

#231

OSO-5

SOLAR E.,U.,V. RADIATION

69-006A-08A

28 tapes

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1. INTRODUCTION:

The documentation for this data set was originally on paper, kept in NSSDC's Data Set Catalogs (DSCs). The paper documentation in the Data Set Catalogs have been made into digital images, and then collected into a single PDF file for each Data Set Catalog. The inventory information in these DSCs is current as of July 1, 2004. This inventory information is now no longer maintained in the DSCs, but is now managed in the inventory part of the NSSDC information system. The information existing in the DSCs is now not needed for locating the data files, but we did not remove that inventory information.

The offline tape datasets have now been migrated from the original magnetic tape to Archival Information Packages (AIP's).

A prior restoration may have been done on data sets, if a requestor of this data set has questions; they should send an inquiry to the request office to see if additional information exists.

2. ERRATA/CHANGE LOG:

NOTE: Changes are made in a text box, and will show up that way when displayed on screen with a PDF reader.

When printing, special settings may be required to make the text box appear on the printed output.

Version	Date	Person	Page	Description of Change
01				
02				

3 LINKS TO RELEVANT INFORMATION IN THE ONLINE NSSDC
INFORMATION SYSTEM:

<http://nssdc.gsfc.nasa.gov/nmc/>

[NOTE: This link will take you to the main page of the NSSDC Master Catalog. There you will be able to perform searches to find additional information]

4. CATALOG MATERIALS:

- a. Associated Documents To find associated documents you will need to know the document ID number and then click here.
<http://nssdcftp.gsfc.nasa.gov/miscellaneous/documents/>

- b. Core Catalog Materials

REDUCED, MERGED 3-CH.UV DATA

69-006A-08A

This data set has been restored. There were originally 28 7-track, 556 BPI tapes written in Binary. There are four restored tapes. The DR tapes are 3480 cartridges and the DS tapes are 9-track, 6250 BPI. The original tapes were created on a 6400 computer. The DR and DS numbers along with the corresponding D numbers are as follows:

DR#	DS#	D#	FILES	TIME SPAN
-----	-----	-----	-----	-----
DR004190	DS004190	D012182	1 - 16	02/05/69 - 02/19/69
		D012183	17 - 98	03/03/69 - 03/28/69
		D012184	99 - 185	04/05/69 - 05/01/69
		D012185	186 - 271	05/06/69 - 06/04/69
		D012186	272 - 403	06/04/69 - 07/07/69
		D012187	404 - 487	07/08/69 - 08/05/69
		D012188	485 - 554	08/16/69 - 09/10/69
		D012189	555 - 631	09/11/69 - 10/14/69
		D012190	632 - 712	10/15/69 - 11/16/69
		D012191	713 - 784	11/17/69 - 12/13/69
DR004191	DS004191	D012192	1 - 92	12/26/69 - 01/22/70
		D012193	93 - 208	01/23/70 - 02/23/70
		D012194	209 - 293	02/24/70 - 03/28/70
		D012195	294 - 370	03/29/70 - 04/24/70
		D012196	371 - 483	05/02/70 - 06/03/70
		D012197	484 - 569	06/04/70 - 06/30/70
DR004192	DS004192	D012198	1 - 105	07/06/70 - 08/02/70
		D012199	106 - 231	08/09/70 - 09/10/70
		D012200	232 - 342	09/11/70 - 10/13/70
		D012201	343 - 469	10/14/70 - 11/16/70
		D012202	470 - 584	11/17/70 - 12/19/70
		D012203	585 - 695	12/19/70 - 01/21/71
DR004193	DS004193	D012204	1 - 104	01/28/71 - 02/22/71
		D012205	105 - 224	02/24/71 - 03/28/71
		D012206	225 - 312	03/29/71 - 04/30/71
		D012207	313 - 424	04/30/71 - 06/01/71
		D012208	425 - 514	06/03/71 - 07/05/71
		D012209	515 - 559	07/06/71 - 07/19/71

OSO-5

69-006A-08A

SOLAR E.U.V. RADIATION

This data set consists of 28 merged Solar E.U.V. Radiation data tapes. These tapes were created on a CDC 6400 Computer at 556 BPI, Binary, 7-track.

All the tapes are multi-filed with one orbit of data per file. Each file begins with one label record of 50 CDC 60-bit words followed by variable length data records. Each data record (one minute of data) contains one attitude/orbit record and a variable number of IPAGE (spacecraft data) records.

The time spans for the tapes are as follows:

<u>D#</u>	<u>C#</u>	<u>TIME SPAN</u>	<u>ORBITS</u>
D-12182	C-09444	2/05/69 - 2/19/69	203- 426
D-12183	C-09445	3/03/69 - 3/28/69	612- 971
D-12184	C-09446	4/05/69 - 5/01/69	1105-1492
D-12185	C-09447	5/06/69 - 6/04/69	1556-1995
D-12186	C-09448	6/04/69 - 7/07/69	2007-2497
D-12187	C-09449	7/08/69 - 8/05/69	2510-2941
D-12188	C-09450	8/16/69 - 9/10/69	3100-3487
D-12189	C-09451	9/11/69 - 10/14/69	3500-3989
D-12190	C-09452	10/15/69 - 11/16/69	4004-4494
D-12191	C-09453	11/17/69 - 12/13/69	4505-4902
D-12192	C-09454	12/26/69 - 1/22/70	5100-5498
D-12193	C-09455	1/23/70 - 2/23/70	5512-5987
D-12194	C-09456	2/24/70 - 3/28/70	6000-6490
D-12195	C-09457	3/29/70 - 4/24/70	6502-6891
D-12196	C-09458	5/02/70 - 6/03/70	700-7497

<u>D#</u>	<u>C#</u>	<u>TIME SPAN</u>	<u>ORBITS</u>
D-12197	C-09459	6/04/70 - 6/30/70	7512-7796
D-12198	C-09460	7/06/70 - 8/02/70	8000-8398
D-12199	C-09461	8/09/70 - 9/10/70	8500-8992
D-12200	C-09462	9/11/70 - 10/13/70	9005-9492
D-12201	C-09463	10/14/70 - 11/16/70	9506-9998
D-12202	C-09464	11/17/70 - 12/19/70	10011-10499
D-12203	C-09465	12/19/70 - 1/21/71	10500-10990
D-12204	C-09466	1/28/71 - 2/22/71	11109-11452
D-12205	C-09467	2/24/71 - 3/28/71	11506-11998
D-12206	C-09468	3/29/71 - 4/30/71	12005-12500
D-12207	C-09469	4/30/71 - 6/01/71	12500-12989
D-12208	C-09470	6/03/71 - 7/05/71	13003-13495
D-12209	C-09471	7/06/71 - 7/19/71	13508-13700

LABEL RECORD FORMAT

69-006A-08A

There is one label record at the beginning of each file of data on these tapes. The format for this record is as follows.

<u>WORD</u>	<u>DESCRIPTION</u>	<u>FORMAT</u>
1	Satellite ID	I5
2	Begin orbit number	I6
3	End orbit number	I6
4	Begin year	I2
5	End year	I2
6	Begin day of year	I3
7	End day of year	I3
8	Begin seconds of day	I5
9	End seconds of day	I5
10	No. of 1-min records in file	I3
11	Pitch (Radians)	F7.4
12	Spin (Rev/sec)	E10.3
13	1st calibration value-CH1	I8
14	1st calibration value-CH2	I8
15	1st calibration value-CH3	I8
16	2nd calibration value-CH1	I8
17	2nd calibration value-CH2	I8
18	2nd calibration value-CH3	I8
19	Time (ms) for 1st calibration	I8
20	Record number - 1st calibration	I3
21	Line number - 1st calibration	I2
22	Time (ms) - 2nd calibration	I8
23	Record number - 2nd calibration	I3
24	Line number - 2nd calibration	I2
25	Time (ms) - 3rd calibration	I8

<u>WORD</u>	<u>DESCRIPTION</u>	<u>FORMAT</u>
26	Record number - 3rd calibration	I3
27	Line number - 3rd calibration	I2
28	Time (ms) - 4th calibration	I8
29	Record number - 4th calibration	I3
30	Line number - 4th calibration	I2
31	Time (ms) - 5th calibration	I8
32	Record number - 5th calibration	I3
33	Line number - 5th calibration	I2
34	Midday count, CH1	I8
35	Midday count, CH2	I8
36	Midday count, CH3	I8
37	Total counts, CH1	I10
38	Total counts, CH2	I10
39	Total counts, CH3	I10
40	Number of calibrations in file	I3
41	Exposure time (seconds)	I10
42-50	Unused	

Midday counts (words 34-36) are measured at 13 minutes after sunrise.

DATA RECORD

FORMAT

69-006A-08A

Each data record contains both orbit/attitude and IPAGE data, there is one orbit/attitude record per physical record. The number of IPAGE records in each physical record is found in word 2 of each physical record.

The formats for these records are:

<u>Word</u>	<u>Description</u>	<u>Format</u>
1	Number of words in IPAGE array	I3
2	Number of IPAGE records in this physical rec.	I3
3	Day count	F
4	Milliseconds of day	F
5	Sat. position vector, X-component (km)	F
6	Sat. position vector, Y-component (km)	F
7	Sat. position vector, Z-component (km)	F
8	Right ascension of Sat. pos. vector (degrees)	F
9	Declination of Sat. pos. vector (degrees)	F
10	Velocity vector, X-component (km/sec)	F
11	Velocity vector, Y-component (km/sec)	F
12	Velocity vector, Z-component (km/sec)	F
13	R.A. of velocity vector (degrees)	F
14	Declination of velocity vector (degrees)	F
15	Geodetic latitude (degrees)	F
16	Geodetic longitude (degrees)	F
17	Geodetic altitude (degrees)	F
18	Unit solar vector, X-component	F
19	Unit solar vector, Y-component	F
20	Unit solar vector, Z-component	F

<u>Word</u>	<u>Description</u>	<u>Format</u>
21	R.A. of unit solar vector (degrees)	F
22	Declination of unit solar vector (degrees)	F
23	MC Illwains "L" parameter (Earth radii)	F
24	Magnetic fields length (Gauss)	F
25	Unit magnetic vector, X-component	F
26	Unit magnetic vector, Y-component	F
27	Unit magnetic vector, Z-component	F
28	R.A. of magnetic vector (degrees)	F
29	Declination of magnetic vector (degrees)	F
30	Pitch angle (Radians)	F
31	Roll angle (Radians)	F
32	Aspect angle (Radians)	F
33	ΔT since digital subcom word 1 (ms)	F
34	Roll-axis orientation, X-component	F
35	Roll-axis orientation, Y-component	F
36	Roll-axis orientation, Z-component	F
37	R.A. of roll-axis (degrees)	F
38	Declination of roll-axis (degrees)	F
39	Pitch-axis orientation, X-component	F
40	Pitch-axis orientation, Y-component	F
41	Pitch-axis orientation, Z-component	F
42	R.A. of pitch-axis (degrees)	F
43	Declination of pitch-axis (degrees)	F
44	Yaw/spin-axis orientation, X-component	F
45	Yaw/spin-axis orientation, Y-component	F
46	Yaw/spin-axis orientation, Z-component	F
47	R.A. of Yaw/spin-axis (degrees)	F
48	Declination of Yaw/spin-axis (degrees)	F
49	Aspect/ref.-axis orientation, X-compon	F

<u>Word</u>	<u>Description</u>	<u>Format</u>
50	Aspect/ref.-axis orientation, Y-component	F
51	Aspect/ref.-axis orientation, Z-component	F
52	R.A. of aspect/ref.-axis (degrees)	F
53	Declination of aspect/ref.-axis (degrees)	F
54	Spin rate (Rev./sec.)	F
55	Data type indicator (1.0=even min. data)	F
56	Orbit number	F
57	Orbit begin (Day count)	F
58	Orbit begin (milliseconds of day)	F
59	Orbit end (Day count)	F
60	Orbit end (milliseconds of day)	F
61	Day/night indicator (Geometric) 1.0=day; 0.0=night	F
62	Sunlight exit (Geometric) (Day count)	F
63	Sunlight exit (Geometric) (ms of day)	F
64	Sunlight entrance (Geometric) (Day count)	F
65	Sunlight entrance (Geometric) (ms of day)	F
66	Unused	
67	Unused	

The IPAGE record consists of 15 items of data packed into 7-60 bit words.

<u>Item</u>	<u>Description</u>	<u>Format</u>
1	Time	I10
2	Code	I5
3	Sensor 1	I8
4	Sensor 2	I8
5	Sensor 3	I8
6	Background 1	I5
7	Background 2	I5
8	Background 3	I5

<u>Word</u>	<u>Description</u>	<u>Format</u>
9	Error Word	02
10	Digital data	08
11	Digital data	08
12	Digital data	08
13	Wheel data	08
14	Wheel data	08
15	Wheel data	08

The data are packed as follows:

<u>Word</u>	<u>Description</u>
1 bits 1-40	Time (ms)
bits 41-60	Code
2 bits 1-30	Sensor 1
bits 31-60	Sensor 2
3 bits 1-30	not used
bits 31-60	Sensor 3
4 bits 1-20	Background 1
bits 21-40	Background 2
bits 31-60	Background 3
5 bits 1-18	Error Word
bits 19-39	Digital data
bits 40-60	Digital data
6 bits 1-18	not used
bits 19-39	Digital data
bits 40-60	Wheel data
7 bits 1-18	not used
bits 19-39	Wheel data
bits 40-60	Wheel data

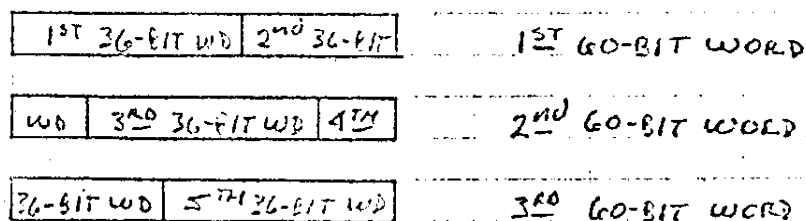
CORRELATION DATA TAP (CDT)
RECORDS FORMAT

69-006A-08A

WHL 1 (HV #1 MONITOR)
WHL 2 (HV #2 MONITOR)
WHL 3 (HV #3 MONITOR)
WHL 4 OPTICS TEMP.
WHL 5 ELECTRONICS TEMP.
WHL 6 HUB TEMP.
WHL 10 RIB TEMP.
WHL 14 BOTTOM SKIN TEMP.
WHL 19 TOP SKIN TEMP.
WHL 21 RIM SKIN TEMP.
WHL 40 DECK TEMP.

ALTITUDE/ORBIT RECORD (BINARY-FLOATING POINT)

(SHOWN AS 36-BIT REPRESENTATION, DUMTAPE
DISPLAYS IN 60-BIT GROUPS WITH 36-BIT
WORDS PACKED CONTIGUOUSLY AS FOLLOWS:



ETC.)

1		TIME 1 - DAY COUNT
2		TIME 2 - MILLISECONDS OF DAY
3		SATELLITE POSITION VECTOR, X-COMPONENT (KM.)
4		" " " Y- " "
5		" " " Z- " "
6		R.A. OF SATELLITE POS. VECTOR (DEGREES)
7		DECLINATION OF " " " "
8		VELOCITY VECTOR, X-COMPONENT (KM./SEC.)
9		" " " Y- " "
10		" " " Z- " "

CORRELATED DATA TAPE (CET) RECORDS FORMAT

CONT'D

11		R.A. OF VELOCITY VECTOR (DEGREES)
12		DECLINATION OF " " "
13		GEODETTIC LATITUDE "
14		" LONGITUDE "
15		" ALTITUDE "
16		UNIT SOLAR VECTOR, X-COMPONENT
17		" " " Y- "
18		" " " Z- "
19		R.A. OF UNIT SOLAR VECTOR (DEGREES)
20		DECLINATION " " " "
21		McILLWAIN'S "L" PARAMETER (EARTH RADII)
22		MAGNETIC FIELD STRENGTH (GAUSS)
23		UNIT MAGNETIC VECTOR, X-COMPONENT
24		" " " Y- "
25		" " " Z- "
26		R.A. OF MAGNETIC VECTOR (DEGREES)
27		DECLINATION " " " "
28		PITCH ANGLE (RADIAN'S)
29		ROLL ANGLE "
30		ASPECT ANGLE "
31		ΔT SINCE DIGITAL SUBCOM WORD 1 (W.)
32		ROLL-AXIS ORIENTATION, X-COMPONENT
33		" " " Y- "
34		" " " Z- "
35		R.A. OF ROLL-AXIS (DEGREES)
36		DECLINATION " " " "
37		PITCH-AXIS ORIENTATION, X-COMPONENT
38		" " " Y- "
39		" " " Z- "
40		R.A. OF PITCH-AXIS (DEGREES)
41		DECLINATION " " " "
42		YAW/SPIN-AXIS ORIENTATION, X-COMPONENT
43		" " " Y- "
44		" " " Z- "
45		R.A. OF YAW/SPIN-AXIS (DEGREES)
46		DECLINATION " " " "
47		ASPECT REF.-AXIS ORIENTATION, X-COMPONENT
48		" " " Y- "
49		" " " Z- "
50		R.A. OF " " " (DEGREES)
51		DECLINATION " " " "
52		SPIN RATE (REV./SEC.)
53		DATA TYPE INDICATOR (1.0=EVEN MIN. D)
54		ORBIT NUMBER
55		ORBIT BEGIN. (DAY COUNT)

CONT'D NEXT PG

9/5/71

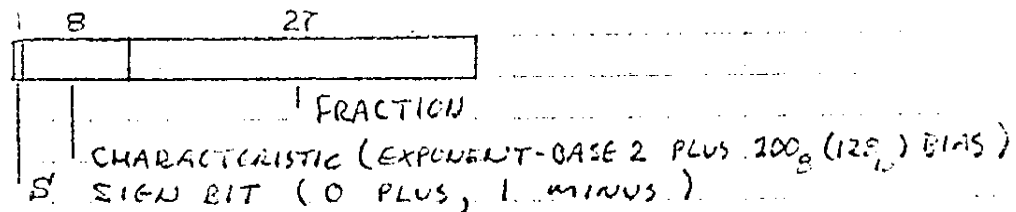
CORRELATED DATA LABEL (CDL)

RECORDS FORMAT

CONT'D

56		ORBIT BEGIN (MILLISECONDS OF DAY)
57		ORBIT END (DAY COUNT)
58		ORBIT END (MILLISECONDS OF DAY)
59		DAY/NIGHT INDICATOR (GEOMETRIC) 10-2A, 2B
60		SUNLIGHT EXIT (GEOMETRIC) (DAY COUNT)
61		" " " (MS. OF DAY)
62		" ENTRANCE " (DAY COUNT)
63		" " " (MS. OF DAY)
64		UNUSED
65		UNUSED
66		} ABOVE 65-WORD BLOCK FORMAT REPEATED FOR TOTAL OF 8 BLOCKS (1 MIN. EACH)
520		

ALL ATTITUDE/ORBIT DATA IS IN IBM 7094
(36-BIT) FLOATING POINT FORM:



ALL CARTESIAN COORDINATES REFER TO THE
CELESTIAL SYSTEM:

- X FIRST POINT OF ARIES
- Y ORTHOGONAL TO X AND Z
- Z POLARIS

LABEL PROCESSING

BCD

A(1)										
A(2)	11	12	13	14	15	16	17	18	19	20
A(3)	21	22	23	24	25	26	27	28	29	30
A(4)	31	32	33	34	35	36	37	38	39	40
A(5)	41	42	43	44	45	46	47	48	49	50

↓
DECODE IN QSPF DRIVER

INTEGER

LABEL (1)	COLS. 1-5	I5	SATELLITE ID. NUMBER
2	COLS. 6,7	I2	YEAR
3	COLS. 8-10	I3	STATION NUMBER
4	COLS. 11-14	I4	STATION TAPE NUMBER
5	COLS. 15,16	I2	ANALOG FILE NUMBER
6	COLS. 17,18	I2	BUFFER FILE NUMBER
7	COLS. 19-21	I3	DAY OF YEAR
8	COLS. 22-24	I3	REAL-TIME FRAME PERIOD
9	COL. 25	I1	TIME ACCURACY CODE
10	COLS. 26-30	I5	START TIME (SECONDS)
11	COL. 31	I1	UNPROCESSIBLE DATA FLAG
12	COLS. 32-36	I5	STOP TIME (SECONDS)
13	COLS. 37,38	I2	EXPERIMENTER NUMBER
14	COLS. 43,44	I2	EDIT FILE
15	COLS. 45-49	I4	EDIT TAPE NUMBER

COLS. 39-42 UNUSED

UNPACKING SCHEME FOR DIGITAL SPACE-CRAFT DATA.

C(1)	DAY				
C(2)	MILLISECONDS				
C(3)	WORD 9	WORD 36	WORD 37	WORD 41	SPARE
C(4)	SPARE	WORD 9	WORD 36	WORD 37	WORD 41
C(5)	SPARE	SPARE	SPARE	SPARE	SPARE
⋮	17 MORE GROUPS				
C(73)					

GROUP

UNPD SUBROUTINE

DSM(1)	DAY			GROUP 1, FIRST HALF
DSM(2)	MILLISECONDS			
:	0 ₁₀	ZERO	WORD 9	
:	36 ₁₀	ZERO	WORD 36	
:	37 ₁₀	ZERO	WORD 37	
:	41 ₁₀	ZERO	WORD 41	
:	0 ₁₀	ZERO	SPARE	
	ZERO			
	MILLISECONDS			
	9 ₁₀	ZERO	WORD 9	
	36 ₁₀	ZERO	WORD 36	
	37 ₁₀	ZERO	WORD 37	
	41 ₁₀	ZERO	WORD 41	
	0 ₁₀	ZERO	SPARE	
	ZERO			

GROUP 1, FIRST HALF

GROUP 1, SECOND HALF

RAW

UNPACKING SCHEME FOR WHEEL SPACE - CRAFT DATA.

B(1)	DAY				
B(2)	MILLISECONDS				
B(3)	WORD 1	WORD 2	WORD 3	WORD 4	WORD 5
B(4)	WORD 8	WORD 10	WORD 14	WORD 19	WORD 21
B(5)	WORD 40	SPARE	SPARE	SPARE	SPARE
B(6)	WORD 1	WORD 2	WORD 3	WORD 4	WORD 5
B(7)	WORD 8	WORD 10	WORD 14	WORD 19	WORD 21
B(8)	WORD 40	SPARE	SPARE	SPARE	SPARE
...	17 MORE GROUPS				
B(127)					

GROUP

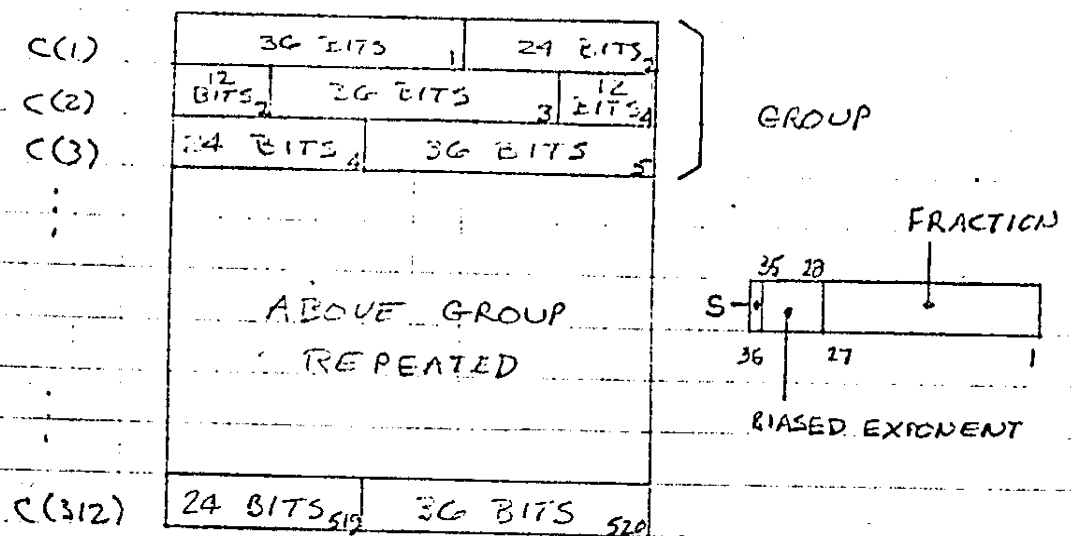
UNFW SUBROUTINE

WHL(1)	DAY		
WHL(2)	MILLISECONDS		
:	1 ₁₀	ZERO	WORD 1
:	2 ₁₀	ZERO	WORD 2
:	3 ₁₀	ZERO	WORD 3
:	4 ₁₀	ZERO	WORD 4
:	5 ₁₀	ZERO	WORD 5
:	8 ₁₀	ZERO	WORD 8
:	10 ₁₀	ZERO	WORD 10
:	14 ₁₀	ZERO	WORD 14
:	19 ₁₀	ZERO	WORD 19
:	21 ₁₀	ZERO	WORD 21
:	40 ₁₀	ZERO	WORD 40
	ZERO		
	ZERO		
WHL(505)	17 MORE GROUPS		

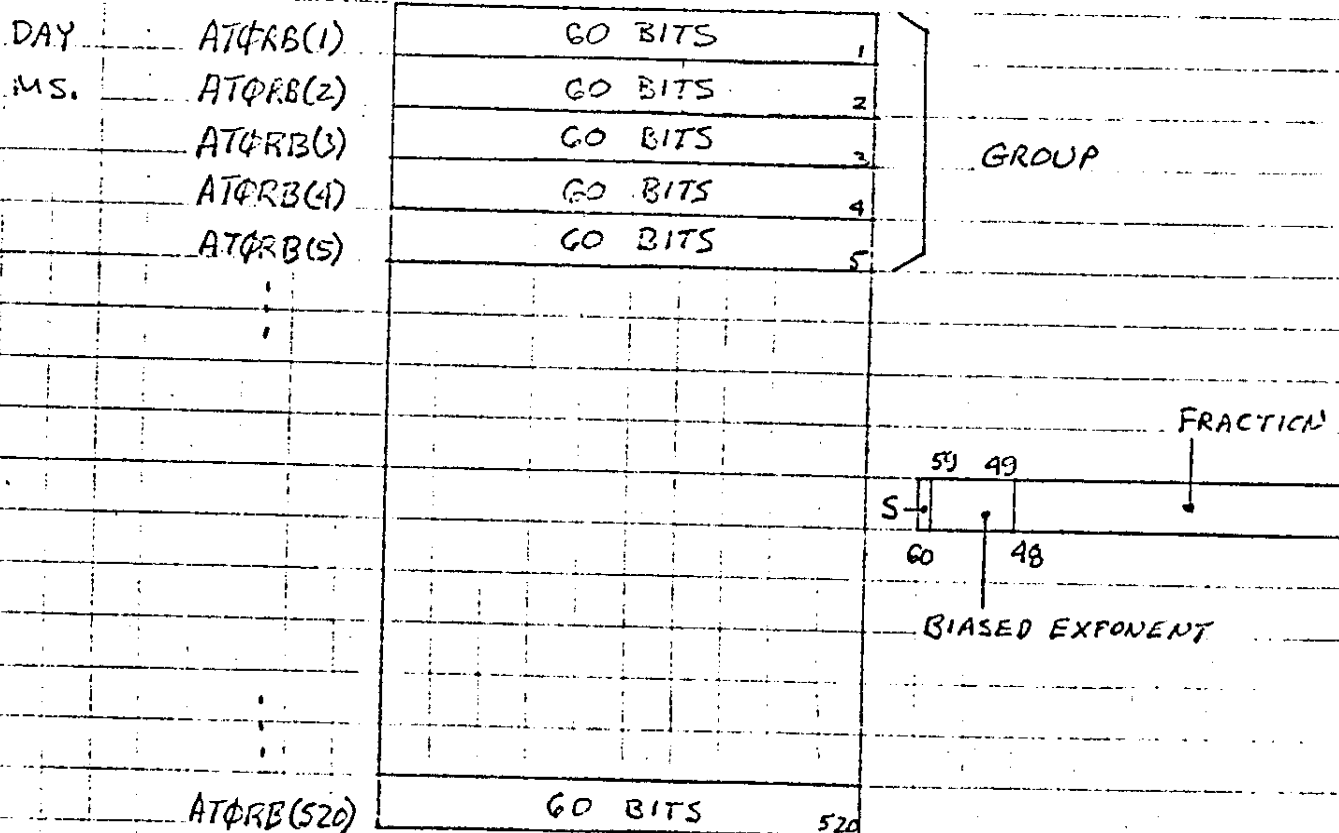
GROUP 1, FIRST MA

GROUP 1, SECOND MA

UNPACKING SCHEME FOR ATTITUDE/ORBIT DATA.



UNPACK36 SUBROUTINE



EIGHT 1-MINUTE SETS OF 65 WORDS PER SET.

UNPACKING SCHEME FOR SPACECRAFT MAIN FRAME DATA.

A(1) OR B(1)

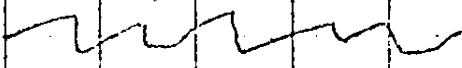
A(2) OR B(2)

⋮

A(42) OR B(42)

⋮

A(420) OR B(420)

TIME WORD 1				
TIME WORD 2				
1	2	3	4	5
6	7	8	9	10
11	12	13	14	15
				
191	192	S	S	S
S	S	S	S	S
TIME WORD 1				
TIME WORD 2				
1	2	3	4	5
				
S	S	S	S	S

1 GROUP OF TEN

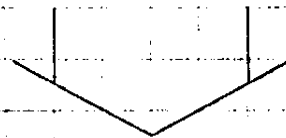
192 12-BIT DATA

SAMPLES

8 12-BIT ZERO

FILL SPACES

9 MORE GROUPS



UNP12 SUBROUTINE

IWORK(1)

IWORK(2)

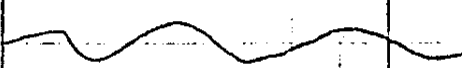
⋮

IWORK(193)

IWORK(194)

⋮

IWORK(1910)

TIME WORD 1	
TIME WORD 2	
ZERO	1
ZERO	2
ZERO	3
	
ZERO	191
ZERO	192
TIME WORD 1	
TIME WORD 2	
ZERO	1
	
ZERO	193

1 GROUP OF TEN

9 MORE GROUPS

ROLL

IWORK (1)

IWORK (2)

⋮

IWORK (194)

IWORK (1940)

TIME WORD 1	
TIME WORD 2	
ZERO	1
ZERO	2
	
ZERO	191
ZERO	192
TIME WORD 1	
TIME WORD 2	
ZERO	1
	
ZERO	192



FIND SUBROUTINE

ITEMP (1)

ITEMP (2)

⋮

ITEMP (12)

TIME IN MILLISECONDS	
CODE	
SENSOR 1	L.O. BITS
SENSOR 1	H.O. BITS
SENSOR 2	L.O. BITS
SENSOR 2	H.O. BITS
SENSOR 3	L.O. BITS
SENSOR 3	H.O. BITS
BACKGROUND 1	
BACKGROUND 2	
BACKGROUND 3	
SPARE	

ROW

IPAGE ARRAY IS BUILT IN OUT SUBROUTINE FROM DSM
AND WHL ARRAYS AND IN DASSMBL SUBROUTINE FROM ITEMIP ARRAY.

LINE 1

1	TIME
2	CODE
3	SENS 1
4	SENS 2
5	SENS 3
6	BKGD 1
7	BKGD 2
8	BKGD 3
9	ERR FLAG
10	DIG. 9
11	DIG. 36
12	DIG. 37
13	WHL. 1
14	WHL. 2
15	WHL. 3

LINE 11

16	TIME
17	CODE
18	SENS 1
19	SENS 2
20	SENS 3
21	BKGD 1
22	BKGD 2
23	BKGD 3
24	ERR FLAG
25	DIG. 41
26	ZERO
27	ZERO
28	WHL. 4
29	WHL. 5
30	WHL. 8

LINE 112

31	TIME
32	CODE
33	SENS 1
34	SENS 2
35	SENS 3
36	BKGD 1
37	BKGD 2
38	BKGD 3
39	ERR FLAG
40	ZERO
41	ZERO
42	ZERO
43	WHL. 10
44	WHL. 11
45	WHL. 19

LINE 113

46	TIME
47	CODE
48	SENS 1
49	SENS 2
50	SENS 3
51	BKGD 1
52	BKGD 2
53	BKGD 3
54	ERR FLAG
55	ZERO
56	ZERO
57	ZERO
58	WHL. 21
59	WHL. 40
60	ZERO

FORMAT

I10
I5
I8
I8
I8
I5
I5
I5
1X12X
2X48
2X48
2X48
2X48
2X48
2X48

ABOVE FORMAT REPEATED AS
NEEDED TO FILL A ONE -
MINUTE PAGE OF OUTPUT.

ROW

PACKING / UNPACKING SCHEMES FOR IPAGE / IPGPKD ARRAYS.

FORMAT

IPAGE(k)

IPAGE(k+1)

⋮

IPAGE(k+14)

TIME	1
CODE	2
SENSOR 1	3
SENSOR 2	4
SENSOR 3	5
BACKGROUND 1	6
BACKGROUND 2	7
BACKGROUND 3	8
ERROR WORD	9
DIGITAL DATA	10
DIGITAL DATA	11
DIGITAL DATA	12
WHEEL DATA	13
WHEEL DATA	14
WHEEL DATA	15

I10

I5

I8

I8

I8

I5

I5

I5

Φ2

Φ8

Φ8

Φ8

Φ8

Φ8

Φ8

...

UNPKIPG SUBROUTINE



PKIPAGE SUBROUTINE



IPGPKD(l)

IPGPKD(l+1)

⋮

IPGPKD(l+6)

1	2
3	4
5	6
7	8
9	10
11	12
13	14
15	16

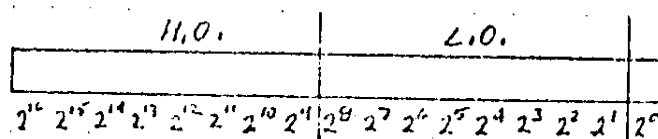
...

RESULTS IN $\frac{7}{15}$ FACTOR OF STORAGE SAVINGS.

ROW

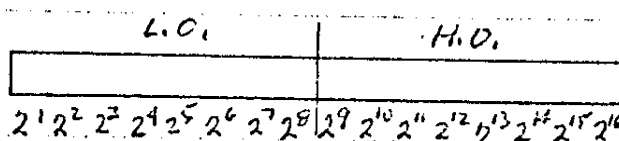
DATA HANDLING

17-BIT S/C WORDS



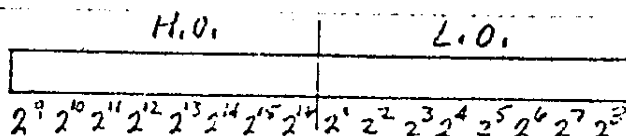
ONBOARD S/C
(SENSOR)

DATA COMES TO US IN 8-BIT BYTES
(BIT 2⁰ DROPPED), L.O./H.O. BYTES
REVERSED AND BIT ORDER REVERSED
WITHIN BYTES (DUE TO T/M
HANDLING ONBOARD S/C):

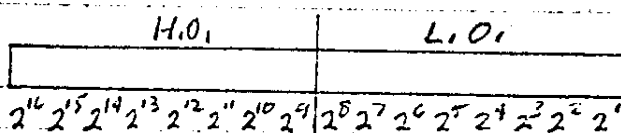


AS GIVEN TO US

ΦSΦFRD PROGRAM REVERSES L.O./H.O.
BYTE ORDER (IN DASSMBL):

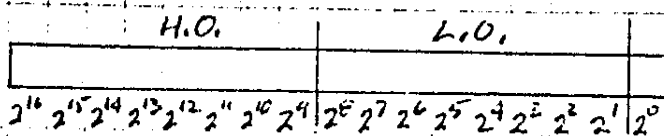


ΦSΦFRD PROGRAM REVERSES BIT
ORDER VIA KBIT TABLE (IN DASSMBL):

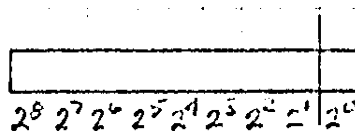


← DONE IN ONE
STEP

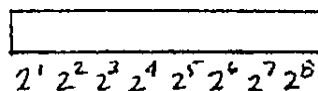
ΦSΦFRD PROGRAM MULTIPLIES BY TWO
(LS2) TO CORRECT FOR BIT 2⁰ BEING
DROPPED (IN DASSMBL) TO
RECONSTRUCT ORIGINAL S/C WORD
WITH UNCERTAINTY ONLY IN BIT 2⁰:



9/2/70

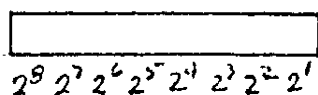
9-BIT S/C WORDSONBOARD S/C
(BACKGROUND)

DATA COMES TO US IN 8-BIT BYTE
(BIT 2^0 DROPPED) AND BIT ORDER
REVERSED (DUE TO T/M HANDLING
ONBOARD S/C):

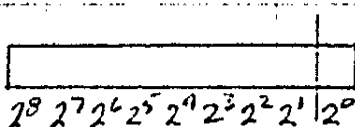


AS GIVEN TO US

ΦSΦFPRD PROGRAM REVERSES BIT ORDER
VIA KBIT TABLE (IN DASSMBL):



ΦSΦFPRD PROGRAM MULTIPLIES BY TWO
(LS2) TO CORRECT FOR BIT 2^0 BEING
DROPPED (IN DASSMBL) TO
RECONSTRUCT ORIGINAL S/C WORD
WITH UNCERTAINTY ONLY IN BIT 2^0 :

DONE IN
ONE STEP9/2/70
Row

MONITORING OF SOLAR FAR ULTRAVIOLET RADIATION

FROM THE OSO-5 SATELLITE

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16. Abstract A spectrophotometer for monitoring the solar EUV in three broad wavelength bands is described. The kind of data obtained, along with sources of error, are presented. The content of the tape library which contains the data is outlined. The scientific results are discussed. These include: solar flares in the EUV, solar eclipse observations in the EUV, SFD's and relationship to solar flares, and the application of satellite sunrise and sunset data for the study of model upper atmospheres for the earth.					
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Preface

The main objective of the work was to monitor the solar EUV from a wheel instrument on OSO-5. The instrument as finally designed, constructed, and calibrated, was a spectrophotometer utilizing a concave grating and three photomultiplier tubes. The latter detected radiation in three broad wavelength channels, respectively: 1) 280-370 Å, 2) 465-630 Å, and 3) 760-1030 Å. The pulses due to the EUV photons striking the photomultipliers were amplified, shaped and counted. Detection occurred for 30 milliseconds during each revolution of the wheel. The spectrophotometer was turned on for several orbits each day, and obtained usable data from launch (January 21, 1969) through June 1971.

Data were obtained for three large solar flares (March 12, 21 and April 21, 1969). The variation of EUV intensity with time was quite similar for all three bands, and, for the April 21 flare, for which hard X-ray data were available, resembled closely the time variation of the latter. Impulsive peaks were observed for all three bands, superimposed on a rapid rise to maximum and slow decline. Band 3, the one containing photons of highest energy, showed much less tendency for exhibiting these impulsive components. A model of a large flare is proposed based on the OSO-5 EUV data and the concept of twisted magnetic fields around sunspot groups brought on by differential rotation of the sun.

Observations of a partial solar eclipse in the three EUV bands gave some information on the brightness of active areas in EUV, and on the presence or absence of limb-brightening.

Data on the time variation of EUV intensity during sunrise or sunset, for each wavelength band, were compared with the variation predicted from the prevailing CIRA 1965 model atmosphere. For sunset, the predicted curves could be brought into agreement with the observations of all three bands by a modification of the CIRA atmosphere involving a lowering of atomic oxygen density and an increase of molecular nitrogen density.

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I. Objective

The objective of the work of this contract was to a) design, construct and calibrate a spectrophotometer for monitoring the EUV radiation from the sun in three broad bands, b) obtain data with the spectrophotometer from the wheel of the OSO-5 satellite and reduce this data to convenient form, and c) analyze some of the more important data to obtain scientific information about the sun and the earth's upper atmosphere.

II. Introduction

The design of the spectrophotometer for accomplishing the above objectives began in 1964 under contract NAS 5-3931 (June 25, 1964). The choice of the three broad bands to be monitored in the solar EUV was made on the basis of their usefulness as a means of obtaining information on the densities of air at higher levels in the earth's atmosphere and their importance in helping to understand such solar phenomena as flares, enhanced emission from active areas, and long range time variation of solar EUV. Some thought was given to the possibility of designing the spectrophotometer for monitoring only some of the brighter EUV lines in the solar spectrum, but the decision to monitor the bands instead was made on the basis of 1) greater reliability of the instrument and associated electronics because of the higher intensity of the radiation and 2) need at the time for examining solar intensity variation for the entire EUV. Although the three broad bands finally chosen did not cover the entire EUV, they did represent most of the EUV radiant energy below $1030 \text{ \AA}$. These bands are: channel 1: $280\text{--}370 \text{ \AA}$; channel 2: $465\text{--}630 \text{ \AA}$; and channel 3: $760\text{--}1030 \text{ \AA}$. Channel 1 contains strong emission lines such as He II ($304 \text{ \AA}$), Mg IX ($368 \text{ \AA}$), Fe XVI ($335 \text{ \AA}$) and Fe XV ($284 \text{ \AA}$). Channel 2 includes such lines as He I ($584 \text{ \AA}$); O V ($630 \text{ \AA}$); Mg X ($625 \text{ \AA}$ and $610 \text{ \AA}$); Si XII ($500 \text{ \AA}$), Ne VII ($465 \text{ \AA}$) and He I continuum. Channel 3 contains the hydrogen Lyman continuum, the hydrogen Lyman series lines from Lyman beta ($1026 \text{ \AA}$) to shorter wavelengths, C III ($977 \text{ \AA}$), O III and O II ($834 \text{ \AA}$), O IV ($790 \text{ \AA}$) and Ne VIII ($770 \text{ \AA}$).

The instrument itself, to assure sufficient speed in the far EUV, was chosen to be a grating spectrophotometer of the grazing-incidence (Rowland circle mount) type. The detection of the EUV was to be made with photomultipliers, one for each wavelength band. The photomultiplier bursts, produced by EUV photons, were to be electronically counted in a suitable way. Radiation from the entire solar disc was to be allowed to enter the spectrophotometer aperture for each revolution of the OSO satellite wheel.

III. Instrumentation

A. Structural Features

The spectrophotometer has the appearance of a truncated, pie-shaped unit made of an aluminum sandwich structure. (Fig. 1). The main spacecraft connector and its cable are mounted on the back wall of the instrument. The back wall and the top are perforated with a pattern of small holes which serve to outgas the instrument in flight. The bottom side of the instrument is made of 1/2 inch aluminum plate containing threaded holes for fastening the instrument to the deck of the spacecraft. The two side walls are made of relatively thin, reinforced aluminum sheet. The front face has a highly reflective surface finish to thermally decouple the instrument from the front panel of the spacecraft. All other exterior surfaces are blackened for efficient radiative coupling to the inner walls of the spacecraft compartment.

The interior of the instrument contains the optical parts and the detection system with associated electronic components.

B. Optics

The optical layout of the spectrophotometer is shown in Figure 2. Light from the entire solar disk enters the slit A and, at a grazing angle of 80° , strikes the concave, 20 cm radius, 1200 line/mm grating G where the EUV in the three wavelength bands are diffracted and brought to focus along the Rowland circle. Three Bendix M 306 resistant strip photomultipliers (1,2,3) receive the three first-order bands, respectively. The EUV which is detected by photomultiplier 2 is first reflected by the mirror M, but the other two beams pass through apertures in the Rowland circle before striking the tube cathodes. Light at the central image is trapped at C. The apertures restrict the geometrical size of each beam, and limit the wavelengths in the bands. The latter limits are: 280-370 Å (Channel 1), 465-630 Å (Channel 2), and 760-1030 Å (Channel 3).

Channel 1 in practice was free of overlapping spectral orders because of the insensitivity of the spectrophotometer for wavelengths less than about 280 Å. Channels 2 and 3, however, include higher order wavelength radiation

Figure 1.

Photograph of Spectrophotometer

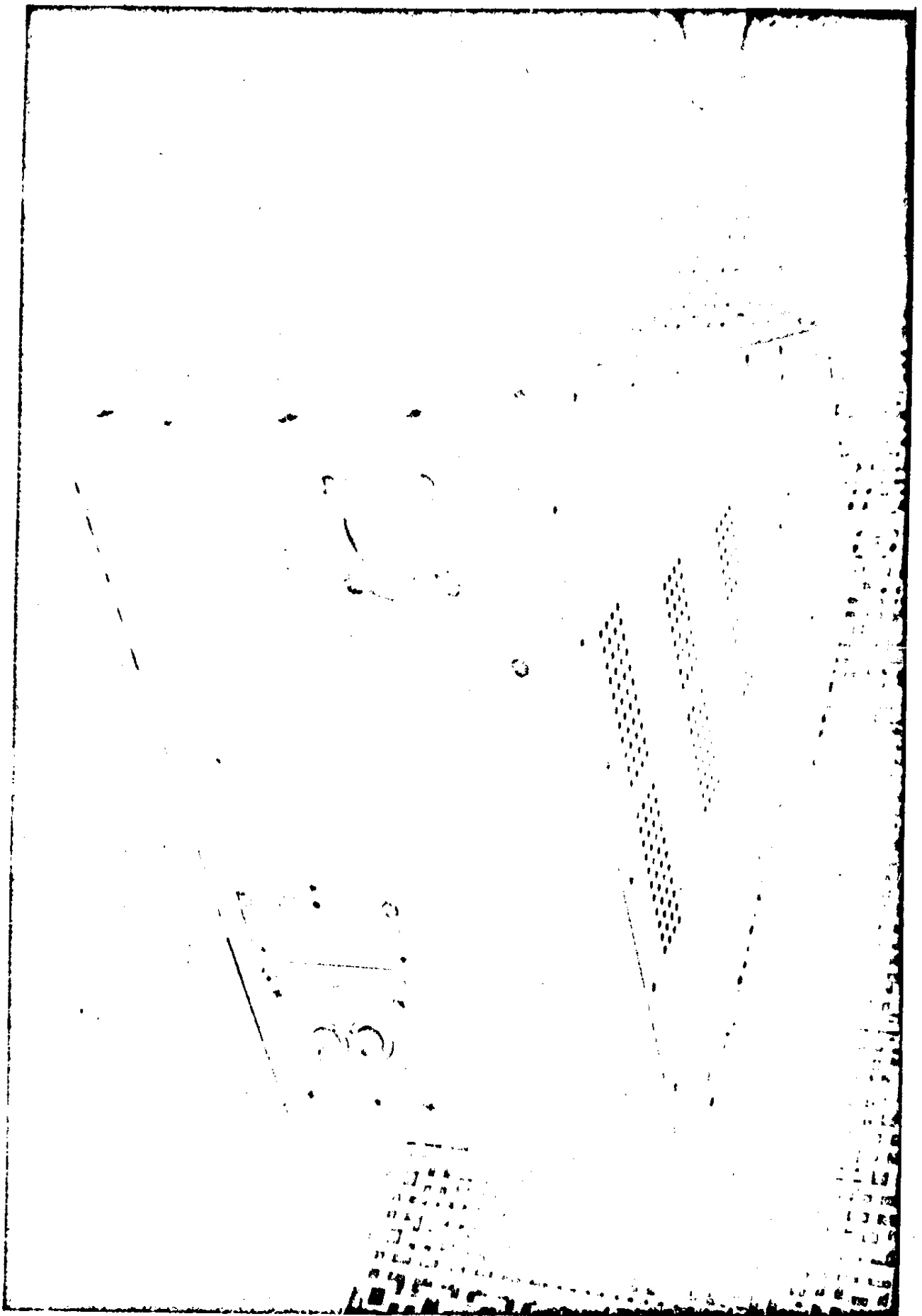
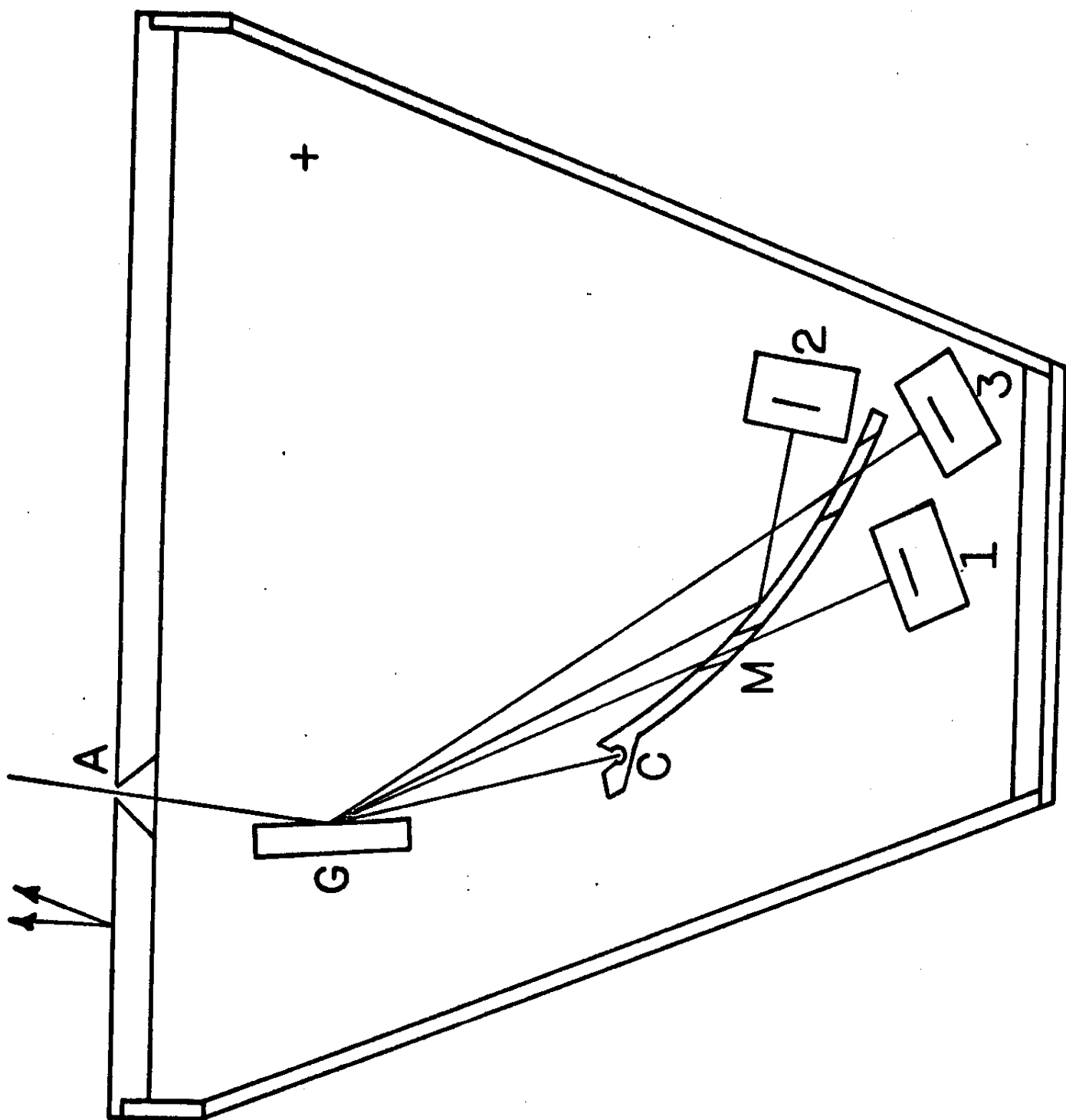


Figure 2.
Optical Layout of Spectrophotometer



outside their proper ranges; these effects had to be allowed for by the calibration process.

C. Detection

Three Bendix M 306 resistance strip photomultipliers are the basic detectors, one for each EUV wavelength band (or channel). The pulse signals from these photomultipliers are amplified and then shaped. The shaped pulses are sent through electronic gates to a combination of three binary counters and shift registers where they are stored. Counting takes place only when the electronic gate is open. The gate is opened when the sun activates an indexed solar eye unit which is fixed on the outboard wall of the instrument. During this interval (two are possible: 30 millisecc or 10 millisecc) the sun is illuminating the spectrophotometer grating. After the gate closes, stored counts for each channel are read out to the telemetry and the counters reset to zero. The count range is from 100 to 20,000. The trigger eye optics consists of a cylindrical lens, two glass filters and two photo-resistive diodes. Following read-in, there is a delay ranging from 120 to 310 milliseconds while the commutator is synchronized with the digital telemetry system. One read-out gate is used to acquire synchronization.

For read-out of solar data a sequence of 10 mainframe words is necessary. The first data word is a code word consisting of eight binary "ones." Words 2 and 3 contain the 16 bit binary number stored in the counter for channel 1. The number is read out starting with the least significant bit and proceeding, in sequence, to the most significant bit. Words 4 and 5 contain the intensity data from channel 2; words 6 and 7, from channel 3. Words 8, 9 and 10 contain the eight least significant bits from the background readings of the three channels, respectively. Zeros are now presented to the telemetry system until the next read-in has been completed. When the instrument is calibrated, the read-out sequence is the same as that above, except that the code word now consists of a binary "zero" followed by seven binary "ones." Data read-out is on Main Frame data words 15 and 27.

Five housekeeping channels are used. Analog subcom channels 1, 2, and 3 monitor a voltage proportional to the low voltage supplied to each of the

three detector high voltage supplies in data channels 1, 2, and 3 respectively. Housekeeping channels 4 and 5 monitor temperature probes; the first probe is in the vicinity of the electronics, the second, near the photomultipliers. The analog subcom is read out on Main Frame data word 25.

The command allocation is as follows:

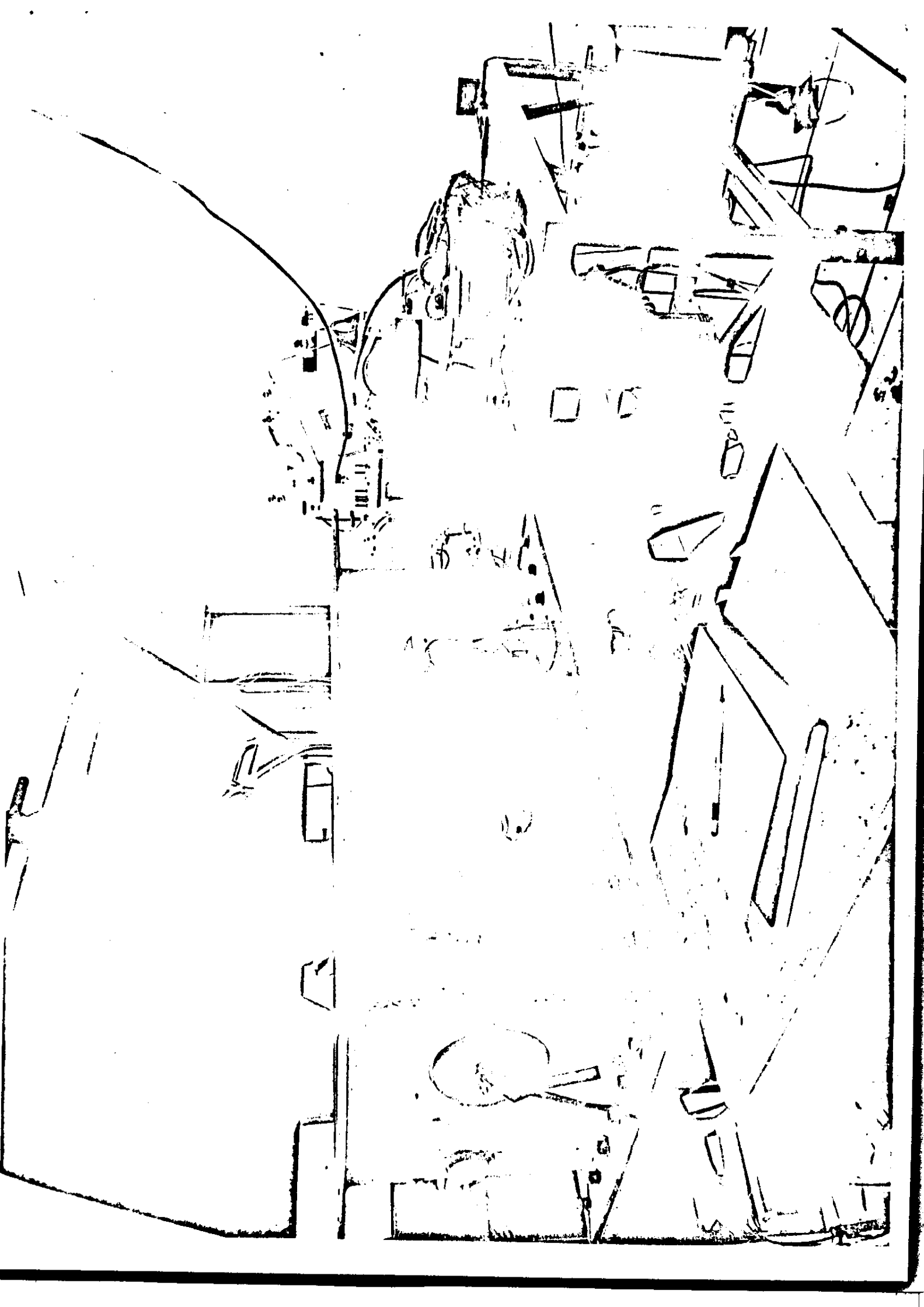
<u>Command No.</u>	<u>Function</u>	<u>Code Format</u>
19	Turns on equipment	0414
11	All high voltage off	0305
113	Channel 2 H.V. on	0309
114	Channel 3 H.V. on	0310
215	Channel 1 H.V. on	0312
202	Calibrate - 4 per hour	0107
229	Calibrate - 1 per hour (30 ms)	0609
132	Calibrate - 1 per hour (10 ms)	0701

D. Calibration

The purpose of the calibration of the spectrophotometer was to provide a means of converting the output of a given channel in terms of counts to an output in terms of absolute intensity of the EUV solar radiation associated with that channel (that is, one of the three wavelength bands).

The vacuum system for calibration (Figure 3) consisted of three separate chambers connected by 6" gate valves: 1) the main chamber which holds the instrument positioned on a rotating table to simulate the rotation of the satellite, 2) the monochromator chamber containing the high voltage capillary discharge source, and 3) the grating chamber. The gases used in the capillary discharge source were hydrogen, helium, argon and xenon in order to provide a range of appropriate wavelengths. A three-stage differential pumping system was required to assure the necessary degree of vacuum in the main chamber. The

Figure 3.
The Calibration System



concave grating, serving as the dispersing element, may be rotated so as to select the wavelength falling on the instrument. A series of apertures collimates the light from the source before the light reaches the grating, so that, as viewed from the instrument, the monochromatic beam from the grating corresponds to a source that subtends an angle of $32'$. The grating can be replaced by a suitable concave mirror when "white" light is desired. Detection was accomplished by means of a flow-through ion chamber; the current produced by the ionization of the gas in the latter chamber was measured and the absolute intensity of EUV radiation energetic enough to ionize the given gas was computed. A photomultiplier detector at the end of the ion chamber enabled the experimenter to determine when all the EUV radiation passing through the chamber was absorbed in the chamber.

The calibration set-up described above gave sufficient flexibility in wavelength band selection to determine the constants required to convert counts from each wavelength channel of the satellite spectrometer detection system into absolute intensity of the EUV radiation (for that channel) striking the optical aperture of the spectrometer. Nine constants are required as outlined below.

To allow for first order and overlapping order effects, the number of counts S'_i of channel i can be represented by:

$$S'_i = K_{i1} I_1 + K_{i2} I_2 + K_{i3} I_3$$

where I_1 , I_2 and I_3 are the actual intensities of the radiation in the three channels, incident on the spectrometer, and K_{i1} , K_{i2} , K_{i3} are constants which are determined by the calibration procedure. The matrix equation:

$$(S') = (K) (I)$$

may be inverted to obtain (I):

$$I = (K)^{-1} (S')$$

The values of the constants (K's) as determined in the laboratory when used for the actual solar observations from the satellite did not yield realistic values for the intensities of channel 2 and channel 3 but the results for channel 1 were

in good agreement with measurements made by other observers. Accordingly, for convenience in interpreting data, the K's were altered so that reduction to absolute intensities was made to conform to the Hinteregger's values:

$$I_1 = 8.99 \times 10^9 \text{ photons/cm}^2/\text{sec}$$

$$I_2 = 4.40 \times 10^9 \text{ photons/cm}^2/\text{sec}$$

$$I_3 = 20.4 \times 10^9 \text{ photons/cm}^2/\text{sec}$$

The matrix used in such reduction is:

$$\begin{bmatrix} S'_1 \\ S'_2 \\ S'_3 \end{bmatrix} = \begin{bmatrix} 4.31 & 0 & 0 \\ 3.66 & 11.2 & 0 \\ 0.371 & 0.372 & 1.88 \end{bmatrix} \times 10^{-7} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix}$$

Before applying the above matrix to compute absolute values, the actual observed counts, S , were corrected to obtain S' . The correction involved two steps: first, the elimination of scattered light, and second, the allowance for degradation since launch time. The scattered light, mostly the 1216 Å radiation of the solar hydrogen Lyman alpha line, was measured by observing the sunrise data of each channel. The degradation correction was made by empirically fitting a suitable analytic expression for each channel to the observed curves: average count at spacecraft noon versus time. A source of error which could not be systematically accounted for was pitch of the spacecraft.

In order to have an in-flight check on the performance of the spectrophotometer, a calibration lamp was included in the instrument. The lamp was a sapphire-windowed glass capillary tube containing Xenon gas and operated by a high voltage supply. The ultraviolet radiation emitted falls on the cathodes of the three photomultipliers and produces an output in the form of counts. Changes with time in the sensitivity of the cathodes or in the response of the electronic components associated with the amplification of signal and the subsequent counting system could be monitored in this way. The detection system can be checked by exciting the lamp every 256 or 1024 revolutions of the wheel (determined by command).

IV. Data Reduction

A. Data Sequence

Counts for each channel are obtained for 30 milliseconds when the sun is in the field of view. The counters are then read out to the telemetry and reset to zero. A background count (usually zero) is then made with the sun out of the field of view and the counters again read out to telemetry. The cycle is then completed until initiated by the next pulse from the monitoring eye.

For a few weeks after launch, data from the calibration lamp in the form of counts were obtained every 1024 revolutions of the wheel. Because of a malfunction, these data were discontinued. Later (May 1969) another malfunction in the calibration unit required that the data henceforth be activated by command.

One orbit storage on s/c tape recorders is made for playback to ground stations. For each channel the solar data appear as two 8-bit binary words serially each revolution of the wheel.

In general, to prolong the period of data-taking despite degradation, data are acquired for three consecutive orbits out of every fifteen per day. Useful data have been collected for the period January 23, 1969 to July 19, 1971, spanning about 14,000 orbits of the satellite. This date was chosen because by that time the degradation of the instrument response for EUV wavelength bands 1 and 2 was quite advanced, and that of band 3 moderately advanced. The noise effects were not reduced proportionately, so that measurements during flares, satellite sunrises, and satellite sunsets were not of sufficient quality to justify further reduction of data.

B. Data Library

The tape library of data acquired for the period January 23, 1969 to July 19, 1971 consists of the following:

1. 1068 quicklook tapes
2. 191 correlated data tapes
3. 178 main frame data tapes
4. 46 command history tapes
5. 137 merged data tapes

6. 28 final merged data tapes ✓
7. 289 scratch tapes
8. 1 tape of condensed data from 13,000 orbits

The printed output library consists of:

1. 14 binders containing label information from direct output of the OSO-5 program (1,000 orbits or CDT files per binder)
2. 2 binders containing selected information on each orbit
3. 2 binders of label information, via the merged program, for each re-formatted file on the merged data tapes
4. 1 binder containing the above three items of information for data of poorer quality which was not placed on the final merged data tapes
5. 1 binder containing printout of the punched output from the OSO-5 program
6. 1 binder containing output of the catalog program which shows orbit number vs. file number for the correlated data tapes
7. 1 binder containing computer program listings for all the auxillary programs as well as main programs for OSO-5

In addition there are 13 boxes of punched output from the OSO-5 program containing condensed data for about 1,000 orbits, and 6 boxes of OSO-5 main and auxillary program decks. A 500 page volume includes the documentation of all OSO-5 computer programs which were written for the handling and analysis of all the data.

C. Data Presentation and Error Analysis

A graph of observed noon-day counts vs. orbit number for all three channels is shown in the lower graph of Figure 4. From top to bottom, the sets of points refer, respectively, to channels 3, 1, 2. Many of the irregularities in these curves are not real. The gradual degradation of each channel is quite apparent, as are the breaks where no data were obtained (instrument off). All of the data counts were acquired in a 30 millisec interval. Other variations in the curves may be attributed to 1) pitch of the satellite, 2) interaction of raster

Figure 4.
Sample Data, EUV vs. Time

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RECORDS
OF THE
UNITED STATES
DEPARTMENT OF THE INTERIOR
BUREAU OF LAND MANAGEMENT
WASHINGTON, D. C. 20080

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WASHINGTON, D. C. 20080

scanning of the pointed instruments on the satellite, 3) intrinsic variation in instrument response, 4) actual variations in the solar EUV intensity for each channel. Each of these will be considered.

A graph of the monitored values of satellite pitch at noon vs. orbit number is shown in the upper graph of Figure 4. This curve does not show short period pitch changes which sometimes also occurred. An effort to find a systematic quantitative relationship between the curves in Figure 4 was unsuccessful. In general, channel 1 intensity increases for large negative pitch, and that for channel 2 decreases. A change in pitch would cause the solar light to sweep through the instrument aperture at a slightly different angle. Because of the presence of baffles in the optical paths of the three channels, pitch changes could cause variations in the amount of EUV striking the photo tubes. Moreover, if the reflectivity of the grating changed over the area of the grating, and if the photocathode surfaces of the photomultipliers were not uniformly sensitive, pitch effects would be present. For analysis of data for a particular orbit, or fraction of an orbit, pitch changes were normally negligible, and do not alter the observed values of, at least, relative intensity vs. time.

When raster scanning of the pointed instruments on the satellite occurs, the EUV counts from the photomultipliers oscillate in a somewhat regular manner. The effect is only occasionally present and can easily be recognized. It may be nearly completely eliminated by a suitable averaging of intensities over several adjacent points. However, time resolution of the measurements may be reduced when such averaging is required.

An apparently random variation of intensity from point to point is present in each channel. It is least for channel 3. No explanation for this irregularity in response could be found, but it appears to be instrumental. When adjacent intensity points over several consecutive revolutions of the wheel are averaged, a regular variation is observed of period approximately 5 minutes. It is believed that this effect is either instrumental or associated with the satellite environment. A gradual decline in average intensity of the EUV is observed in all cases during the daytime interval after satellite sunrise and before satellite sunset. Again, this effect is believed to be instrumental and is probably the result of

temperature changes. It may also reflect a temporary loss in sensitivity of the photomultipliers over the time of continuous diurnal exposure.

Changes in intensity other than those mentioned above are assumed to be real variations in solar EUV radiation. An example is that of a solar flare. For such variations, after a suitable averaging procedure, relative intensities are normally estimated to be accurate to 2% with a time resolution of about 4 seconds.

V. Science

A. Scope of Science Analysis

Four scientific projects were undertaken and completed in the analysis of the reduced solar EUV data. These are 1) study of large flares, 2) interpretation of solar eclipse EUV data of March 7, 1970, 3) study of relationship between solar EUV flare intensities and sudden frequency disturbances (SFD's), 4) analysis of sunrise and sunset absorption data for comparison with predicted absorption of CIRA model atmospheres for the earth.

The detailed results of the above projects are contained in the papers:

1. "Solar Flares in the EUV Observed from OSO-5," by P. T. Kelly and W. A. Rense, to be published in Solar Physics, September or October, 1972 issue.
2. "Observations of March 7, 1970 Solar Eclipse from OSO-5 in Far UV," by R. Parker and W. A. Rense, Report UAG-2, Part III, (World Data Center A, Upper Atmosphere Geophysics), April, 1971, p. 417.
3. "SFD's for Three Large Solar Flares," by F. Solheim. Thesis in progress for Ph.D. degree, University of Colorado, 1972.
4. "Broad Band Solar EUV Absorption in Upper Atmosphere," by K. Allen and W. A. Rense (to be submitted for publication).

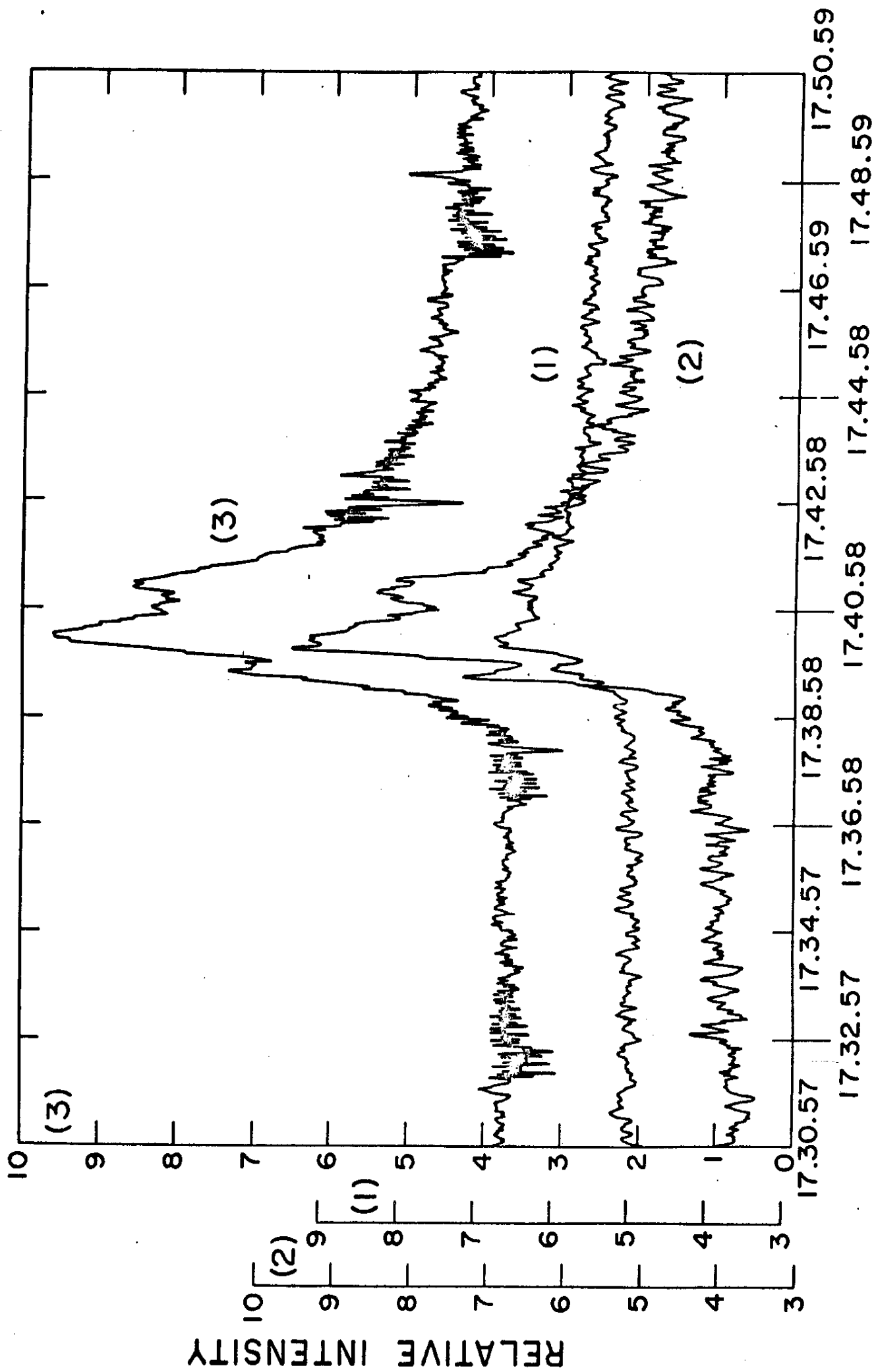
Only a brief summary of some of the results of the above papers will be given here.

B. Solar Flares in the EUV

Solar flares in the three EUV channels were observed for flares of brightness 1B, 2B and 3B. Figures 5, 6 and 7 show the variation of EUV intensity with time for each of the channels for the large flares of March 12, March 21, and April 21, 1969. In general, the time dependence of flare intensity in each band is characterized by a more or less slowly varying component with one or more impulsive bursts superimposed. Channel 2 (465-630 Å) and channel 3 (760-1030 Å) are quite similar in their time variations, but channel 1 (280-370 Å) shows less or no impulsive structure, and declines more slowly. The total time-integrated absolute flare energies for the three channels, 1, 2, and 3, are, respectively, (in units of ergs): March 12, 1.0×10^{29} , 1.4×10^{29} , and $1.3 \times$

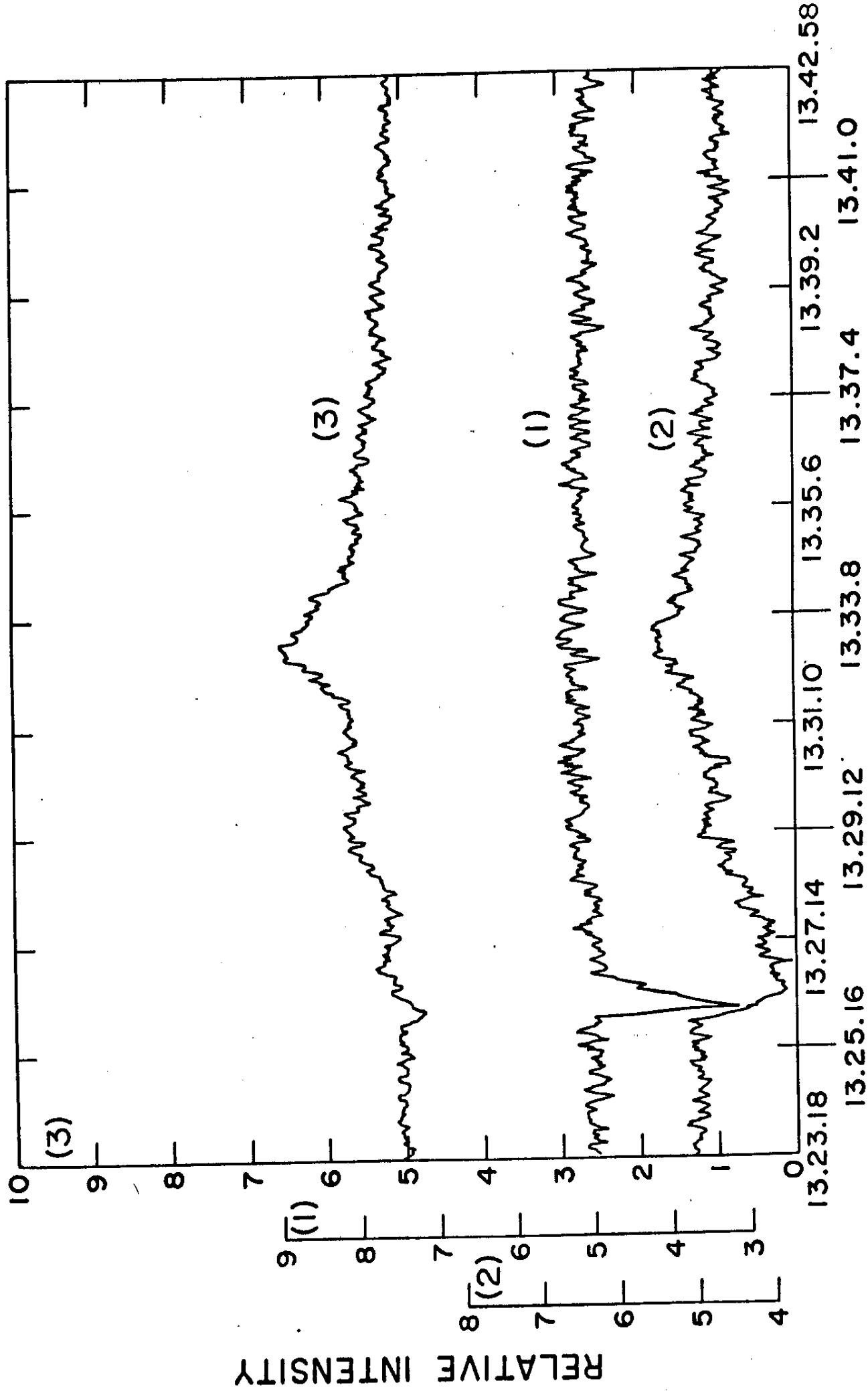
Figure 5.

Solar Flare of March 12, 1969



GMT 12 MARCH 1969

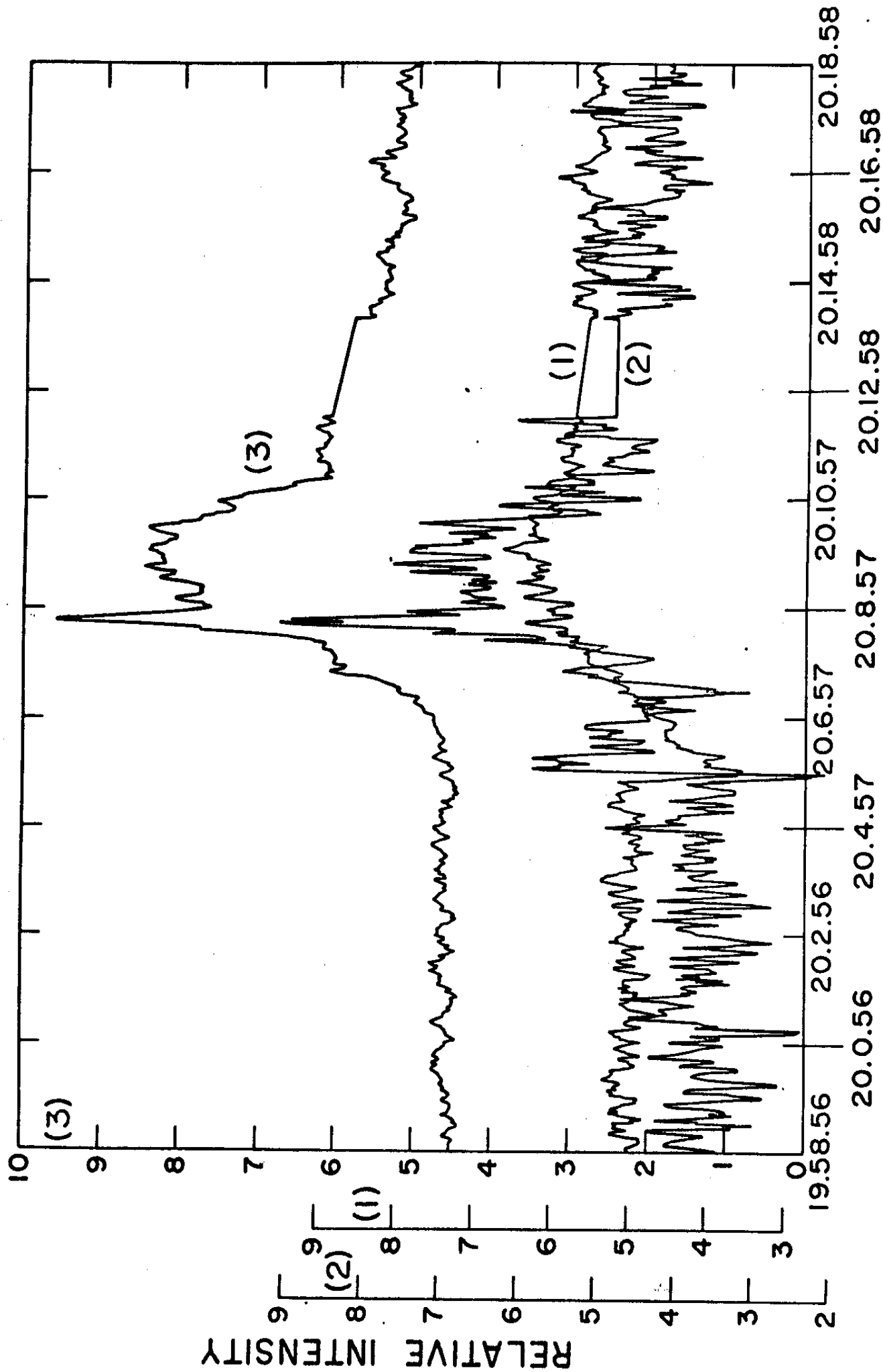
Figure 6.
Solar Flare of March 21, 1969



GMT 21 MARCH 1969

Figure 7.

Solar Flare of April 21, 1969



GMT 21 APRIL 1969

10^{29} ; March 21, 7.0×10^{28} , 4.0×10^{28} and 1.3×10^{29} ; April 21, 1.3×10^{29} , 1.6×10^{29} and 2.2×10^{29} ,

A comparison of available data on 2800/mc/sec radio emission during the above flares led to the conclusion that the onset of the first rapid intensity increase in the radio emission was associated with the first impulsive component of the flare EUV radiation. For the April 21 flare, data on hard X-ray emission was available. The time variation of this X-ray component of the flare was similar in considerable detail to that of the EUV components.

An idealized model of a flare is proposed which accounts for the general characteristics of the time variation in the flare EUV. The model is primarily based on the theoretical investigations of Bessey and Kuperus (5) (Bessey, R. J. and Kuperus, M.: 1969, Conference on Chromosphere - Corona Transition Region, Boulder, Colorado) and of Barnes and Sturrock (6) (Barnes, C. W. and Sturrock, P. A.: 1972, AP. J. 174, p. 659). The first of these papers deals with the dynamic and thermal changes that occur in a mass of solar chromospheric plasma when energy is applied to a thin layer. Their computations show that within 200 seconds, for an energy input of about 10^{12} ergs/gm/sec: 1) the original exponential density distribution is replaced by one that is approximately uniform; 2) upward expansion velocities of as much as 50 km/sec could be produced; 3) shock waves could be formed with material streaming up after the shock. These results apply to an idealized situation with no magnetic field present. However, they apply qualitatively if a magnetic field is present, especially where the latter is nearly perpendicular to the photospheric surface. Barnes and Sturrock (loc. cit., above) consider the case with a magnetic field extending from a sunspot to regions symmetrically surrounding the spot, and of opposite polarity. They calculated the energy in possible force-free fields (resulting from twisting due to differential rotation) which have the same boundary conditions and found that, for a sufficient amount of twisting, the energy in the force-free field can be greater than that in an open field having the same photospheric boundary conditions. They propose that in a flare a force-free field, by a series of explosive processes, may change to an open field of lower energy.

The model described here utilizes the results of the above investigators to explain qualitatively the general features of the EUV radiation emitted during

a large flare. Consider the magnetic field associated with an active spot group after it has been twisted by rotation of the spot center. Then, as mentioned above, its energy is greater than that of the original, untwisted field. This energy comes from that associated with the differential rotation of the sun. Next, suppose that the degree of twisting has proceeded to the point that the closed force-free field has energy greater than that of an open field with the same photospheric boundary conditions, namely, it is in a metastable state as pointed out by Barnes and Sturrock in the paper cited above. If heating in some part of the lower region of the plasma engulfed by the magnetic field produces a local energy input over a critical value, given as 10^{12} erg/g/sec by Bessey and Kuperus, then a shock wave will be produced as found by the latter authors (loc. cit.). The material streaming upward after the shock wave opens the magnetic lines of force and provides the mechanism for the explosive transition from the metastable closed field to the lower energy open field. Magnetic energy is released to the plasma to raise its temperature and to accelerate charged particles. This is the part of the flare which corresponds to the impulsive peaks of the EUV time-variation curves (Figures 5, 6, and 7). According to Barnes and Sturrock the energy released could be of the order of one-fifth of that in the original current-free magnetic field. The energy given to a charged particle during this phase averages about 100 keV and may be as high as 10^3 keV. The lines of the open field are then reconnected to form a closed field corresponding to the original undistorted field. The energy here released may be of the order of that in the original field and accounts for the main part of the flare energy (Barnes and Sturrock, loc. cit., and Sturrock (7), Solar Physics, in press, and, for the relativistic particles, C. deJager (8), Utrechtse Sterrekundige Overdrukken, No. 92, 1, 1969).

The triggering of the transition from the closed field metastable state to the open field configuration may be the falling of material in prominences (Ch. L. Hyder (9), Solar Physics, Vol. 2, 1967). Much of the EUV flare radiation could be a result of collisional excitation at lower levels after the release of trapped particles when the magnetic field opens. The hard X-rays originate in the same way, as well as some of the radio emission. Those emissions would be associated with the impulsive part of the flare.

C. Solar Eclipse Observations

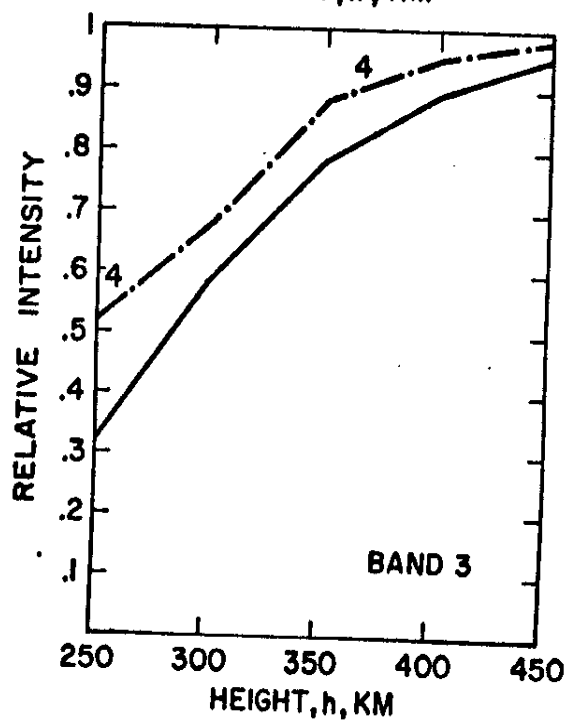
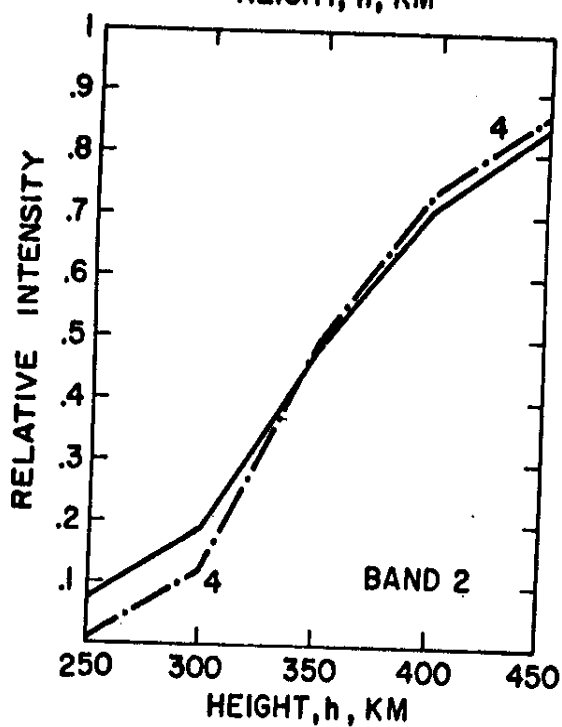
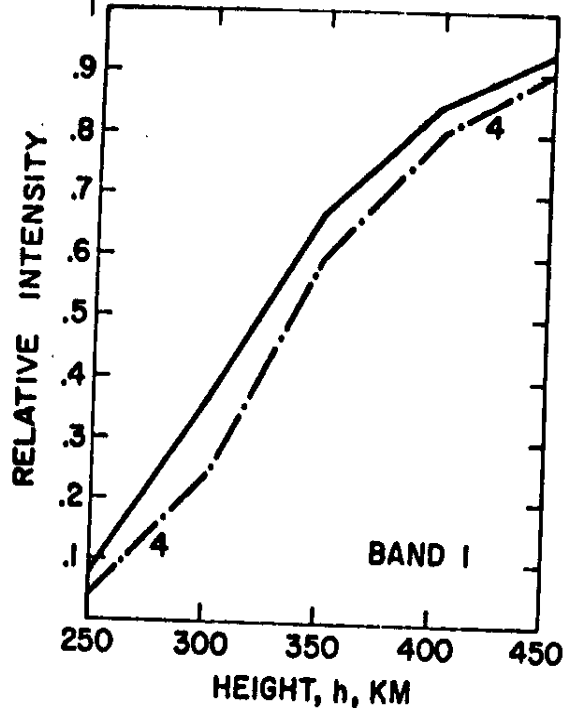
The solar eclipse observations of March 7, 1970 led to the following conclusions: 1) limb brightening is present for the integrated EUV radiation in channels 1 and 2 (the higher photon energy channels) but not in channel 3. 2) The active regions in the southern hemisphere were brighter than the surrounding regions by factors 3, 4, and 2 for channels 1, 2, and 3, respectively. In the northern hemisphere the active regions were brighter by factors of 2, 4, and 2, respectively.

D. Sunrise and Sunset Data

EUV absorption in the three channels has been observed during sunrise and sunset as viewed from the satellite. The observations were made in a zone between latitudes $\pm 33^\circ$. Typical curves, intensity vs. h , are shown in Figure 8, where h is the perpendicular distance between the satellite-sun line and the earth's surface. This type of variation of integrated intensity for each channel can be predicted from a model atmosphere since the wavelength components of the solar EUV in the channels are known, as well as their absorption coefficients for each important atmospheric constituent. Predicted intensity variations for the prevailing CIRA (1965) atmospheric model of the time of the EUV observations were compared with the latter. Within experimental error, the CIRA models accounted for the observed results for channel 2 over several sunrise and sunset data sets at widely-spaced time intervals. Channel 1 showed slightly greater intensity than predicted by the prevailing CIRA model. Channel 3 data, on the average, showed considerably less intensity than that predicted by the prevailing CIRA model.

In order to account for the observed inconsistency of the channel 3 and channel 1 data with the predictions of the CIRA model, it is necessary for one to assume less atomic oxygen and more molecular nitrogen than given by the prevailing CIRA model. If the CIRA model atmosphere is modified so that the atomic oxygen density is reduced by about one-third, and the molecular nitrogen density increased by about a factor of 2, the modified CIRA model will predict intensities in agreement with all three wavelength channels. The change

Figure 8.
EUV Intensity Variations at Sunset



has little effect on the overall EUV absorption of channel 2 (where the absorption effects of O and N₂ are comparable) but a large effect (in the correct direction) for channel 3 where absorption by nitrogen dominates. In addition, predicted intensities for channel 1 are slightly greater because this channel is most sensitive to the lowered oxygen density. Other investigators have also observed less atomic oxygen than predicted by the CIRA (1965) model ("Ionospheric Estimates of Atomic Oxygen Concentration from Charged Particle Measurements," Mahajan, K. K., (10), J. Geophys. Res. 76, 4621, 1971).

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