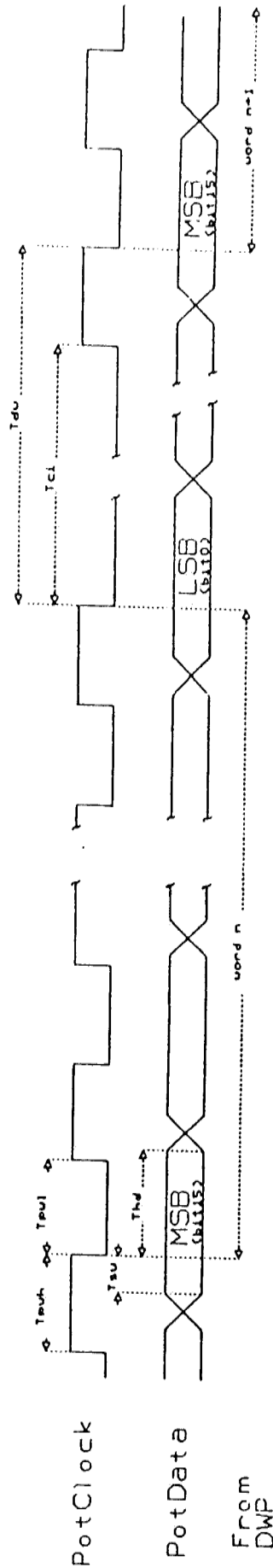


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# Spacecraft Potential and WHISPER synchronisation (16 bit. word)



## Timing Characteristics

Parameter	Description	min	max
Tpwh	Clock high pulse width	1 $\mu$ S	
Tpwl	Clock low pulse width	1 $\mu$ S	
Tsu	Data setup time	1 $\mu$ S	
Thd	Data hold time	1 $\mu$ S	
Tci	Clock inactive period	1 mS	
Tdw	Delay between words	2 mS	

Fig 3.4/4 S/C potential and WHISPER synchronisation

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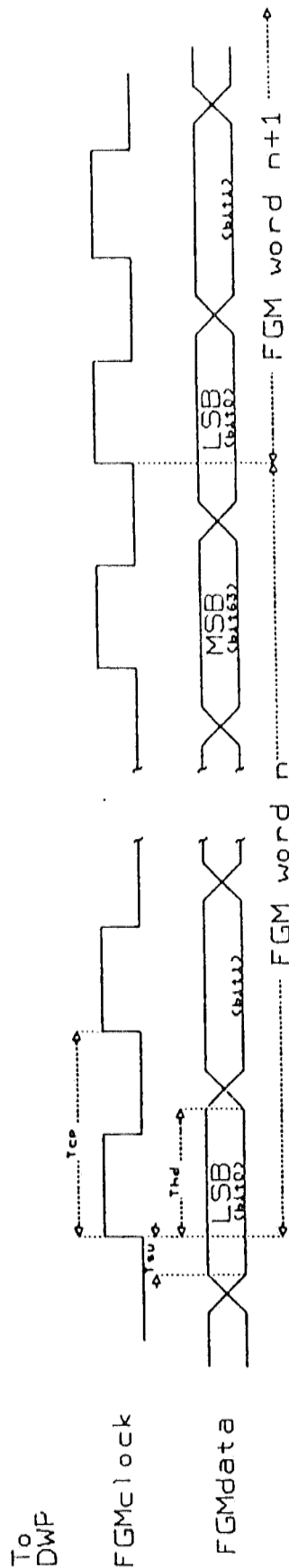
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Fig 3.4/4.3 FGM data exchange

Distribution of FGM Data (64 bit word)

### Timing Characteristics

Parameter	Description	min	max
Tcp	Clock period (1024 Hz)	977 $\mu$ S	977 $\mu$ S
Tsu	Data setup time	30 ns	
Thd	Data hold time	0 ns	



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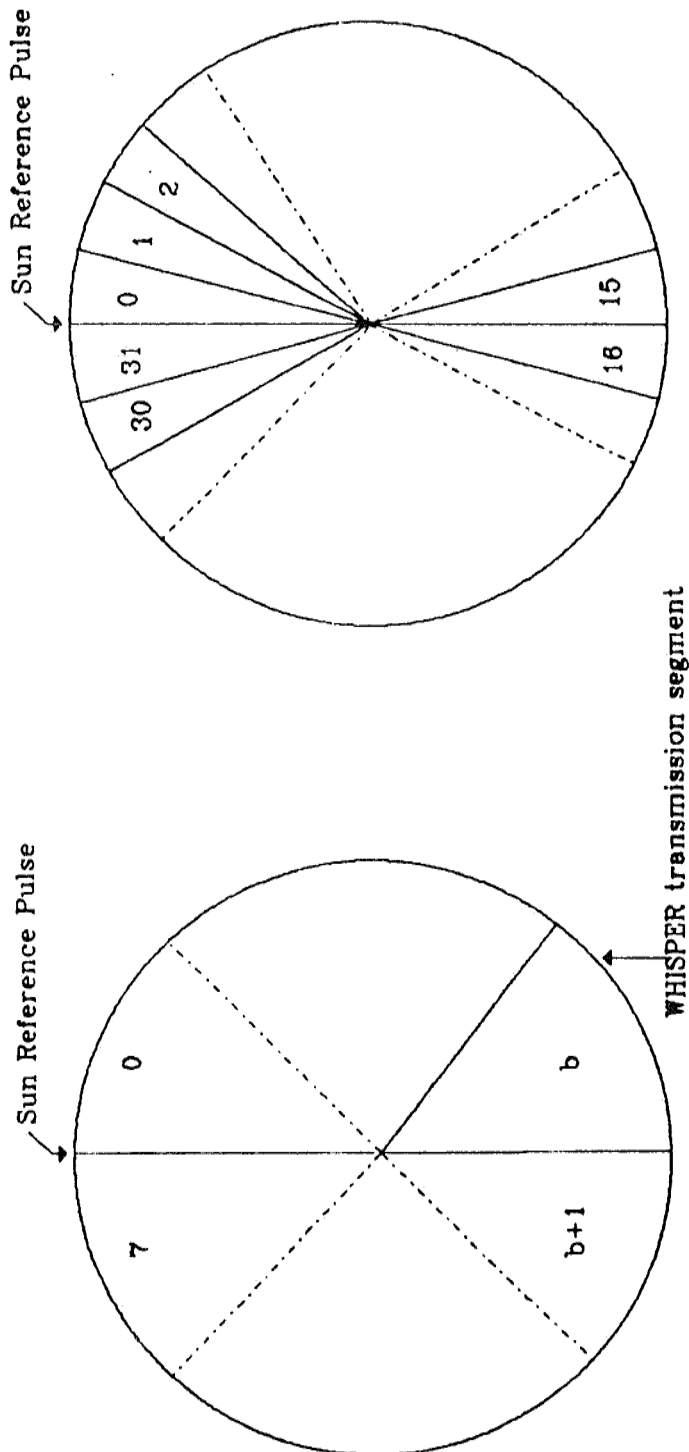


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Fig 3.4/4.4 WHISPER transmission and spin synchronisation



### Gliding Mode

If WHISPER transmits in segment  $b$  on spin  $S$  of the spacecraft, then on the next spin ( $S+1$ ) WHISPER will transmit in segment  $b+1$ .

A spacecraft spin is divided into eight equal segments. Segment 0 is the segment starting at the Sun Reference Pulse.

### Synchronous mode

WHISPER transmissions are synchronised to the voltage flyback period of the electron detection plates. Flyback occurs at the end of a spin segment. Transmissions occur either:

- i/ 16 times per spin (segments 1,3,5, ... , 29,31)
- ii/ 32 times per spin (segments 0,1,2, ... , 30,31)

Drawing TM011 Rev 3.1 Jan 9 1991



### 3.5 CONNECTORS AND HARNESS (TISC)

#### 3.5.1 Interconnecting block diagram

Ref to A4 condensed Fig 3.5/1 and Tab 3.5/3.1.

Drawing A0 detailed Fig 3.5/1 gives a complete definition of the harness.

The harness is classified in several categories:

- Unit harness provided by the relevant experiment
- Experiment harness (experiment mass budget)
- WEC common harness between experiment of the consortium (WEC harness mass budget)

The two last categories will be manufactured by the harness subcontractor. All harness except WEC7c are standard. WEC7c wires will be provided by STAFF for manufacturing by the harness subcontractor.

#### 3.5.2 Interconnecting Harness Characteristics

Tab 3.5/3.1 and 3.5/3.2 give masses and densities relevant to each harness and estimated total mass for each one and the mass of the common wec harness.

#### 3.5.3 Connectors Type

Tab 3.5/1.1 to 5 give the list of the connectors used per unit. All connectors will be non magnetic, class B.

#### 3.5.4 High Voltage Control

WHISPER has a dedicated disable connector for high voltage control.

It will be connected to the high voltage S/C panel control when mounted on the S/C. It is also used as a testing connector for the tests in the laboratory.

#### 3.5.5 Pin Allocation

See Tables 3.5/2.1 to 3.5/2.30.



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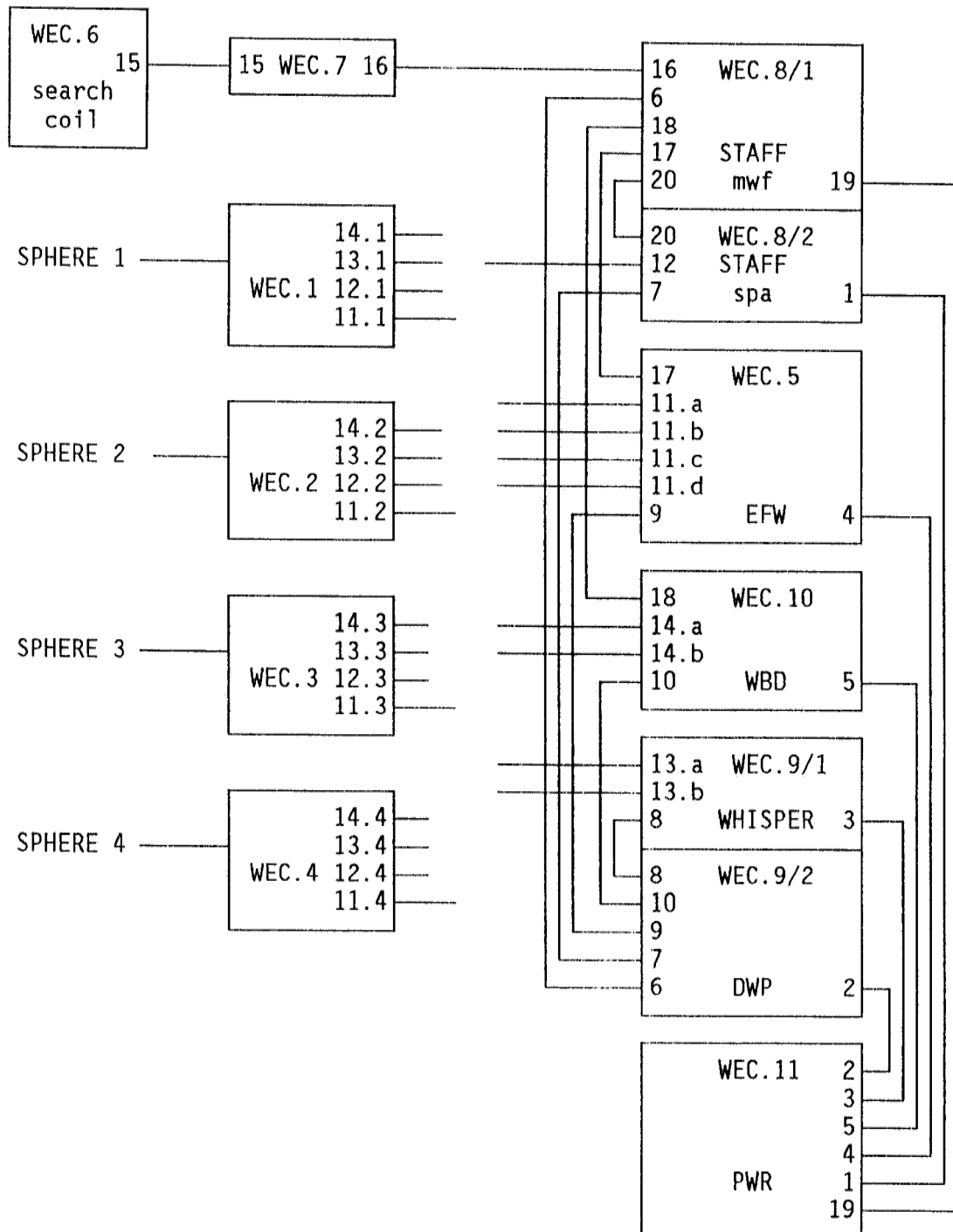


Fig. 3.5/1 WEC internal interconnections diagram



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Nº	from	to	type	function	conn	rem
19	WEC 11	WEC 8/1	4 tp AWG 24	power distr	9+15	
01	WEC 11	WEC 8/2	3 tp AWG 24	power distr	2* 9	
02	WEC 11	WEC 9/2	2 tp AWG 22	power distr	2*25	
			1 tp AWG 24	curr sensor		
			12 s AWG 24	on/off cmd		
03	WEC 11	WEC 9/1	4 tp AWG 24	power distr	2*15	
			1 tsp AWG 22	power distr TX		
04	WEC 11	WEC 5	1 tp AWG 22	power distr	2* 9	
			1 tsp AWG 24	synchro		
05	WEC 11	WEC 10	1 tp AWG 22	power distr	2* 9	
			1 tsp AWG 24	synchro		
06	WEC 8/1	WEC 9/2	37 s AWG 26	data exchange	2*50	
			3 ss AWG 26			
			3 overall shld			
07	WEC 8/2	WEC 9/2	17 s AWG 26	data exchange	2*25	
			1 tsp AWG 26			
			4 ss AWG 24			
			2 overall shld			
08	WEC 9/1	WEC 9/2	32 s AWG 26	data exchange	2*37	***
09	WEC 5	WEC 9/2	12 s AWG 26	data exchange	2*15	
10	WEC 10	WEC 9/2	18 s AWG 26	data exchange	2*25	
11.a	WEC 1	WEC 5	{	analog signals	2*25	*
11.b	WEC 2	WEC 5	{ 4*15 s AWG 26	analog signals	2*25	*
11.c	WEC 3	WEC 5	{ 4* 1 ss AWG 24	analog signals	2*25	*
11.d	WEC 4	WEC 5	{	analog signals	2*25	*
12	WEC 1-4	WEC 8/2	4 ss AWG 24	analog signals	5 *9	
13.a	WEC 1-2	WEC 9/1	2 ss AWG 24	analog signals	1* 9	
13.b	WEC 3-4	WEC 9/1	2 ss AWG 24	WHISP transmit	1* 9	
14.a	WEC 1-2	WEC 10	2 ss AWG 24	analog signals	1*15	
14.b	WEC 3-4	WEC 10	2 ss AWG 24	analog signals	1*15	
15	WEC 6	WEC 7	7 tsp spec cab	analog signals	2*25	**
16	WEC 7	WEC 8/1	3 tsp AWG 26	analog signals	2*25	
			6 s AWG 26			
			1 ss AWG 24	calibration		
17	WEC 8/1	WEC 5	3 tsp AWG 26	analog signals	15+9	
18	WEC 8/1	WEC 10	2 tsp AWG 26	analog signals	2* 9	
20	WEC 8/1	WEC 8/2	10 s AWG 26	analog signals	2*15	***

\* = WEC 5c

\*\* = WEC 7c

\*\*\* = unit harness

Tab 3.5/3.1 - WEC harness description



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H/N Nr	from to	wire g/m	overall shield g/m	conn type	wire length m	wire g	overall shield g	conn g	total common g	unit harn g
19	11 08.1	20.0	10	2*9	0.7	14.00	7.00	36.00	57.00	
1	11 08.2	15.0	10	9*15	1.0	15.00	10.00	44.00	69.00	
2	11 09.2	48.2	12	2*25	0.2	9.64	2.40	66.00	78.04	
3	11 09.1	33.2	10	2*15	0.4	13.28	4.00	52.00	69.28	
4	11 05	15.4	10	2*9	2.7	41.58	27.00	36.00	104.58	
5	11 10	15.4	10	2*9	3.2	49.28	32.00	36.00	117.28	
6	08.1 09.2	79.8	50	2*50	0.7	55.86	35.00	114.00	204.86	
7	08.2 09.2	41.8	30	2*25	1.0	41.80	30.00	66.00	137.80	
8	09.1 09.2	60.8	15	2*37	0.2	12.16	3.00	92.00		107.16
9	05 09.2	22.8	10	2*15	3.1	70.68	31.00	52.00	153.68	
10	10 09.2	34.2	12	2*25	3.4	116.28	40.80	66.00	223.08	
11	1..4 05	35.5	12	8*25	9.8	347.90	117.60	264.00		729.50
12	1..4 08.2	4.7	10	1*15	11.6	54.52	116.00	26.00	196.52	
13	1..4 09.1	4.7	10	2*9	12.4	58.28	124.00	36.00	218.28	
14	1..4 10	12.0	10	2*15 4*15	10.0	120.00	100.00	52.00 104.00	272.00 104.00	
15	06 07	109.0	0	2*25	5.6	610.40	0.00	66.00		676.40
16	07 08.1	43.2	12	2*25	1.2	51.84	14.40	66.00	132.24	
17	08.1 05	23.6	10	15+9	2.6	61.36	26.00	44.00	131.36	
18	08.1 10	13.2	10	2*9	2.7	35.64	27.00	36.00	98.64	
20	08.1 08.2	24.5	10	2*15	0.1	2.45	1.00	52.00		55.45
total					72.60	1760	748	1406	2368	1569

Tab 3.5/3.2 - WEC harness characteristics and mass





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EXP	CONNECTOR ID	TYPE MANUFACTURER	FUNCTION
WEC1/4	J01	tbd DBMA 25p NMB	EFW data link
	J02	tbd DAMA 15s NMB	STAFF, WBD, WHISPER i/f
	J03	Cannon DAMA 15p NMB	override control
	J04	tbd DEMA 9p NMB	pyro i/f
	J05	Cannon DEMA 9p NMB	S/C power i/f
WEC 5	J01	Cannon DEMA 9p NMB	PWR i/f
	J02	Cannon DBMA 25s NMB	wec 1 data link
	J03	Cannon DBMA 25s NMB	wec 2 data link
	J04	Cannon DBMA 25s NMB	wec 3 data link
	J05	Cannon DBMA 25s NMB	wec 4 data link
	J06	Cannon DAMA 15s NMB	DWP data link
	J07	Cannon DEMA 9s NMB	STAFF data link

Table 3.5/1.1 EFW connectors list

EXP	CONNECTOR ID	TYPE MANUFACTURER	FUNCTION
WEC6	J01	tbd DBMA 25s NMB	wec 7 data link
WEC7	J01	Cannon tbd 25s NMB	wec 6 data link
	J02	Cannon tbd 25p NMB	wec 8 i/f
WEC8	J01	Cannon DAMA 15p NMB	PWR i/f
	J02	Cannon DBMA 25s NMB	wec 7 i/f
	J03	Cannon DAMA 15p NMB	unit i/f
	J04	Cannon DEMA 9s NMB	WBD data link
	J05	Cannon DAMA 15s NMB	EFW data link
	J06	Cannon DAMA 15p NMB	EDI data link
	J07	Cannon DDMA 50s NMB	DWP data link
	J08	Cannon DAMA 15s NMB	unit i/f
	J09	Cannon DEMA 9p NMB	PWR i/f
	J10	Cannon DAMA 15s NMB	test
	J11	Cannon DAMA 15p NMB	EFW data link
	J12	Cannon DBMA 25s NMB	DWP data link

Table 3.5/1.2 STAFF connectors list

EXP	CONNECTOR ID	TYPE MANUFACTURER	FUNCTION
WEC9.1	J01	Souriau DAM 15p NMB	PWR i/f
	J02	Souriau DEMA 9s NMB	wec 3 & 4 data link
	J03	Souriau DEMA 9p NMB	wec 1 & 2 data link
	J04	Souriau DCMA 37p NMB	DWP data link
	J05	Souriau DEMA 9s NMB	test and HV control
WEC9.2	J06	Souriau DBMA 25s NMB	OBDH i/f
	J07	Souriau DBMA 25s NMB	OBDH i/f
	J08	Souriau DBMA 25p NMB	PWR i/f
	J09	Souriau DCMA 37p NMB	WHISPER data link
	J10	Souriau DBMA 25s NMB	WBD data link
	J11	Souriau DCMA 37s NMB	IEL i/f
	J12	Souriau DBMA 25p NMB	STAFF data link
	J13	Souriau DDMA 50p NMB	STAFF data link
	J14	Souriau DAMA 15p NMB	EFW data link

Table 3.5/1.3 WEC 9 connectors list



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EXP	CONNECTOR ID	TYPE MANUFACTURER	FUNCTION
WEC10	J01	Cannon DBMA 25p NMB	obdh i/f
	J02	Cannon DAM7W2p	wec 3 & 4 data link
	J03	Cannon DAM7W2s	wec 1 & 2 data link
	J04	Cannon DEMA 9s NMB	STAFF data link
	J05	Cannon DBMA 25s NMB	DWP data link
	J06	Cannon DEMA 9p NMB	PWR i/f

Table 3.5/1.4 WBD connectors list

EXP	CONNECTOR ID	TYPE MANUFACTURER	FUNCTION
WEC11	J01	Souriau DAMA 15p NMB	S/C power i/f
	J02	Souriau DEMA 9s NMB	EFW power i/f
	J03	Souriau DEMA 9s NMB	WBD power i/f
	J04	Souriau DEMA 9s NMB	STAFF power i/f
	J05	Souriau DAMA 15s NMB	WHISPER power i/f
	J06	Souriau DBMA 25s NMB	DWP power i/f
	J07	Souriau DEMA 9s NMB	STAFF power i/f

Table 3.5/1.5 PWR connectors list



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SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT				TARGET
WEC/EFW WEC1,2,3,4					WEC/EFW WEC 5 J02,03,04,05
J01	Signal Designation	EMC Cat	Wire	AWG	mΩ
1	Structure ground		ov	shld	1
2	Sensor signal	2	ss	24	2
3	+ 100 V	2	s	26	3
4	+ 5 V	2	s	26	4
5	- 8 V	2	s	26	5
6	+ 12 V FLT	2	s	26	6
7	- 12 V FLT	2	s	26	7
8	AGND	2	s	26	8
9	BC1	2	s	26	9
10	BOOMENA	2	s	26	10
11	nc				
12	nc				
13	nc				
14	Sensor signal return	2	ss	shld	14
15	nc				
16	+ 8 V	2	s	26	16
17	AGND	2	s	26	17
18	- 100 V	2	s	26	18
19	FLT return	2	s	26	19
20	BIAS/STAT	2	s	26	20
21	BC0	2	s	26	21
22	BC2	2	s	26	22
23	nc				
24	nc				
25	nc				

Table 3.5/2.1 : WEC1,2,3,4 J01 to WEC 5 respectively J02,03,04,05 pin assignment



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SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT					TARGET	
WEC/EFW WEC 1							a WEC 8.2 J11 b WEC 9.1 J03 c WEC 10 J03	
J02	Signal Designation	EMC Cat	Cabl	Wire	AWG	mΩ		
1	Structure ground			ov	shld	15	a	
1	Structure ground			ov	shld	1	b	
1	Structure ground			ov	shld	4	c	
2	nc							
3	nc							
4	+ Ez return	2	2	ss	shld	7	b	
5	nc							
6	+ Ez signal	2	3	ss	24	A1	c	
7	nc							
8	+ Ez return	2	1	ss	shld	6	a	
9	nc							
10	nc							
11	+ Ez signal	2	2	ss	24	6	b	
12	nc							
13	nc							
14	+ Ez return	2	3	ss	shld	A1s	c	
15	+ Ez signal	2	1	ss	24	5	a	

Table 3.5/2.2 : WEC1 J02 to WEC 8.2 J11, WEC 9.1 J03, WEC 10 J03 pin assignment



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SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT						TARGET
WEC/EFW WEC 2							a WEC 8.2 J11 b WEC 9.1 J03 c WEC 10 J03
J02	Signal Designation	EMC Cat	Cabl	Wire	AWG	mΩ	
1	Structure ground			ov	shld	15	a
1	Structure ground			ov	shld	1	b
1	Structure ground			ov	shld	4	c
2	nc						
3	nc						
4	- Ez return	2	2	ss	shld	9	b
5	nc						
6	- Ez signal	2	3	ss	24	A2	c
7	nc						
8	- Ez return	2	1	ss	shld	8	a
9	nc						
10	nc						
11	- Ez signal	2	2	ss	24	8	b
12	nc						
13	nc						
14	- Ez return	2	3	ss	shld	A2s	c
15	- Ez signal	2	1	ss	24	7	a

Table 3.5/2.3 : WEC2 J02 to WEC 8.2 J11, WEC 9.1 J03, WEC 10 J03 pin assignment

SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT					TARGET	
WEC/EFW WEC 3							a WEC 8.2 J11 b WEC 9.1 J02 c WEC 10 J02	
J02	Signal Designation	EMC Cat	Cabl	Wire	AWG	mΩ		
1	Structure ground			ov	shld	15	a	
1	Structure ground			ov	shld	1	b	
1	Structure ground			ov	shld	4	c	
2	WHISPER/TX true. return	2	2	ss	shld	7	b	
3	nc							
4	nc							
5	nc							
6	+ Ey signal	2	3	ss	24	A1	c	
7	nc							
8	+ Ey return	2	1	ss	shld	2	a	
9	WHISPER/TX true. signal	2	2	ss	24	6	b	
10	nc							
11	nc							
12	nc							
13	nc							
14	+ Ey return	2	3	ss	shld	A1s	c	
15	+ Ey signal	2	1	ss	24	1	a	

Table 3.5/2.4 : WEC3 J02 to WEC 8.2 J11, WEC 9.1 J02, WEC 10 J02 pin assignment



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SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT					TARGET	
WEC/EFW WEC 4							a WEC 8.2 J11	
							b WEC 9.1 J02	
							c WEC 10 J02	
J02	Signal Designation		EMC Cat	Cabl	Wire	AWG	mΩ	
1	Structure ground				ov	shld	15	a
1	Structure ground				ov	shld	1	b
1	Structure ground				ov	shld	4	c
2	WHISPER/TX comp.	return	2	2	ss	shld	9	b
3	nc							
4	nc							
5	nc							
6	- Ey	signal	2	3	ss	24	A2	c
7	nc							
8	- Ey	return	2	1	ss	shld	4	a
9	WHISPER/TX comp.	signal	2	2	ss	24	8	b
10	nc							
11	nc							
12	nc							
13	nc							
14	- Ey	return	2	3	ss	shld	A2s	c
15	- Ey	signal	2	1	ss	24	3	a

Table 3.5/2.5 : WEC4 J02 to WEC 8.2 J11, WEC 9.1 J02, WEC 10 J02 pin assignment





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SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT				TARGET
WEC/EFW WEC1,2,3,4					OBDH RTU
J03	Signal Designation	EMC Cat	Wire	AWG	mΩ
1	structure ground				
2	secondary relay off return	2			
3	secondary relay on return	2			
4	secondary relay status signal	2			
5	end of wire & tension signal	2			
6	potentiometre supply	2			
7	potentiometre signal signal	2			
8	nc				
9	secondary relay off signal	2			
10	secondary relay on signal	2			
11	nc				
12	secondary relay status return	2			
13	end of wire & tension return	2			
14	potentiometre return	2			
15	nc				

Table 3.5/2.6 : WEC1,2,3,4 J03 (override) to RTU pin assignment

SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT				TARGET
WEC/EFW WEC1,2,3,4					PYRO PEU
J04	Signal Designation	EMC	cabl	Wire	AWG mΩ
1	EED 1 .FIRE	3	1	tsp tbd	
2	EED 1 .RTN	3	1	tsp tbd	
3	structure gnd				
4	EED 2 .FIRE	3	2	tsp tbd	
5	EED 2 .RTN	3	2	tsp tbd	
6	structure gnd				
7	structure gnd				
8	structure gnd				
9	structure gnd				

Table 3.5/2.7 : WEC1,2,3,4 J04 (pyro) to PEU pin assignment

SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT						TARGET
WEC/EFW WEC1,2,3,4							POWER PDU
J05	Signal Designation	EMC	cabl	Wire	AWG	mΩ	
1	structure gnd						
2	28 V primary relay .SUP	1	1				
3	28 V primary relay .RTN	1	1				
4	28 V secondary relay .SUP	1	3				
5	28 V secondary relay .RTN	1	3				
6	28 V primary relay .SUP	1	2				
7	28 V primary relay .RTN	1	2				
8	28 V secondary relay .SUP	1	4				
9	28 V secondary relay .RTN	1	4				

Table 3.5/2.8 : WEC1,2,3,4 J05 (power) to PDU pin assignment

SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT						TARGET
WEC/EFW WEC 5							WEC/PWR WEC 11
J01	Signal Designation	EMC Cat	Cabl	Wire	AWG	mΩ	J02
1	+ 27 V .SUP	1	1	tp	22		1
2	nc						2
3	nc CSY shld grounded at WEC11	2	2	tsp	shld		3
4	nc						4
5	structure ground			ov	shld		5
6	+ 27 V .RTN	1	1	tp	22		6
7	CSY .TRUE	2	2	tsp	24		7
8	CSY .COMP	2	2	tsp	24		8
9	nc						9

Table 3.5/2.9 : WEC5 J01 to WEC11 J02 pin assignment



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SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT				TARGET	
WEC/EFW WEC 5						WEC/DWP WEC 9.2	
J06	Signal Designation	EMC Cat	Wire	AWG	mΩ	J14	
1	signal ground	2	s	26		1	
2	EFW data	2	s	26		2	
3	Ready-to-send	2	s	26		3	
4	EFW AD clock	2	s	26		4	
5	EFWSampClock	2	s	26		5	
6	Sun Ref Pulse	2	s	26		6	
7	signal ground	2	s	26		7	
8	structure ground	2	ov	shld		8	
9	EFW Command	2	s	26		9	
10	Clear-to-Send	2	s	26		10	
11	signal ground tbc		s	26		11	
12	nc					12	
13	signal ground tbc		s	26		13	
14	nc					14	
15	blanking pulse	2	s	26		15	

Table 3.5/2.10 : WEC5 J06 to WEC9.2 J14 pin assignment



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SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT					TARGET	
WEC/EFW WEC 5							WEC/STAFF WEC 8.1	
J07	Signal Designation	EMC	cabl	Wire	AWG	mΩ	J05	
1	SCX+	2	1	tsp	26		1	
2	nc							
3	SCY-	2	2	tsp	26		4	
4	SCZ+	2	3	tsp	26		5	
5	nc							
6	SCX-	2	1	tsp	26		2	
7	SCY+	2	2	tsp	26		3	
8	nc							
9	SCZ-	2	3	tsp	26		6	
							7	
							8	
							9	
	shld grounded at WEC8.1		1	tsp shld			10	
							11	
	shld grounded at WEC8.1		2	tsp shld			12	
							13	
	shld grounded at WEC8.1		3	tsp shld			14	
	structure ground						15	

Table 3.5/2.11 : WEC5 J07 to WEC8.1 J05 pin assignment

SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT					TARGET	
WEC/STAFF WEC 6							WEC/STAFF WEC 7	
J01	Signal Designation	EMC	Cable	Wire	AWG	mΩ	J01	
1	Bxe return	2	1	tsp	26		1	
2	Bxe shld at signal gnd both end		1	tsp	shld		2	
3	X feed back signal	2	4	tsp	26		3	
4	nc							
5	shld at signal gnd both end		7	tsp	shld		5	
6	Bye signal	2	2	tsp	26		6	
7	Y feed back return	2	5	tsp	26		7	
8	shld at signal gnd both end		5	tsp	shld		8	
9	temp sensor true	2	7	tsp	26		9	
10	Bze return	2	3	tsp	26		10	
11	Bze shld at signal gnd both end		3	tsp	shld		11	
12	Z feed back signal	2	6	tsp	26		12	
13	nc							
14	Bxe signal	2	1	tsp	26		14	
15	X feed back return	2	4	tsp	26		15	
16	shld at signal gnd both end		4	tsp	shld		16	
17	structure ground						17	
18	Bye shld at signal gnd both end		2	tsp	shld		18	
19	Bye return	2	2	tsp	26		19	
20	Y feed back signal	2	5	tsp	26		20	
21	nc							
22	temp sensor comp	2	7	tsp	26		22	
23	Bze signal	2	3	tsp	26		23	
24	Z feed back return	2	6	tsp	26		24	
25	shld at signal gnd both end		6	tsp	shld		25	

Table 3.5/2.12 : WEC6 J01 to WEC7 J01 pin assignment



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SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT					TARGET	
WEC/STAFF WEC 6							WEC/STAFF WEC 7	
J01	Signal Designation		EMC	Cable	Wire	AWG	mΩ	J01
1	Bxe	signal	2	1	tsp	26		1
2	Bxe	shld		1	tsp	shld		2
3	X feed back	return	2	4	tsp	26		3
4	connected to 2							
5	nc	sensor shld grounded at WEC7		7	tsp	shld		5
6	Bye	signal	2	2	tsp	26		6
7	Y feed back	return	2	5	tsp	26		7
8	nc	Y shld grounded at WEC7		5	tsp	shld		8
9	temp sensor	true	2	7	tsp	26		9
10	Bze	signal	2	3	tsp	26		10
11	Bze	shld		3	tsp	shld		11
12	Z feed back	return	2	6	tsp	26		12
13	connected to 11							
14	Bxe	return	2	1	tsp	26		14
15	X feed back	signal	2	4	tsp	26		15
16	nc	X shld grounded at WEC7		4	tsp	shld		16
17	structure ground							17
18	Bye	shld		2	tsp	shld		18
19	Bye	return	2	2	tsp	26		19
20	Y feed back	signal	2	5	tsp	26		20
21	connected to 18							
22	temp sensor	comp	2	7	tsp	26		22
23	Bze	return	2	3	tsp	26		23
24	Z feed back	signal	2	6	tsp	26		24
25	nc	Z shld grounded at WEC7		6	tsp	shld		25

Table 3.5/2.12 : WEC6 J01 to WEC7 J01 pin assignment



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SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT						TARGET
WEC/STAFF WEC 7							WEC/STAFF WEC 8.1
J02	Signal Designation	EMC		Wire	AWG	mΩ	J02
1	Bxe in	2	1	tsp	26		1
2	nc Bxe shld grounded at WEC8.1		1	tsp	shld		2
3	nc						3
4	MagPApwr return	2		s	26		4
5	TempSO	2	g5	s	26		5
6	Temp return	2	g5	s	26		6
7	structure ground			ov	shld		7
8	nc Bye shld grounded at WEC8.1		2	tsp	shld		8
9	Bye return	2	2	tsp	26		9
10	CalSc	2	4	ss	24		10
11	nc Bze shld grounded at WEC8.1		3	tsp	shld		
12	Bze return	2	3	tsp	26		12
13	nc						13
14	Bxe return	2	1	tsp	26		14
15	nc						15
16	-V Mag PA	2		s	26		16
17	+V Mag PA	2		s	26		17
18	Temp S1	2	g5	s	26		18
19	Temp shld grounded at WEC7		g5	ov	shld		
20	nc						20
21	Bye in	2	2	tsp	26		21
22	CalSc return	2	4	ss	shld		22
23	nc						23
24	Bze in	2	3	tsp	26		24
25	nc						25

Table 3.5/2.13 : WEC7 J02 to WEC8.1 J02 pin assignment



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SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT					TARGET	
WEC/STAFF WEC 8.1							WEC/PWR WEC 11	
J01	Signal Designation	EMC Cat		Wire	AWG	mΩ	J04	
1	- 9 V	1	1	tp	24		1	
2	- 5.75 V	1	2	tp	24		2	
3	structure ground							
4	+ 5.75 V	1	3	tp	24		4	
5	+ 9 V	1	4	tp	24		5	
6	- 9 V return	1	1	tp	24		6	
7	- 5.75 V return	1	2	tp	24		7	
8	+ 5.75 V return	1	3	tp	24		8	
9	+ 9 V return	1	4	tp	24		9	
10	nc							
11	nc							
12	nc							
13	nc							
14	nc							
15	nc							

Table 3.5/2.14 : WEC8.1 J01 to WEC11 J04 pin assignment





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SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT				TARGET	
WEC/STAFF WEC 8.1						WEC/STAFF WEC 8.2	
J03	Signal Designation		EMC Cat	Wire	AWG	mΩ	J08
1	Bxe	signal	2	s	26		3
2	Bxe	return	2	s	26		11
3	Bye	signal	2	s	26		1
4	Bye	return					9
5	Bze	signal	2	s	26		2
6	Bze	return					10
7	CAL	signal	2	s	26		5
8	CAL	return	2	s	26		12
9	CAL E	cmd	2	s	26		7
10	signal ground			s	26		13
11	CAL B	cmd	2	s	26		8
12	signal ground			s	26		14
13	nc						
14	nc						
15	structure ground			ov	shld		15

Table 3.5/2.15 : WEC8.1 J03 to WEC8.2 J08 pin assignment  
(unit harness)



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SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT					TARGET	
WEC/STAFF WEC 8.1							WEC/WBD WEC 10	
J04	Signal Designation		EMC	Cable	Wire	AWG	mΩ	J04
1	Bxe	signal	2	1	tsp	26		1
2	Bxe	return	2	1	tsp	26		6
3	Bye	signal	2	2	tsp	26		3
4	Bye	return	2	2	tsp	26		8
5	nc							
6	Bxe	shld grounded at WEC8.1		1	tsp	shld		
7	nc							
8	Bye	shld grounded at WEC8.1		2	tsp	shld		
9	structure ground							9

Table 3.5/2.16 : WEC8.1 J04 to WEC10 J04 pin assignment

SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT					TARGET	
WEC/STAFF WEC 8.1							IEL EDI CONTROLL	
J06	Signal Designation		EMC	Cable	Wire	AWG	mΩ	
1	Bxe	out		1	tsp	26		
2	Bxe	rtn		1	tsp	26		
3	Bye	out		2	tsp	26		
4	Bye	rtn		2	tsp	26		
5	Bze	out		3	tsp	26		
6	Bze	rtn		3	tsp	26		
7	nc							
8	nc							
9	nc							
10	Bxe	shld grounded at WEC8.1		1	tsp	shld		
11	nc							
12	Bye	shld grounded at WEC8.1		2	tsp	shld		
13	nc							
14	Bze	shld grounded at WEC8.1		3	tsp	shld		
15	Structure ground							

Table 3.5/2.17 : WEC8.1 J06 (IEL) to EDI pin assignment

SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT						TARGET
WEC/STAFF WEC 8.1							WEC/DWP WEC 9.2
J07	Signal Designation	EMC Cat	Cabl	Wire	AWG	mΩ	J13
1	Signal ground			s	26		1
2	SCTD1	2	g1	s	26		2
3	SCTD3	2	g1	s	26		3
4	SCTD5	2	g1	s	26		4
5	SCTD7	2	g1	s	26		5
6	SCTD9	2	g1	s	26		6
7	SCTD11	2	g1	s	26		7
8	SCTD13	2	g1	s	26		8
9	SCTD15	2	g1	s	26		9
10	SCCa1op0	2	g2	s	26		10
11	SCCa1Mode0	2	g2	s	26		11
12	SCCa1Mode2	2	g2	s	26		12
13	SCCa1Level1	2	g2	s	26		13
14	SCBWcmd	2	g2	s	26		14
15	SCSaH	2	4	ss	26		15
16	SCBcmd1	2	g2	s	26		16
17	Shld grounded at WEC8.1		g2	"s" shld			17
17	Shld grounded at WEC8.1		4, 5	ss shld			17
18	TempSense1	2	g3	s	26		18
19	Shld grounded at WEC8.1		g1	"s" shld			19
19	Shld grounded at WEC8.1		g3	"s" shld			19
19	Shield ground at WEC8.1		6	ss shld			19
20	SCTD0	2	g1	s	26		20
21	SCTD2	2	g1	s	26		21
22	SCTD4	2	g1	s	26		22
23	SCTD6	2	g1	s	26		23
24	SCTD8	2	g1	s	26		24
25	SCTD10	2	g1	s	26		25
26	SCTD12	2	g1	s	26		26
27	SCTD14	2	g1	s	26		27
28	SCRESET	2	g2	s	26		28
29	SCCa1op1	2	g2	s	26		29
30	SCCa1Mode1	2	g2	s	26		30
31	SCCLeve10	2	g2	s	26		31
32	SCCa1level2	2	g2	s	26		32
33	SCEOT	2	5	ss	26		33
34	SCBcmd0	2	g2	s	26		34
35	SCSOC	2	6	ss	26		35
36	TempSense0	2	g3	s	26		36
37	TempReturn	2	g3	s	26		37
38	nc						38
39	Volt monitoring V0	2		s	26		39
40	Volt " V1	2		s	26		40
41	Volt " V2	2		s	26		41
42	Volt " V3	2		s	26		42
43	nc						43
44	signal ground			s	26		44
45/49	nc						45/49
50	structure ground			ov shld.			50

Table 3.5/2.18 : WEC8.1 J07 to WEC9.2 J13 pin assignment



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SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT						TARGET	
WEC/STAFF WEC 8.2								WEC/PWR WEC 11	
J09	Signal Designation					EMC Cat	Cabl	Wire	AWG mΩ J07
1	+ 6	V				1	1	tp	24 5
2	- 6	V				1	2	tp	24 1
3	nc								
4	+ 5.25	V				1	3	tp	24 4
5	nc								
6	+ 6	V	return			1	1	tp	24 9
7	- 6	V	return			1	2	tp	24 6
8	+ 5.25	V	return			1	3	tp	24 8
9	structure	ground							3

Table 3.5/2.19 : WEC8.2 J09 to WEC11 J07 pin assignment



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SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT					TARGET
WEC/STAFF WEC 8.2							WEC/DWP WEC 9.2
J12	Signal Designation	EMC Cat	Cabl	Wire	AWG	mΩ	J12
1	Structure ground			ov	shld		1
2	SATD1	2	g1	s	26		2
3	SATD3	2	g1	s	26		3
4	SATD5	2	g1	s	26		4
5	SATD7	2	g1	s	26		5
6	- 6V monitor	2		s	26		6
7	Signal ground			s	26		7
8	TempReturn	2	7	tsp	26		8
9	Signal ground			s	26		9
	nc shld grounded at WEC 9.2		7	tsp	shld		9
	nc shld grounded at WEC 9.2		4/6	ss	shld		9
	nc shld grounded at WEC 9.2		g2	"s"	shld		9
10	SAAck	2	g2	s	26		10
11	SAmData	2	6	ss	24		11
12	SAReset	2	g2	s	26		12
13	SASunpulse	2	g2	s	26		13
14	SATD0	2	g1	s	26		14
15	SATD2	2	g1	s	26		15
16	SATD4	2	g1	s	26		16
17	SATD6	2	g1	s	26		17
18	+ 6V monitor	2		s	26		18
19	+ 5V monitor	2		s	26		19
20	Tempsense4	2	7	tsp	26		20
21	shld grounded at WEC 8.2		3	ss	shld		
21	shld grounded at WEC 8.2		g1	"s"	shld		
22	SAStrobe	2	3	ss	24		22
23	SACmdClock	2	4	ss	24		23
24	SACStrobe	2	5	ss	24		24
25	SASpinRef	2	g2	s	26		25

Table 3.5/2.20 : WEC8.2 J12 to WEC9.2 J12 pin assignment



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SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT						TARGET
WEC/WHISPER WEC 9.1							WEC/PWR WEC 11
J01	Signal Designation	EMC Cat	Cabl	Wire	AWG	mΩ	J05
1	- 6 V	1	1	tp	24		1
2	+ 8 V	1	2	tp	24		2
3	nc						3
4	+ 27 V	1	5	tsp	22		4
5	nc + 27 V shld grounded at WEC11	1	5	tsp shld			5
6	nc						6
7	+ 5.5 V	1	3	tp	24		7
8	+ 6 V	1	4	tp	24		8
9	- 6 V return	1	1	tp	24		9
10	+ 8 V return	1	2	tp	24		10
11	nc						11
12	+ 27 V return	1	5	tsp	22		12
13	structure ground						13
14	+ 5.5 V return	1	3	tp	24		14
15	+ 6 V return	1	4	tp	24		15

Table 3.5/2.21 : WEC9.1 J01 to WEC11 J05 pin assignment

SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT					TARGET
WEC/WHISPER WEC 9.1						WEC/DWP WEC 9.2
J04	Signal Designation	EMC Cat	Wire	AWG	mΩ	J09
1	Signal ground		s	26		1
2	WHTD1	2	s	26		2
3	WHTD3	2	s	26		3
4	WHTD5	2	s	26		4
5	WHTD7	2	s	26		5
6	WHTD9	2	s	26		6
7	WHTD11	2	s	26		7
8	WHTD13	2	s	26		8
9	WHTD15	2	s	26		9
10	WHFrameReady	2	s	26		10
11	WHT1mRead	2	s	26		11
12	WHCmdClock	2	s	26		12
13	WHCmdStrobe	2	s	26		13
14	WHReset	2	s	26		14
15	nc					15
16	WHSampleSync	2	s	26		16
17	TempSense3	2	s	26		17
18	nc					18
19	structure ground		ov	shld		19
20	WHTD0	2	s	26		20
21	WHTD2	2	s	26		21
22	WHTD4	2	s	26		22
23	WHTD6	2	s	26		23
24	WHTD8	2	s	26		24
25	WHTD10	2	s	26		25
26	WHTD12	2	s	26		26
27	WHTD14	2	s	26		27
28	Signal ground		s	26		28
29	WHRstCntr	2	s	26		29
30	nc					30
31	WHCmData	2	s	26		31
32	Signal ground		s	26		32
33	WHA1arm	2	s	26		33
34	WHblankP	2	s	26		34
35	Signal ground		s	26		35
36	TempReturn	2	s	26		36
37	nc					37

Table 3.5/2.22 : WEC9.1 J04 to WEC9.2 J09 pin assignment  
(unit harness)



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SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT				TARGET
WEC/WHISPER WEC 9.1					HV panel
J05	Signal Designation	EMC Cat	Wire	AWG	mΩ
1	HVCRTN				
* 2	WDPG/TXD				
* 3	RXD				
4	nc				
5	HVC				
6	nc				
* 7	Ground				
8	nc				
9	nc				

Table 3.5/2.23 : WEC9.1 J05 to HV control panel pin assignment

Pins with \* are for WHISPER offline only





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SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT						TARGET
WEC/DWP WEC 9.2 J06							OBDH RTU
J07	Signal Designation	EMC Cat	Cabl	Wire	AWG	mΩ	
1	Science sampling TRUE		1	tsp	26		
2	House keeping sampling TRUE		2	tsp	26		
3	Serial telemetry data TRUE		3	tsp	26		
4	Signal ground		3	tsp	shld		
5	Transfer clock TRUE		4	tsp	26		
6	Memory load sampling TRUE		5	tsp	26		
7	Memory load data TRUE		6	tsp	26		
8	nc						
9	Reset pulse TRUE		7	tsp	26		
10	Spin segment clock TRUE		8	tsp	26		
11	Sun reference pulse TRUE		9	tsp	26		
12	Signal ground						
13	Structure ground						
14	Science sampling COMP		1	tsp	26		
15	House keeping sampling COMP		2	tsp	26		
16	Telemetry data COMP		3	tsp	26		
17	nc						
18	Transfer clock COMP		4	tsp	26		
19	Memory load sampling COMP		5	tsp	26		
20	Memory load data COMP		6	tsp	26		
21	nc						
22	Reset pulse COMP		7	tsp	26		
23	Spin segment clock COMP		8	tsp	26		
24	Sun reference pulse COMP		9	tsp	26		
25	Signal ground						

Table 3.5/2.24 : WEC9.2 J06 & J07 to RTU pin assignment



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SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT					TARGET	
WEC/DWP WEC 9.2							WEC/PWR WEC 11	
J08	Signal Designation	EMC Cat	Cabl	Wire	AWG	mΩ	J06	
1	nc						1	
2	EFW - off	2		s	24		2	
3	STAFF/wf - off	2		s	24		3	
4	STAFF/sa - off	2		s	24		4	
5	WHISPER - off	2		s	24		5	
6	WHISPER/TX - off	2		s	24		6	
7	WBD - off	2		s	24		7	
8	- current sensor	2	3	tp	24		8	
9	nc						9	
10	nc						10	
11	+ 5.65 V1 DWP return	1	1	tp	22		11	
12	+ 5.65 V2 DWP return	1	2	tp	22		12	
13	structure ground			ov	shld		13	
14	EFW - on	2		s	24		14	
15	STAFF/wf - on	2		s	24		15	
16	STAFF/sa - on	2		s	24		16	
17	WHISPER - on	2		s	24		17	
18	WHISPER/TX - on	2		s	24		18	
19	WBD - on	2		s	24		19	
20	+ current sensor	2	3	tp	24		20	
21	nc						21	
22	nc						22	
23	+ 5.65 V1 DWP	1	1	tp	22		23	
24	+ 5.65 V2 DWP	1	2	tp	22		24	
25	nc						25	

Table 3.5/2.25 : WEC9.2 J08 to WEC11 J06 pin assignment



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SOURCE		HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT				TARGET	
WEC/DWP WEC 9.2						WEC/WBD WEC 10	
J10	Signal Designation	EMC Cat	Wire	AWG	mΩ	J05	
1	Signal ground		s	26		1	
2	WBDStsData	2	s	26		2	
3	nc					3	
4	WBDTlmdata	2	s	26		4	
5	nc					5	
6	WBDCmdData	2	s	26		6	
7	Signal ground		s	26		7	
8	nc					8	
9	nc					9	
10	TempReturn	2	s	26		10	
11	WBDPurSens	2	s	26		11	
12	WBDSyncBlank	2	s	26		12	
13	structure ground		ov	shld		13	
14	WBDStsStrobe	2	s	26		14	
15	WBDStsClock	2	s	26		15	
16	WBDTlmStrobe	2	s	26		16	
17	WBDTlmClock	2	s	26		17	
18	WBDCmdClock	2	s	26		18	
19	WBDCmdStrobe	2	s	26		19	
20	WBDReset	2	s	26		20	
21	WBDGainUpdate	2	s	26		21	
22	TempSense2	2	s	26		22	
23	nc					23	
24	Signal ground		s	26		24	
25	nc					25	

Table 3.5/2.26 : WEC9.2 J10 to WEC10 J05 pin assignment



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SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT					TARGET
WEC/DWP WEC 9.2						IEL a ASPOC b CIS c EDI d FGM e PEACE
J11	Signal Designation	EMC Cat	Cab1	Wire	AWG	mΩ
1	Structure ground					
2	EFW & WHISP data SPdataASP-		1	tsp	26	a
3	Clock shld grounded at WEC9.2		2	tsp	shld	(a)
4	EFW & WHISP clock SPclkASP-		2	tsp	26	a
5	nc					
6	EFW & WHISP data SPdataCIS-		3	tsp	26	b
7	Clock shld grounded at WEC9.2		4	tsp	shld	(b)
8	EFW & WHISP clock SPclkCIS-		4	tsp	26	b
9	Signal shld grounded at WEC9.2		5	tsp	shld	(c)
10	Whisp blanking pulse EDIbp-		5	tsp	26	c
11	nc					
12	PEACE data PCdata-		6	tsp	26	e
13	Clock shld grounded at WEC9.2		7	tsp	shld	(e)
14	PEACE clock PCclock-		7	tsp	26	e
15	Plate pulses PCpulses-		8	tsp	26	e
16	nc					
17	FGM data FGMdata-		9	tsp	26	d
18	nc					
19	FGM clock FGMclock-		10	tsp	26	d
20	EFW & WHISP data SPdataASP+		1	tsp	26	a
21	Data shld grounded at WEC9.2		1	tsp	shld	(a)
22	EFW & WHISP clock SPclkASP+		2	tsp	26	a
23	nc					
24	EFW & WHISP data SPdataCIS+		3	tsp	26	b
25	Data shld grounded at WEC9.2		3	tsp	shld	(b)
26	EFW & WHISP clock SPclkCIS+		4	tsp	26	b
27	nc					
28	Whisp blanking pulse EDIbp+		5	tsp	26	c
29	nc					
30	PEACE data PCdata+		6	tsp	26	e
31	Data shld grounded at WEC 9.2		6	tsp	shld	(e)
32	PEACE clock PCclock+		7	tsp	26	e
33	Plate pulses PCpulses+		8	tsp	26	e
34	nc					
35	FGM data FGMdata+		9	tsp	26	d
36	nc					
37	FGM clock FGMclock+		10	tsp	26	d

Table 3.5/2.27 : WEC9.2 J11 to IEL destination pin assignment



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SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT						TARGET
WEC/WBD WEC 10							OBDH RTU
J01	Signal Designation	EMC	Cabl	Wire	AWG	mΩ	
1	nc						
2	VCO reset B +	2	2	tsp	26		
3	VCO reset B shld		2	tsp	shld		
4	VCO reset A -	2	1	tsp	26		
5	high rate clock B + in	2	4	tsp	26		
6	high rate clock B shld		4	tsp	shld		
7	high rate clock A - in	2	3	tsp	26		
8	high rate data B +	2	6	tsp	26		
9	high rate data B shld		6	tsp	shld		
10	high rate data A - out	2	5	tsp	26		
11	signal ground						
12	nc						
13	structure ground						
14	overall shld						
15	VCO reset B -	2	2	tsp	26		
16	VCO reset A +	2	1	tsp	26		
17	VCO reset A shld		1	tsp	shld		
18	high rate clock B -	2	4	tsp	26		
19	high rate clock A +	2	3	tsp	26		
20	high rate clock A shld		3	tsp	shld		
21	high rate data B -	2	6	tsp	26		
22	high rate data A +	2	5	tsp	26		
23	high rate data A shld		5	tsp	26		
24	signal ground						
25	nc						

Table 3.5/2.28 : WEC10 J01 to RTU pin assignment



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SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT						TARGET
WEC/WBD WEC 10							WEC/PWR WEC 11
J06	Signal Designation	EMC Cat	Cabl	Wire	AWG	mΩ	J03
1	+ 27 V	1	1	tp	22		1
2	nc						2
3	nc CSY shld grounded at WEC11		2	tsp shld			3
4	nc						4
5	structure ground						5
6	+ 27 V return	1	1	tp	22		6
7	CSY TRUE.	2	2	tsp	24		7
8	CSY COMP.	2	2	tsp	24		8
9	nc						9

Table 3.5/2.29 : WEC10 J06 to WEC11 J03 pin assignment

SOURCE	HARNESS WIRING AND CONNECTOR PIN ASSIGNMENT						TARGET
WEC/PWR WEC 11							POWER PDU
J01	Signal Designation	EMC Cat	Cabl	Wire	AWG	mΩ	
1	+ 28 V A .SUP	1	1	tp			
2	nc						
3	structure ground						
4	nc						
5	nc CSY shld grounded at PDU		3	tsp	26		
6	nc						
7	nc						
8	+ 28 V B .SUP	1	2	tp			
9	+ 28 V A .RTN	1	1	tp			
10	nc						
11	nc						
12	CSY .TRUE	2	3	tsp	26		
13	CSY .COMP	2	3	tsp	26		
14	nc						
15	+ 28 V B .RTN	1	2	tp			

Table 3.5/2.30 : WEC11 J01 to PDU pin assignment



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Fig 3.5/2

HV Disable Schematic

TBD